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Adv. Fixed Point Theory, 4 (2014), No. 3, 355-364

ISSN: 1927-6303

WEAKLY CONTRACTIVE MAPPINGS IN T_0 -QUASI-METRIC SPACES

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Abstract. It is the aim of this paper to prove the existence of a fixed point for weakly C -contractive and weakly S -contractive self mappings defined in T_0 -quasi-metric spaces.

Keywords: bicomplete di-metric; weakly C -contractive maps; weakly S -contractive maps; fixed point.

2010 AMS Subject Classification: 47H17, 47H05, 47H10.

1. Introduction

There is a growing interest for asymmetric structures, and more specifically for the "asymmetric distances". Recently, many results established in metric spaces which have their equivalent formulations in quasi-pseudometric spaces. However, the technicality of the proofs is completely different.

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Received March 31, 2014

In a recent paper, Gaba [1] proved a fixed point result for C -contractive and S -contractive self mappings defined in T_0 -quasi-metric spaces. For recent results concerning the theory, we refer the reader to [2]-[5].

2. Preliminaries

In this section, we recall some elementary definitions and terminology from the classical theory as well as for asymmetric topology which are necessary for a good understanding of the work below. For more information about this theory, the reader is referred to [6].

Definition 2.1. Let (X, m) be a metric space. A map $T : X \rightarrow X$ is called a C -contraction iff there exists $0 \leq k < \frac{1}{2}$ such that for all $x, y \in X$, the following inequality holds:

$$m(Tx, Ty) \leq k[m(x, Tx) + m(y, Ty)].$$

Definition 2.2. Let (X, m) be a metric space. A map $T : X \rightarrow X$ is called a *weak contraction* or said to be *weakly contractive* iff for all $x, y \in X$, the following inequality holds:

$$m(Tx, Ty) \leq km(x, Tx) - \psi(m(x, y)).$$

where $\psi : [0, \infty) \rightarrow [0, \infty)$ is a continuous and non-decreasing mapping such that $\psi(x) = 0$ iff $x = 0$ and $\lim_{x \rightarrow \infty} \psi(x) = \infty$.

Definition 2.3. Let (X, m) be a metric space. A map $T : X \rightarrow X$ is called a *weak C-contraction* or said to be *weakly C-contractive* iff for all $x, y \in X$, the following inequality holds:

$$m(Tx, Ty) \leq \frac{1}{2}[m(x, Tx) + m(y, Ty)] - \psi(m(x, Tx), m(y, Ty)).$$

where $\psi : [0, \infty)^2 \rightarrow [0, \infty)$ is a continuous mapping such that $\psi(x, y) = 0$ if and only if $x = y = 0$.

Definition 2.4. Let (X, m) be a metric space. A map $T : X \rightarrow X$ is called a S -contraction iff there exists $0 \leq k < \frac{1}{3}$ such that for all $x, y \in X$, the following inequality holds:

$$m(Tx, Ty) \leq k[m(x, Ty) + m(Tx, y) + m(x, y)].$$

Definition 2.5. Let (X, m) be a metric space. A map $T : X \rightarrow X$ is called a *weak S -contraction* or said to be *weakly S -contractive* iff for all $x, y \in X$, the following inequality holds:

$$m(Tx, Ty) \leq \frac{1}{3}[m(x, Ty) + m(Tx, y) + m(x, y)] - \psi(m(x, Ty), m(Tx, y), m(x, y)).$$

where $\psi : [0, \infty)^3 \rightarrow [0, \infty)$ is a continuous mapping such that $\psi(x, y, z) = 0$ if and only if $x = y = z = 0$.

Definition 2.6. Let X be a non empty set. A function $d : X \times X \rightarrow [0; \infty)$ is called a *quasi-pseudometric* on X iff

- i) $d(x, x) = 0 \quad \forall x \in X$,
- ii) $d(x, z) \leq d(x, y) + d(y, z) \quad \forall x, y, z \in X$.

