# APPROXIMATION OF COMMON SOLUTIONS OF FIXED POINT PROBLEM FOR $\alpha$-HEMICONTRACTIVE MAPPING, SPLIT EQUILIBRIUM AND VARIATIONAL INEQUALITY PROBLEMS 

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Abstract. In this paper, a Halpern-type algorithm for approximating a common fixed point of multivalued $\alpha$ hemicontractive mappings and a set of solutions of split equilibrium and variational inequality problems is constructed. Strong convergence of the sequence generated by the algorithm is proved in the setting real Hilbert spaces. Our results improved and generalised the results of Meche and Zegeye [2] in particular and some recent results in Literature.

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## 1. Introduction

Throughout this paper, $F(S)$ denotes the set of fixed point of the multivalued mapping $S, \mathrm{R}$ denotes the set of all real numbers, and N a set of positive integers. Let $H$ be a Hilbert space and $C$ be a nonempty closed convex subset of $H$. Let $C B(C)$ denotes the family of nonempty, closed and bounded subsets of $C$ and $K(C)$ denotes a family of nonempty and compact subsets of $C$.

[^0]The Hausdorff metric is defined by

$$
D(A, B)=\max \{(\sup d(x, B), x \in A),(\sup d(y, A), y \in B)\}
$$

for all $A, B \in C B(C)$, where $d(x, B)=\inf \{\|x-b\|: b \in B\}$

Definition 1.1. (see [2]) Let $S: C \longrightarrow C B(C)$ be a multivalued mapping. Then, $S$ is said to be L-Lipshitizian if there exists $L>0$ such that

$$
\begin{equation*}
D(S x, S y) \leq L\|x-y\|, \forall x, y \in C \tag{1.1}
\end{equation*}
$$

$S$ is said to be nonexpansive if it is Lipschitz continous with $L=1$ in (1.1). Note that the class of nonexpansive mapping is one of the initial classes of mappings for which fixed point results were obtained using the geometric structure of the underlying Banach space rather than the compactness property. An element $x \in C$ is called the fixed point of a multivalued mapping $S$ if $x \in S x$. A nonexpansive multivalued mapping $S$ with a nonempty fixed point set is called quasi-nonexpansive multivalued mapping(i.e, a mapping $S: C \longrightarrow C B(C)$ such that $D(S x, S p) \leq$ $\mid x-p \|, \forall(x, p) \in C \times F(S))$.

Definition 1.2. (see [2]) Let $S: C \longrightarrow C B(C)$ be a multivalued mapping. Then, $S$ is said to be demicontractive if $F(S)=\{x \in C: x \in S x\} \neq \emptyset$ and for all $u \in S$ satisfying $\|u-p\| \leq D(S x, S p)$, there exists $k \in(0,1)$ such that

$$
\begin{equation*}
D^{2}(S x, S p) \leq\|x-p\|^{2}+k\|x-u\|^{2}, \forall x \in C \text { and } \forall p \in F(S), \tag{1.2}
\end{equation*}
$$

Note that if $k$ in (1.2) is 1 , then $S$ is called hemicontractive multivalued mapping. Thus, the class of demicontractive multivalued napping is a proper subclass of the class of hemicontractive multivalued mapping.
ln 2015, Osilike and Onah [12] introduced a new class of mapping called $\alpha$-hemicontractive
mapping in a closed convex subset of a real Hilbert space. They showed that the class of $\alpha$ demicontractive mapping introduced by Maruster and Maruster in [18] is a subclass of the class of $\alpha$-hemicontractive mapping. Also, it was shown in [12] that the class of hemicontractive mapping and the class of $\alpha$-hemicontractive mapping are independent(see [12] for details).

Definition 1.3. Let $S: C \longrightarrow C B(C)$ be a multivalued mapping. Then, $S$ is said to be $\alpha$ hemicontractive multivalued mapping if $F(S)=\{x \in C: x \in S x\} \neq \emptyset$ and for all $u \in S$ satisfying $\|u-p\| \leq D(S x, S p)$, we have

$$
\begin{equation*}
D^{2}(S x, S \alpha p) \leq\|x-\alpha p\|^{2}+\|x-u\|^{2}, \forall x \in C \text { and } \forall p \in F(S) \tag{1.3}
\end{equation*}
$$

for some $\alpha \geq 1$. The class of mapping defined by (1.3) is a superclass of the class of $\alpha$ demicontractive multivalued mapping(where a mapping $S: C \longrightarrow C B(C)$ is called $\alpha$-demicontractive multivalued mapping if $F(S)=\{x \in C: x \in S x\} \neq \emptyset$ and for all $u \in S$ satisfying $\|u-p\| \leq$ $D(S x, S p)$, there exists $k \in(0,1)$ such that $D^{2}(S x, S \alpha p) \leq \mid x-\alpha p\left\|^{2}+k\right\| x-u \|^{2}, \forall x \in C$, $\forall p \in F(S)$ and for some $\alpha \geq 1$ ).

Observe that (1.3) is equivalent to

$$
\begin{equation*}
\langle x-u, x-\alpha p\rangle \geq 0, \forall x \in C, \forall p \in F(S), \forall u \in S \text { and for some } \alpha \geq 1 \tag{1.4}
\end{equation*}
$$

Let $F: C \times C \longrightarrow R$ be a bifunction. The equilibrium problem for $F$ is to find $z \in C$ such that

$$
\begin{equation*}
F(z, y) \geq 0, \forall y \in C \tag{1.5}
\end{equation*}
$$

The set of all solutions of $(1.5)$ is denoted by $E P(F)$, that is, $E P(F)=\{z \in C: F(z, y) \geq 0, \forall y \in$ $C$.

Let $A: C \longrightarrow R$ be a nonlinear mapping. The classical variational inequality problem, which was developed as a useful tool in solving partial differential equation by Stampacchia(see [22] for details), is the problem of finding $x \in C$ such that

$$
\begin{equation*}
\langle u-x, A x\rangle \geq 0, \forall u \in C \tag{1.6}
\end{equation*}
$$

The set of all solutions of (1.6) is denoted by $\operatorname{VI}(C, A)$.

Recently, Karmi and Rizvi [17] considered a problem which they called split equilibrium problem. Let $H_{1}$ and $H_{2}$ be two Hilbert spaces and $C, K$ be two nonempty closed and convex subsets of $H_{1}$ and $H_{2}$ respectively. Let $F_{1}: C \times C \longrightarrow R$ and $F_{2}: K \times K \longrightarrow R$ be two bifunctions and $A: H_{1} \longrightarrow H_{2}$ be a bounded linear operator. The split equilibrium problem is to find $x^{\star} \in C$ such that

$$
\begin{equation*}
F_{1}\left(x^{\star}, x\right) \geq 0, \forall x \in C \text { and } y^{\star}=A x^{\star} \in K \text { such that } F_{2}(y \star, y) \geq 0, \forall y \in K \tag{1.7}
\end{equation*}
$$

The set of solutions of split equilibrium problem is denoted by $\Omega$, that is, $\Omega=\{z \in C: x \in$ $\left.E P\left(F_{1}\right), A x \in E P\left(F_{2}\right)\right\}$.

Very recently, Meche and Zegeye [2] first introduced an iteration sequence (for finding common set of solutions of fixed point problem, split equilibrium and variational inequality problems) defined as follows:

Let $x_{o}, u \in C$ be arbitrary and let $x_{n}$ be a sequence in $C$ generated by

$$
\begin{align*}
& z_{n}=T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x_{n} \\
& y_{n}=J_{t} z_{n}  \tag{1.8}\\
& u_{n}=\left(1-\delta_{n}\right) y_{n}+\delta_{n} v_{n} \\
& x_{n+1}=a_{n} u+b_{n} w_{n}+c_{n} y_{n}
\end{align*}
$$

for all $n \geq 0$, where $v_{n} \in S y_{n}$ and $w_{n} \in S u_{n}$ are such that $\left\|v_{n}-w_{n}\right\| \leq 2 D\left(S y_{n}-S u_{n}\right), s, r, t>$ $0, \lambda \in\left(0, \frac{1}{d}\right), d=B B^{\star}$, where $B^{\star}$ is the adjoint of $B, a_{n}, \delta_{n} \subset(0,1)$ and $b_{n}, c_{n} \subset[a, b]$ for some $a, b \in(0,1)$.They used (1.8) to prove the following theorems:
Theorem MZ1[2]: Let $H_{1}$ and $H_{2}$ be two Hilbert spaces and $C, Q$ be two nonempty, closed and convex subsets of $H_{1}$ and $H_{2}$ respectively. Let $F_{1}: C \times C \longrightarrow R$ and $F_{2}: Q \times Q \longrightarrow R$ be two bifunctions satisfying Assumption G. Let $A: C \longrightarrow H_{1}$ be a continous monotone mapping and $B: Q \longrightarrow H_{2}$ be a bounded linear operator. Let $S: C \longrightarrow C B(C)$ be $L$-Lipschitz hemicontractivetype multivalued mapping. Assume that $\Theta=F(S) \cap \Omega \cap V I(C A)$ is nonempty and $S p=p$ for
all $p \in \Theta$. Let $x_{0}, u \in C$ be arbitrary and let $x_{n}$ be a sequence in $C$ generated by

$$
\begin{align*}
& z_{n}=T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x_{n} \\
& y_{n}=J_{t} z_{n} \\
& u_{n}=\left(1-\delta_{n}\right) y_{n}+\delta_{n} v_{n}  \tag{1.9}\\
& x_{n+1}=a_{n} u+b_{n} w_{n}+c_{n} y_{n}
\end{align*}
$$

for all $n \geq 0$, where $v_{n} \in S y_{n}$ and $w_{n} \in S u_{n}$ are such that $\left\|v_{n}-w_{n}\right\| \leq 2 D\left(S y_{n}-S u_{n}\right), s, r, t>$ $0, \lambda \in\left(0, \frac{1}{d}\right), d=B B^{\star}$, where $B^{\star}$ is the adjoint of $B, a_{n}, \delta_{n} \subset(0,1)$ and $b_{n}, c_{n} \subset[a, b]$ for some $a, b \in(0,1)$ satisfying the following conditions:
i. $a_{n}+b_{n}+c_{n}=1$,
ii. $a_{n}+b_{n} \leq \delta_{n} \leq c<\frac{1}{\sqrt{1+4 L^{2}}+1}$.