Moreover, if $d(x, y) = 0 = d(y, x) \implies x = y$, then d is said to be a T_0 -*quasi-pseudometric* or a *di-metric*. The latter condition is referred to as the T_0 -condition.

Example 2.7. [7] On $\mathbb{R} \times \mathbb{R}$, we define the real valued map d given by

$$d(a, b) = a \dot{-} b = \max\{a - b, 0\}.$$

Then (\mathbb{R}, d) is a di-metric space.

Remark 2.8.

- Let d be a quasi-pseudometric on X . Then the map d^{-1} defined by $d^{-1}(x, y) = d(y, x)$ whenever $x, y \in X$ is also a quasi-pseudometric on X , called the conjugate of d . (In the literature, it is also denoted by d^t or \bar{d}).
- It is easy to verify that the function d^s defined by $d^s := d \vee d^{-1}$, i.e.,

$$d^s(x, y) = \max\{d(x, y), d(y, x)\}$$

defines a metric on X whenever d is a T_0 -quasi-pseudometric.

Definition 2.9. The di-metric space (X, d) is said to be *bicomplete* if the metric space (X, d^s) is complete.

Example 2.10. Let $X = [0; \infty)$. Define for each $x, y \in X$, $n(x, y) = x$ if $x > y$, and $n(x, y) = 0$ if $x \leq y$. It is not difficult to check that (X, n) is a T_0 -quasi-pseudometric space. Notice also that

for $x, y \in [0; \infty)$, we have $n^s(x, y) = \max\{x, y\}$ if $x \neq y$ and $n^s(x, y) = 0$ if $x = y$. The metric n^s is complete on $[0, \infty)$.

Definition 2.11. Let (X, d) be a quasi-pseudometric space. For $x \in X$ and $\varepsilon > 0$,

$$B_d(x, \varepsilon) = \{y \in X : d(x, y) < \varepsilon\}$$

denotes the open ε -ball at x . The collection of all such balls is a base for a topology $\tau(d)$ induced by d on X . Similarly, for $x \in X$ and $\varepsilon \geq 0$,

$$C_d(x, \varepsilon) = \{y \in X : d(x, y) \leq \varepsilon\}$$

denotes the closed ε -ball at x .

In the case where (X, d) is a T_0 quasi-pseudometric space, we know that d^s defined by $d^s := d \vee d^{-1}$, i.e. $d^s(x, y) = \max\{d(x, y), d(y, x)\}$ defines a metric on X . Hence, we shall say that a subset $E \subset X$ is *join closed* if it is d^s -closed, i.e., closed with respect to the topology generated by d^s .

Definition 2.12. Let X be a nonempty set. Two self mappings $F, G : X \rightarrow X$ are said to be *weakly compatible* iff for all $x \in X$ the equality $Fx = Gx$ implies $FGx = GFx$.

Next, we recall the following interesting results established in Chatterja *et al.* [8], Shukla *et al.* [9] and Vahid [10].

Theorem 2.13. *A weak C-contraction on a complete metric space has a unique fixed point. A weak S-contraction on a complete metric space has a unique fixed point.*

Theorem 2.14. *Let (X, d) be a complete metric space and let E be a nonempty closed subset of X . Let $T, S : E \rightarrow E$ be such that*

$$d(Tx, Sy) \leq \frac{1}{2}[d(Rx, Sy) + d(Tx, Ry)] - \psi(d(Rx, Sy), d(Tx, Ry))$$

for every pair $(x, y) \in X^2$, where $\psi : [0, \infty)^2 \rightarrow [0, \infty)$ is a continuous mapping such that $\psi(x, y) = 0$ if and only if $x = y = 0$ and $R : E \rightarrow X$ satisfying the following hypothesis:

- (i) $TE \subseteq RE$ and $SE \subseteq RE$,
- (ii) the pairs (T, R) and (S, R) are weakly compatible.

In addition, we assume that RE is a closed subset of X . Then T , R and S have a unique common fixed point.

The following results generalize the above theorems to the setting of a bicomplete di-metric space.