Then, the sequence $\left\{x_{n}\right\}$ is bounded.
Theorem MZ2[2]: Let $H_{1}$ and $H_{2}$ be two Hilbert spaces and $C, Q$ be two nonempty, closed and convex subsets of $H_{1}$ and $H_{2}$ respectively. Let $F_{1}: C \times C \longrightarrow R$ and $F_{2}: Q \times Q \longrightarrow R$ be two bifunctions satisfying Assumption G. Let $A: C \longrightarrow H_{1}$ be a continous monotone mapping and $B: Q \longrightarrow H_{2}$ be a bounded linear operator. Let $S: C \longrightarrow C B(C)$ be $L$-Lipschitz hemicontractivetype multivalued mapping. Assume that $\Theta=F(S) \cap \Omega \cap V I(C A)$ is nonempty, $S p=p$ for all $p \in \Theta$ and $(I-S)$ is demiclosed at zero. Let $x_{0}, u \in C$ be arbitrary and let $x_{n}$ be a sequence in $C$ generated by

$$
\begin{align*}
& z_{n}=T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x_{n}, \\
& y_{n}=J_{t} z_{n}, \\
& u_{n}=\left(1-\delta_{n}\right) y_{n}+\delta_{n} v_{n},  \tag{1.10}\\
& x_{n+1}=a_{n} u+b_{n} w_{n}+c_{n} y_{n},
\end{align*}
$$

for all $n \geq 0$, where $v_{n} \in S y_{n}$ and $w_{n} \in S u_{n}$ are such that $\left\|v_{n}-w_{n}\right\| \leq 2 D\left(S y_{n}-S u_{n}\right), s, r, t>$ $0, \lambda \in\left(0, \frac{1}{d}\right), d=B B^{\star}$, where $B^{\star}$ is the adjoint of $B, a_{n}, \delta_{n} \subset(0,1)$ and $b_{n}, c_{n} \subset[a, b]$ for some $a, b \in(0,1)$ satisfying the following conditions:
i. $a_{n}+b_{n}+c_{n}=1$,
ii. $a_{n}+b_{n} \leq \delta_{n} \leq c<\frac{1}{\sqrt{1+4 L^{2}}+1}$.

Then, the sequence $\left\{x_{n}\right\}$ converges strongly to $\alpha p$, where $\alpha p=P_{\Theta}(u)$.

It is our purpose in this paper to first introduce a new iterative sequence and then prove strong convergence theorem of our new iterative sequence to the common solutions of fixed point problem for $\alpha$-hemicontractive mapping (which is a more general operator than the one used by Meche and Zegeye), split equilibrium and variational inequality problems.

## 2. Preliminary

In this section, we collect some concepts and results that play a crucial role in the sequel.
Let $S: C \longrightarrow C$ be a nonexpansive mapping with $F(S) \neq \emptyset$. Then, for every $x \in C$ and $y \in F(S)$, we obtain that

$$
\begin{equation*}
\langle x-S x, y-S x\rangle \leq \frac{1}{2}\|S x-x\|^{2} \tag{2.1}
\end{equation*}
$$

(see e.g. [17]). Let $H$ be a real Hilbert space, $C$ a closed convex subset of $H$ and $P_{C}: H \longrightarrow 2^{C}$ a metric projection of $H$ onto $C$. Recall that for every $x \in H$, there exists a unique nearest point in $C$, denoted by $P_{C} x$ such that

$$
\left\|x-P_{C} x\right\|=\inf \{\|x-y\|: y \in C\} .
$$

The mapping $P_{C}: H \longrightarrow 2^{C}$ is characterised by

$$
\begin{equation*}
z=P_{C} x \in C \text { if and only if }\langle x-z, z-y\rangle \geq 0, \forall x \in H, y \in C \tag{2.2}
\end{equation*}
$$

In what follows, we shall use the following assumptions:
Assumption G: Let $H$ be a Hilbert space and $C$ a nonempty, closed and convex subset of $H$.
Let $F: C \times C \longrightarrow R$ be a bifunction satisfying the following conditions:
$G_{1}: F(x, x)=0, \forall x \in H$
$G_{2}: F$ is a monotone, i.e, $F(x, y)+F(y, x) \leq 0, \forall x, y \in C$
$G_{3}: \lim _{t \longrightarrow 0}(t z+(1-t) y) \leq F(x, y), \forall x, y, z \in C$
$G_{4}$ : for each $x \in C, y \rightarrow F(x, y)$ is convex and lower semicontinous.

In the proof of our main results, we make use of the following lemmas:

Lemma 2.1. Let $F_{1}: C \times C \longrightarrow R$ be a bifunction satisfying assumption $G$. For $s>0$ and for all $x \in H$, define the mapping $T_{s}^{F_{1}}: H_{1} \longrightarrow C$ as follows:

$$
\begin{equation*}
T_{s}^{F_{1}} x=\left\{x \in C: F_{1}(x, y)+\frac{1}{s}\langle y-z, x-y\rangle \geq 0, \forall y \in C\right\} \tag{2.3}
\end{equation*}
$$

Then, we have the following:
(1) $T_{S}^{F_{1}}$ is nonempty and single valued;
(2) $T_{s}^{F_{1}}$ is firmly nonexpansive, i.e, $\left\|T_{s}^{F_{1}} x-T_{s}^{F_{1}} y\right\| \leq\left\langle T_{s}^{F_{1}} x-T_{s}^{F_{1}} y, x-y\right\rangle$;
(3) $F\left(T_{s}^{F_{1}}\right)=E P\left(T_{s}^{F_{1}}\right)$;
(4) $E P\left(F_{1}\right)$ is closed and convex.

Furthermore, assume that $F_{2}: Q \times Q \longrightarrow R$ is another bifunction that satisfies assumption $G$. For $r>0$ and for all $x \in H$ define the mapping $T_{s}^{F_{2}}: H_{1} \longrightarrow Q$ as follows:

$$
\begin{equation*}
T_{s}^{F_{2}} x=\left\{x \in Q: F_{1}(x, y)+\frac{1}{s}\langle y-z, x-y\rangle \geq 0, \forall y \in Q\right\} \tag{2.4}
\end{equation*}
$$

Then, we have the following:
(1) $T_{s}^{F_{2}}$ is nonempty and single valued;
(2) $T_{s}^{F_{2}}$ is firmly nonexpansive, i.e, $\left\|T_{s}^{F_{2}} x-T_{s}^{F_{2}} y\right\| \leq\left\langle T_{s}^{F_{2}} x-T_{s}^{F_{1}} y, x-y\right\rangle$;
(3) $F\left(T_{s}^{F_{2}}\right)=E P\left(T_{s}^{F_{2}}\right)$;
(4) $E P\left(F_{2}\right)$ is closed and convex.

Lemma 2.2. Let $H$ be a Hilbert space. Then, for all $x_{i} \in H$ and $\alpha_{i} \in[0,1]$, for $i=1,2,3$, such that $\alpha_{1}+\alpha_{2}+\alpha_{3}=1$, the following equality holds:

$$
\left\|\alpha_{1}+\alpha_{2}+\alpha_{3}\right\|^{2}=\sum_{i=1}^{2} \alpha_{i}\|x\|^{2}-\sum_{1 \leq i, j \leq 3} \alpha_{i} \alpha_{j}\left\|x_{i}-x_{j}\right\|
$$

Lemma 2.3. Let $H$ be a real Hilbert space. Then, for every $x, y \in H$, we have the following:
i. $\|x-y\|^{2}=\|x\|^{2}+\|y\|^{2}-2\langle x, y\rangle$;
ii. $\|x+y\|=\|x\|^{2}+2\langle x, x+y\rangle$.

Lemma 2.4. Let $H$ be a real Hilbert space. Let $A, B \in C B(H)$ and $a \in A$. Then for any $\varepsilon>0$, there exists a point $b \in B$ such that $\|a-b\| \leq D(A, B)+\varepsilon$. In particular, for every $a \in A$, there exists an element $b \in B$ such that $\|a-b\| \leq 2 D(A, B)+\varepsilon$.

Lemma 2.5. Let $\left\{b_{n}\right\}$ be a sequence of nonnegative real numbers such that

$$
b_{n+1} \leq\left(1-\alpha_{n}\right) b_{n}+\alpha_{n} \delta_{n}
$$

for $n \geq n_{0}$, where $\alpha_{n} \subset(0,1)$ and $\delta_{n} \in R$ satisfying the following restrictions : $\lim _{n \rightarrow \infty}=0, \sum_{n=0}^{\infty} \alpha_{n}=$ $\infty$ and $\lim _{n \rightarrow \infty} \sup \delta_{n} \leq 0$. Then, $\lim _{n \rightarrow \infty} b_{n}=0$.

Lemma 2.6. Let $H$ be a Hilbert space and $C$ a closed convex subset of $H$. Let $A: C \longrightarrow H$ be a continous monotone mapping. Then, for $t>0$ and for all $x \in H$, there exists $z \in C$ such that

$$
\langle A z, y-z\rangle+\frac{i}{t}\langle y-z, z-x\rangle \geq 0, \forall x, y \in C
$$

Moreover, the mapping $J_{t}: H \longrightarrow C$ defined by

$$
J_{t}=\left\{z \in C:\langle A z, z x\rangle+\frac{i}{t}\langle y-z, z-x\rangle \geq 0, \forall y \in C\right\}
$$

satisfies the following:
(1) $J_{t}$ is nonempty and single valued;
(2) $J_{t}$ is firmly nonexpansive;
(3) $F\left(J_{t}\right)=V I(C, A)$;
(4) $\operatorname{VI}(C, A)$ is closed and convex.

Lemma 2.7. Let $\left\{a_{n}\right\}$ be a sequence of real numbers such that there exists a subsequence $\left\{n_{i}\right\}$ of $\{n\}$ such that $a_{n_{i}} \leq a_{n_{i+1}}$ for all $i \in N$. Then, there exists a nondecreasing sequence $m_{k} \in N$ such that $m_{k} \rightarrow \infty$ and the following properties are satisfied by all (sufficiently large) numbers $k \in N: a_{m_{k}}<a_{m_{k+1}}$ and $a_{k}<a_{m_{k+1}} . \operatorname{lnfact}, m_{k}=\max \left\{j \leq k: a_{j}<a_{j+1}\right\}$