Definition 2.15. Let (X, d) be a quasi-pseudometric space. A map $T : X \rightarrow X$ is called a *weak C-pseudocontraction* or said to be *weakly C-pseudocontractive* iff for all $x, y \in X$, the following inequality holds:

$$d(Tx, Ty) \leq \frac{1}{2}[d(x, Tx) + d(y, Ty)] - \psi(d(x, Tx), d(y, Ty)).$$

where $\psi : [0, \infty)^2 \rightarrow [0, \infty)$ is a continuous mapping such that $\psi(x, y) = 0$ if and only if $x = y = 0$.

Definition 2.16. Let (X, d) be a quasi-pseudometric space. A map $T : X \rightarrow X$ is called a *weak S-pseudocontraction* or said to be *weakly S-pseudocontractive* iff for all $x, y \in X$, the following inequality holds:

$$d(Tx, Ty) \leq \frac{1}{3}[d(x, Ty) + d(Tx, y) + d(x, y)] - \psi(d(x, Ty), d(Tx, y), d(x, y)).$$

where $\psi : [0, \infty)^3 \rightarrow [0, \infty)$ is a continuous mapping such that $\psi(x, y, z) = 0$ if and only if $x = y = z$.

Definition 2.17. Let E_1, \dots, E_n, F be totally ordered spaces with respective orders $\leq_{E_1}, \dots, \leq_{E_n}$ and \leq_F . A map $f : E_1 \times E_2 \times \dots \times E_n \rightarrow F$ is said to be *component non-increasing* if

$$f(x_1, \dots, x_n) \leq_F f(a_1, \dots, a_n)$$

whenever $a_i \leq_{E_i} x_i$ for any $i = 1, \dots, n$.

Example 2.18. Let $E_1 = E_2 = F = [0, \infty)$ with the natural order and define the function $f : [0, \infty) \times [0, \infty) \rightarrow [0, \infty)$ by $f(x, y) = -(x^2 + y^2)$. Clearly, if $a \leq b$ and $c \leq d$, we have $f(b, d) \leq f(a, c)$.

More generally, by setting $E_1 = E_2 = \dots = E_n = F = [0, \infty)$ with the natural order and defining the function $f : [0, \infty) \times \dots \times [0, \infty) \rightarrow [0, \infty)$ by $f(x_1, x_2, \dots, x_n) = -(x_1^2 + x_2^2 + \dots + x_n^2)$, f is component non-increasing.

3. Main results

We are in a position to state our first fixed point result.

Theorem 3.1. *Let (X, d) be a totally ordered bicomplete di-metric space and let $T : X \rightarrow X$ be a weak C -pseudocontraction. Moreover, we assume that ψ is component non-increasing. Then T has a unique fixed point.*

Proof. Since $T : X \rightarrow X$ is a weak C -pseudocontraction, for all $x, y \in X$, the following inequality holds

$$d(Tx, Ty) \leq \frac{1}{2}[d(x, Ty) + d(Tx, y)] - \psi(d(x, Ty), d(Tx, y)).$$

where $\psi : [0, \infty)^2 \rightarrow [0, \infty)$ is a continuous mapping such that $\psi(x, y) = 0$ if and only if $x = y = 0$.

For any $x, y \in X$, we have

$$\begin{aligned} d^{-1}(Tx, Ty) = d(Ty, Tx) &\leq \frac{1}{2}[d(y, Tx) + d(Ty, x)] - \psi(d(y, Tx), d(Ty, x)). \\ &\leq \frac{1}{2}[d^{-1}(Tx, y) + d^{-1}(x, Ty)] - \psi(d^{-1}(Tx, y), d^{-1}(x, Ty)), \end{aligned}$$

that is,

$$d^{-1}(Tx, Ty) \leq \frac{1}{2}[d^{-1}(Tx, y) + d^{-1}(x, Ty)] - \psi(d^{-1}(Tx, y), d^{-1}(x, Ty)),$$

and we see that $T : (X, d^{-1}) \rightarrow (X, d^{-1})$ is a weak C -pseudocontraction. Therefore, since ψ is component non-increasing, we have

$$\begin{aligned} d(Tx, Ty) &\leq \frac{1}{2}[d(x, Ty) + d(Tx, y)] - \psi(d(x, Ty), d(Tx, y)) \\ &\leq \frac{1}{2}[d^s(x, Ty) + d^s(Tx, y)] - \psi(d^s(x, Ty), d^s(Tx, y)), \end{aligned}$$

and

$$\begin{aligned} d^{-1}(Tx, Ty) &\leq \frac{1}{2}[d^{-1}(Tx, y) + d^{-1}(x, Ty)] - \psi(d^{-1}(Tx, y), d^{-1}(x, Ty)), \\ &\leq \frac{1}{2}[d^s(x, Ty) + d^s(Tx, y)] - \psi(d^s(x, Ty), d^s(Tx, y)), \end{aligned}$$

for all $x, y \in X$. Hence, we have

$$d^s(Tx, Ty) \leq \frac{1}{2}[d^s(x, Ty) + d^s(Tx, y)] - \psi(d^s(x, Ty), d^s(Tx, y)),$$

for all $x, y \in X$ and so, $T : (X, d^s) \rightarrow (X, d^s)$ is a weak C -contraction. By assumption, (X, d) is bicomplete, hence (X, d^s) is complete. Therefore by Theorem 2.13, T has a unique fixed point. This completes the proof.

Theorem 3.2. *Let (X, d) be a totally ordered bicomplete di-metric space and let E be a nonempty join closed subset of X . Let $T, S : E \rightarrow E$ be such that*

$$d(Tx, Sy) \leq \frac{1}{2}[d(Rx, Sy) + d(Tx, Ry)] - \psi(d(Rx, Sy), d(Tx, Ry)),$$

and

$$d(Sx, Ty) \leq \frac{1}{2}[d(Sx, Ry) + d(Rx, Ty)] - \psi(d(Sx, Ry), d(Rx, Ty)),$$

for every pair $(x, y) \in X^2$, where $\psi : [0, \infty)^2 \rightarrow [0, \infty)$ is a continuous mapping such that $\psi(x, y) = 0$ if and only if $x = y = 0$ and $R : E \rightarrow X$ satisfy the following hypothesis:

- (i) $TE \subseteq RE$ and $SE \subseteq RE$,
- (ii) the pairs (T, R) and (S, R) are weakly compatible.

In addition, we assume that RE is a join closed subset of X . Then T , R and S have a unique common fixed point.

Proof. We prove that $T : (E, d^s) \rightarrow (E, d^s)$ satisfies the assumptions of Theorem 2.14. For every pair $(x, y) \in X^2$, we have

$$d(Tx, Sy) \leq \frac{1}{2}[d(Rx, Sy) + d(Tx, Ry)] - \psi(d(Rx, Sy), d(Tx, Ry)).$$

It is also very clear that

$$d^{-1}(Tx, Sy) = d(Sy, Tx) \leq \frac{1}{2}[d^{-1}(Rx, Sy) + d^{-1}(Tx, Ry)] - \psi(d^{-1}(Rx, Sy), d^{-1}(Tx, Ry)).$$

Since ψ is component non-increasing, we have

$$\begin{aligned} d(Tx, Sy) &\leq \frac{1}{2}[d(Rx, Sy) + d(Tx, Ry)] - \psi(d(Rx, Sy), d(Tx, Ry)) \\ &\leq \frac{1}{2}[d^s(Rx, Sy) + d^s(Tx, Ry)] - \psi(d^s(Rx, Sy), d^s(Tx, Ry)) \end{aligned}$$

and

$$d^{-1}(Tx, Sy) \leq \frac{1}{2}[d^{-1}(Rx, Sy) + d^{-1}(Tx, Ry)] - \psi(d^{-1}(Rx, Sy), d^{-1}(Tx, Ry)) \\ \frac{1}{2}[d^s(Rx, Sy) + d^s(Tx, Ry)] - \psi(d^s(Rx, Sy), d^s(Tx, Ry)).$$

Hence, we see that

$$d^s(Tx, Sy) \leq \frac{1}{2}[d^s(Rx, Sy) + d^s(Tx, Ry)] - \psi(d^s(Rx, Sy), d^s(Tx, Ry)).$$

By assumption, (X, d) is bicomplete, hence (X, d^s) is complete. Moreover, since E and RE are join closed, we conclude by Theorem 2.14 that T, R and S have a unique common fixed point.