## 3. Main Results

Theorem 3.1. Let $H_{1}$ and $H_{2}$ be two Hilbert spaces and $C, Q$ be two nonempty, closed and convex subsets of $H_{1}$ and $H_{2}$ respectively. Let $F_{1}: C \times C \longrightarrow R$ and $F_{2}: Q \times Q \longrightarrow R$ be two bifunctions satisfying Assumption $G$. Let $A: C \longrightarrow H_{1}$ be a continous monotone mapping and $B$ :
$Q \longrightarrow H_{2}$ be a bounded linear operator. Let $S: C \longrightarrow C B(C)$ be L-Lipschitz $\alpha$-hemicontractive multivalued mapping. Assume that $\Theta=F(S) \cap \Omega \cap V I(C A)$ is nonempty and $S \alpha p=\alpha p$ for all $p \in \Theta$ and for some $\alpha \geq 1$.Let $x_{0}, u \in C$ be arbitrary and let $x_{n}$ be a sequence in $C$ generated by

$$
\left.\begin{array}{l}
z_{n}=T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x_{n}, \\
y_{n}=J_{t} z_{n},  \tag{3.1}\\
u_{n}=\left(1-\delta_{n}\right) y_{n}+\delta_{n} v_{n}, \\
x_{n+1}=a_{n} u+b_{n}\left[\left(1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}\right]+c_{n} y_{n},
\end{array}\right\}
$$

for all $n \geq 0$, where $v_{n} \in S y_{n}$ and $w_{n} \in S u_{n}$ are such that $\left\|v_{n}-w_{n}\right\| \leq 2 D\left(S y_{n}-S u_{n}\right), s, r, t>$ $0, \lambda \in\left(0, \frac{1}{d}\right), d=B B^{\star}$, where $B^{\star}$ is the adjoint of $B, a_{n}, \delta_{n} \subset(0,1)$ and $b_{n}, c_{n} \subset[a, b]$ for some $a, b \in(0,1)$ satisfying the following conditions:
i. $a_{n}+b_{n}+c_{n}=1$,
ii. $a_{n}+b_{n} \leq \delta_{n} \leq c<\frac{1}{\sqrt{1+4 L^{2}}+1}$.

Then, the sequence $\left\{x_{n}\right\}$ is bounded.
Proof. First, we show that $B^{\star}\left(1-T_{r}^{F_{2}}\right) B$ is a $\frac{1}{2 d}$-inversely strongly monotone mapping. Since, $T_{r}^{F_{2}}$ is nonexpansive, we have that $\left(1-T_{r}^{F_{2}}\right)$ is $\frac{1}{2}$-inversely strongly monotone. Thus, $\forall x, y \in H_{1}$, we have

$$
\begin{aligned}
\| B^{\star} & \left(1-T_{r}^{F_{2}}\right) B x-B^{\star}\left(1-T_{r}^{F_{2}}\right) B y \|^{2} \\
& =\left\langle B^{\star}\left(1-T_{r}^{F_{2}}\right) B x-B^{\star}\left(1-T_{r}^{F_{2}}\right) B y, B^{\star}\left(1-T_{r}^{F_{2}}\right) B x-B^{\star}\left(1-T_{r}^{F_{2}}\right) B y\right\rangle \\
& =\left\langle\left(\left(1-T_{r}^{F_{2}}\right) B x-\left(1-T_{r}^{F_{2}}\right) B y\right), B B^{\star}\left(\left(1-T_{r}^{F_{2}}\right) B x-\left(1-T_{r}^{F_{2}}\right) B y\right)\right\rangle \\
& \leq B B^{\star}\left|\left\langle\left(1-T_{r}^{F_{2}}\right) B x-\left(1-T_{r}^{F_{2}}\right) B y\right),\left(\left(1-T_{r}^{F_{2}}\right) B x-\left(1-T_{r}^{F_{2}}\right) B y\right)\right\rangle \mid \\
& =d\left\|\left(1-T_{r}^{F_{2}}\right) B x-\left(1-T_{r}^{F_{2}}\right) B y\right\|^{2} \\
& \leq 2 d\left\langle x-y, B^{\star}\left[\left(1-T_{r}^{F_{2}}\right) B x-\left(1-T_{r}^{F_{2}}\right) B y\right\rangle\right] \\
& \left.=2 d\left\langle x-y, B^{\star}\left(1-T_{r}^{F_{2}}\right) B x-B^{\star}\left(1-T_{r}^{F_{2}}\right) B y\right\rangle\right],
\end{aligned}
$$

which implies that $B^{\star}\left(1-T_{r}^{F_{2}}\right) B$ is $\frac{1}{2 d}$-inversely strongly monotone. Next, we show that ( $1-$ $\left.\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right)$ is nonexpansive. Now, since $\lambda \in\left(0, \frac{1}{d}\right)$, we otain that $\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right)$ is
nobexpansive. Hence, from the nonexpansiveness of $T_{s}^{F_{1}}$, we obtain

$$
\begin{align*}
& \left\|T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x-T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) y\right\| \\
& \quad \leq\left\|\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x-\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) y\right\| \\
& \quad \leq\|x-y\| . \tag{3.2}
\end{align*}
$$

Now, let $\alpha p \in \Theta$, for some $\alpha \geq 1$. Then, we have $S(\alpha p)=\alpha p, J_{t}(\alpha p)=\alpha p$ and $\alpha p \in \Theta$; hence $\alpha p=T_{s}^{F_{1}}(\alpha p)$ and $B(\alpha p)=T_{s}^{F_{2}}(\alpha p)$, which implies that $T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right)(\alpha p)=\alpha p$. Thus, from (3.1) and (3.2), we have

$$
\begin{align*}
\left\|z_{n}-\alpha p\right\| & =\left\|T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x_{n}-\alpha p\right\| \\
& \leq\left\|\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x_{n}-\alpha p\right\| \\
& \leq\left\|x_{n}-\alpha p\right\| . \tag{3.3}
\end{align*}
$$

Since $J_{t}$ is npnexpansive, we get

$$
\begin{align*}
\left\|y_{n}-\alpha p\right\| & =\left\|J_{t} z_{n}-\alpha p\right\| \\
& =\left\|J_{t} z_{n}-J_{t}(\alpha p)\right\| \\
& \leq\left\|z_{n}-\alpha p\right\|, \tag{3.4}
\end{align*}
$$

which by (3.3) gives

$$
\begin{equation*}
\left\|y_{n}-\alpha p\right\| \leq\left\|x_{n}-\alpha p\right\| \tag{3.5}
\end{equation*}
$$

Since $S$ is $\alpha$-hemicontractive, for all $w_{n} \in S u_{n}$, we have

$$
\begin{align*}
\left\|w_{n}-\alpha p\right\|^{2} & \leq D^{2}\left(S u_{n}, S y_{n}\right) \\
& \leq\left\|u_{n}-\alpha p\right\|^{2}+\left\|u_{n}-w_{n}\right\|^{2} \tag{3.6}
\end{align*}
$$

Also,

$$
\begin{aligned}
\left\|u_{n}-\alpha p\right\|^{2} & =\left\|\left(1-\delta_{n}\right) y_{n}+\delta_{n} v_{n}-\alpha p\right\|^{2} \\
& =\left\|\left(1-\delta_{n}\right)\left(y_{n}-\alpha p\right)+\delta_{n}\left(v_{n}-\alpha p\right)\right\|^{2}
\end{aligned}
$$

which, using Lemma 2.2, gives

$$
\left\|u_{n}-\alpha p\right\|^{2}=\left(1-\delta_{n}\right)\left\|y_{n}-\alpha p\right\|^{2}+\delta_{n}\left\|v_{n}-\alpha p\right\|^{2}-\delta_{n}\left(1-\delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2}
$$

Since $S$ is $\alpha$-hemicontractive, for all, $v_{n} \in S y_{n}$, we have

$$
\begin{aligned}
\left\|u_{n}-\alpha p\right\|^{2} & =\left(1-\delta_{n}\right)\left\|y_{n}-\alpha p\right\|^{2}+\delta_{n} D^{2}\left(v_{n}-\alpha p\right)-\delta_{n}\left(1-\delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \\
& \leq\left(1-\delta_{n}\right)\left\|y_{n}-\alpha p\right\|^{2}+\delta_{n}\left[\left\|y_{n}-\alpha p\right\|^{2}+\left\|y_{n}-v_{n}\right\|^{2}\right]-\delta_{n}\left(1-\delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \\
& =\left(1-\delta_{n}\right)\left\|y_{n}-\alpha p\right\|^{2}+\delta_{n}\left\|y_{n}-\alpha p\right\|^{2}+\delta_{n}\left\|y_{n}-v_{n}\right\|^{2}-\delta_{n}\left(1-\delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \\
& =\left\|y_{n}-\alpha p\right\|^{2}+\delta_{n}\left\|y_{n}-v_{n}\right\|^{2}-\delta_{n}\left(1-\delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \\
& =\left\|y_{n}-\alpha p\right\|^{2}+\delta_{n}^{2}\left\|y_{n}-v_{n}\right\|^{2} .
\end{aligned}
$$

(3.4) and (3.7) imply that

$$
\begin{equation*}
\left\|u_{n}-\alpha p\right\|^{2} \leq\left\|x_{n}-\alpha p\right\|^{2}+\delta_{n}^{2}\left\|y_{n}-v_{n}\right\|^{2} \tag{3.8}
\end{equation*}
$$

(3.6) and (3.8) imply that

$$
\begin{equation*}
\left\|w_{n}-\alpha p\right\|^{2} \leq\left\|x_{n}-\alpha p\right\|^{2}+\delta_{n}^{2}\left\|y_{n}-v_{n}\right\|^{2}+\left\|u_{n}-w_{n}\right\|^{2} \tag{3.9}
\end{equation*}
$$

Next, we estimate $\left\|u_{n}-w_{n}\right\|^{2}$ : From (3.1), we get

$$
\begin{aligned}
\left\|u_{n}-w_{n}\right\|^{2} & =\left\|\left(1-\delta_{n}\right) y_{n}+\delta_{n} v_{n}-w_{n}\right\|^{2} \\
& =\left\|\left(1-\delta_{n}\right) y_{n}+\delta_{n} v_{n}-\delta_{n} w_{n}+\delta_{n} w_{n}-w_{n}\right\|^{2} \\
& =\left\|\left(1-\delta_{n}\right) y_{n}+\delta_{n}\left(v_{n}-w_{n}\right)-\left(1-\delta_{n}\right) w_{n}\right\|^{2} \\
& =\left\|\left(1-\delta_{n}\right)\left(y_{n}-w_{n}\right)+\delta_{n}\left(v_{n}-w_{n}\right)\right\|^{2},
\end{aligned}
$$

which by Lemma 2.2 gives

$$
\left\|u_{n}-w_{n}\right\|^{2}=\left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2}+\delta_{n}\left\|v_{n}-w_{n}\right\|^{2}-\delta_{n}\left(1-\delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2}
$$