Theorem 3.3. *Let (X, d) be a totally ordered bicomplete di-metric space and let $T : X \rightarrow X$ be a weak S -pseudocontraction. Moreover, we assume that ψ is component non-increasing. Then T has a unique fixed point.*

Proof. It is enough to prove that $T : (X, d^s) \rightarrow (X, d^s)$ is a weak S -contraction. Since $T : X \rightarrow X$ is a weak S -pseudocontraction, for all $x, y \in X$ the following inequality holds

$$d(Tx, Ty) \leq \frac{1}{2}[d(x, Ty) + d(Tx, y) + d(x, y)] - \psi(d(x, Ty), d(Tx, y), d(x, y)).$$

where $\psi : [0, \infty)^3 \rightarrow [0, \infty)$ is a continuous mapping such that $\psi(x, y) = 0$ if and only if $x = y = z = 0$. For any $x, y \in X$, we have

$$d^{-1}(Tx, Ty) = d(Ty, Tx) \\ \leq \frac{1}{2}[d(y, Tx) + d(Ty, x) + d(x, y)] - \psi(d(y, Tx), d(Ty, x), d(x, y)) \\ \leq \frac{1}{2}[d^{-1}(Tx, y) + d^{-1}(x, Ty) + d^{-1}(x, y)] - \psi(d^{-1}(Tx, y), d^{-1}(x, Ty), d^{-1}(y, x)),$$

that is,

$$d^{-1}(Tx, Ty) \leq \frac{1}{2}[d^{-1}(Tx, y) + d^{-1}(x, Ty) + d^{-1}(x, y)] - \psi(d^{-1}(Tx, y), d^{-1}(x, Ty), d^{-1}(y, x)),$$

and we see that $T : (X, d^{-1}) \rightarrow (X, d^{-1})$ is a weak S -pseudocontraction. Since ψ is component non-increasing, we have

$$\begin{aligned} d(Tx, Ty) &\leq \frac{1}{2}[d(x, Ty) + d(Tx, y) + d(x, y)] - \psi(d(x, Ty), d(Tx, y), d(x, y)), \\ &\leq \frac{1}{2}[d^s(x, Ty) + d^s(Tx, y) + d^s(x, y)] - \psi(d^s(x, Ty), d^s(Tx, y), d^s(x, y)), \end{aligned}$$

and

$$\begin{aligned} d^{-1}(Tx, Ty) &\leq \frac{1}{2}[d^{-1}(Tx, y) + d^{-1}(x, Ty)] - \psi(d^{-1}(Tx, y), d^{-1}(x, Ty)), \\ &\leq \frac{1}{2}[d^s(x, Ty) + d^s(Tx, y) + d^s(x, y)] - \psi(d^s(x, Ty), d^s(Tx, y), d^s(x, y)), \end{aligned}$$

for all $x, y \in X$. Hence, we have

$$d^s(Tx, Ty) \leq \frac{1}{2}[d^s(x, Ty) + d^s(Tx, y) + d^s(x, y)] - \psi(d^s(x, Ty), d^s(Tx, y), d^s(x, y)),$$

for all $x, y \in X$ and so, $T : (X, d^s) \rightarrow (X, d^s)$ is a weak S -contraction. By assumption, (X, d) is bicomplete, hence (X, d^s) is complete. Therefore by Theorem 2.13, T has a unique fixed point. This completes the proof.

Conflict of Interests

The authors declare that there is no conflict of interests.

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