Since, $v_{n}, w_{n} \in S u_{n}, S y_{n}$ respectively implies that $\left\|v_{n}-w_{n}\right\| \leq 2 D\left(S y_{n}, S u_{n}\right)$, we get

$$
\left\|u_{n}-w_{n}\right\|^{2}=\left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2}+4 \delta_{n} D^{2}\left(S v_{n}, S y_{n}\right)-\delta_{n}\left(1-\delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2}
$$

and since $S$ is $L$-Lipschitizian mapping, we get

$$
\begin{align*}
\left\|u_{n}-w_{n}\right\|^{2} \leq & \left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2}+4 \delta_{n} L^{2}\left\|y_{n}-u_{n}\right\|^{2}-\delta_{n}\left(1-\delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \\
= & \left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2}+4 \delta_{n} L^{2}\left\|y_{n}-\left[\left(1-\delta_{n}\right) y_{n}+\delta_{n} v_{n}\right]\right\|^{2} \\
& -\delta_{n}\left(1-\delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \\
= & \left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2}+4 \delta_{n} L^{2}\left\|y_{n}-\left(1-\delta_{n}\right) y_{n}-\delta_{n} v_{n}\right\|^{2} \\
& -\delta_{n}\left(1-\delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \\
= & \left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2}+4 \delta_{n} L^{2}\left\|\delta_{n}\left(y_{n}-v_{n}\right)\right\|^{2} \\
& -\delta_{n}\left(1-\delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \\
= & \left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2}+4 \delta_{n}^{3} L^{2}\left\|y_{n}-v_{n}\right\|^{2} \\
& -\delta_{n}\left(1-\delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} . \tag{3.10}
\end{align*}
$$

Putting (3.10) into (3.9), we have

$$
\begin{align*}
\left\|w_{n}-\alpha p\right\|^{2} \leq & \left\|x_{n}-\alpha p\right\|^{2}+\delta_{n}^{2}\left\|y_{n}-v_{n}\right\|^{2}+\left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2}+4 \delta_{n}^{3} L^{2}\left\|y_{n}-v_{n}\right\|^{2} \\
& -\delta_{n}\left(1-\delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \\
= & \left\|x_{n}-\alpha p\right\|^{2}+\delta_{n}^{2}\left\|y_{n}-v_{n}\right\|^{2}+\left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2} \\
& +\delta_{n}\left(4 \delta_{n}^{2} L^{2}+\delta_{n}-1\right)\left\|y_{n}-v_{n}\right\|^{2} \\
= & \left\|x_{n}-\alpha p\right\|^{2}+\left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2} \\
& -\delta_{n}\left(1-4 \delta_{n}^{2} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} . \tag{3.11}
\end{align*}
$$

Now, we estimate $\left\|x_{n+1}-\alpha p\right\|^{2}$ :

$$
\begin{aligned}
\left\|x_{n+1}-\alpha p\right\|^{2}= & \left\|a u+b_{n}\left[\gamma_{n} w_{n}+\left(1-\gamma_{n}\right) x_{n}\right]+c_{n}-\alpha p\right\|^{2} \\
= & \| a_{n}(u-\alpha p)+\left(a_{n}+b_{n}+c_{n}\right) \alpha p+b_{n}\left[\gamma_{n} w_{n}+\left(1-\gamma_{n}\right) x_{n}-\alpha p\right] \\
& +c_{n}\left(y_{n}-\alpha p \|^{2}\right. \\
= & \| a_{n}(u-\alpha p)+b_{n}\left[\gamma_{n}\left(w_{n}-\alpha p\right)+\left(1-\gamma_{n}\right)\left(x_{n}-\alpha p\right)\right] \\
& +c_{n}\left(y_{n}-\alpha p\right) \|^{2},
\end{aligned}
$$

which by Lemma 2.2 gives

$$
\begin{align*}
\left\|x_{n+1}-\alpha p\right\|^{2}= & a_{n}\|u-\alpha p\|^{2}+b_{n}\left\|\gamma_{n}\left(w_{n}-\alpha p\right)+\left(1-\gamma_{n}\right)\left(x_{n}-\alpha p\right)\right\|^{2} \\
& +c_{n}\left\|y_{n}-\alpha p\right\|^{2}-c_{n} b_{n}\left\|\left(1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}-y_{n}\right\|^{2} \\
= & a_{n}\|u-\alpha p\|^{2}+b_{n}\left\|\gamma_{n}\left(w_{n}-\alpha p\right)+\left(1-\gamma_{n}\right)\left(x_{n}-\alpha p\right)\right\|^{2} \\
& +c_{n}\left\|y_{n}-\alpha p\right\|^{2}-c_{n} b_{n}\left\|\left(1-\gamma_{n}\right)\left(w_{n}-y_{n}\right)+\gamma_{n}\left(x_{n}-y_{n}\right)\right\|^{2} \\
= & a_{n}\|u-\alpha p\|^{2}+b_{n}\left[\left(1-\gamma_{n}\right)\left\|w_{n}-\alpha p\right\|^{2}+\gamma_{n}\left\|x_{n}-\alpha p\right\|^{2}\right. \\
& \left.-\gamma_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-x_{n}\right\|^{2}\right]+c_{n}\left\|y_{n}-\alpha p\right\|^{2} \\
& -c_{n} b_{n}\left[\left(1-\gamma_{n}\right)\left\|w_{n}-y_{n}\right\|^{2}+\gamma_{n}\left\|x_{n}-y_{n}\right\|^{2}-\gamma_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-x_{n}\right\|^{2}\right] \\
= & a_{n}\|u-\alpha p\|^{2}+b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-\alpha p\right\|^{2}+b_{n} \gamma_{n}\left\|x_{n}-\alpha p\right\|^{2} \\
& -b_{n} \gamma_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-x_{n}\right\|^{2}+c_{n}\left\|y_{n}-\alpha p\right\|^{2}-c_{n} b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-y_{n}\right\|^{2} \\
& -c_{n} b_{n} \gamma_{n}\left\|x_{n}-y_{n}\right\|^{2}+c_{n} b_{n} \gamma_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-x_{n}\right\|^{2} \\
\leq & a_{n}\|u-\alpha p\|^{2}+b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-\alpha p\right\|^{2}+b_{n} \gamma_{n}\left\|x_{n}-\alpha p\right\|^{2} \\
& -c_{n} b_{n} \gamma_{n}\left\|w_{n}-y_{n}\right\|^{2}+c_{n}\left\|y_{n}-\alpha p\right\|^{2}-c_{n} b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-y_{n}\right\|^{2} \\
& +\left[c_{n} b_{n} \gamma_{n}\left(1-\gamma_{n}\right)-b_{n} \gamma_{n}\left(1-\gamma_{n}\right)\right]\left\|w_{n}-x_{n}\right\|^{2} . \tag{3.12}
\end{align*}
$$

(3.11) and (3.12) imply that

$$
\begin{aligned}
\left\|x_{n+1}-\alpha p\right\|^{2} \leq & a_{n}\|u-\alpha p\|^{2}+b_{n}\left(1-\gamma_{n}\right)\left[\left\|x_{n}-\alpha p\right\|^{2}+\left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2}\right. \\
& \left.-\delta_{n}\left(1-4 \delta_{n}^{2} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2}\right]+b_{n} \gamma_{n}\left\|x_{n}-\alpha p\right\|^{2} \\
& +b_{n} \gamma_{n}\left(1-\gamma_{n}\right)\left(c_{n}-1\right)\left\|w_{n}-x_{n}\right\|^{2}+c_{n}\left\|y_{n}-\alpha p\right\|^{2} \\
& -c_{n} b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-y_{n}\right\|^{2} \\
= & a_{n}\|u-\alpha p\|^{2}+b_{n}\left(1-\gamma_{n}\right)\left\|x_{n}-\alpha p\right\|^{2}+b_{n}\left(1-\gamma_{n}\right)\left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2} \\
& \left.-b_{n}\left(1-\gamma_{n}\right) \delta_{n}\left(1-4 \delta_{n}^{2} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2}\right]+b_{n} \gamma_{n}\left\|x_{n}-\alpha p\right\|^{2} \\
& +b_{n} \gamma_{n}\left(1-\gamma_{n}\right)\left(c_{n}-1\right)\left\|w_{n}-x_{n}\right\|^{2}+c_{n}\left\|y_{n}-\alpha p\right\|^{2} \\
& -c_{n} b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-y_{n}\right\|^{2}
\end{aligned}
$$

$$
\begin{align*}
\leq & a_{n}\|u-\alpha p\|^{2}+b_{n}\left(1-\gamma_{n}\right)\left\|x_{n}-\alpha p\right\|^{2}+b_{n}\left(1-\gamma_{n}\right)\left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2} \\
& \left.-b_{n}\left(1-\gamma_{n}\right) \delta_{n}\left(1-4 \delta_{n}^{2} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2}\right]+b_{n} \gamma_{n}\left\|x_{n}-\alpha p\right\|^{2} \\
& +b_{n} \gamma_{n}\left(1-\gamma_{n}\right)\left(c_{n}-1\right)\left\|w_{n}-x_{n}\right\|^{2}+c_{n}\left\|x_{n}-\alpha p\right\|^{2} \\
& -c_{n} b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-y_{n}\right\|^{2} \quad(\text { by }(3.5)) \\
= & a_{n}\|u-\alpha p\|^{2}+\left[b_{n}\left(1-\gamma_{n}\right)+b_{n} \gamma_{n}+c_{n}\right]\left\|x_{n}-\alpha p\right\|^{2} \\
& +b_{n}\left(1-\gamma_{n}\right)\left(1-\delta_{n}\right)\left\|-\left(w_{n}-y_{n}\right)\right\|^{2} \\
& -b_{n}\left(1-\gamma_{n}\right) \delta_{n}\left(1-4 \delta_{n}^{2} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \\
& +b_{n} \gamma_{n}\left(1-\gamma_{n}\right)\left(c_{n}-1\right)\left\|w_{n}-x_{n}\right\|^{2}-c_{n} b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-y_{n}\right\|^{2} \\
= & a_{n}\|u-\alpha p\|^{2}+\left[b_{n}\left(1-\gamma_{n}\right)+b_{n} \gamma_{n}+c_{n}\right]\left\|x_{n}-\alpha p\right\|^{2} \\
& +b_{n}\left(1-\gamma_{n}\right)\left(1-\delta_{n}\right)\left\|w_{n}-y_{n}\right\|^{2} \\
& -b_{n}\left(1-\gamma_{n}\right) \delta_{n}\left(1-4 \delta_{n}^{2} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \\
& +b_{n} \gamma_{n}\left(1-\gamma_{n}\right)\left(c_{n}-1\right)\left\|w_{n}-x_{n}\right\|^{2}-c_{n} b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-y_{n}\right\|^{2} \\
\leq & a_{n}\|u-\alpha p\|^{2}+\left[b_{n}\left(1-\gamma_{n}\right)+b_{n} \gamma_{n}+c_{n}\right]\left\|x_{n}-\alpha p\right\|^{2} \\
& +b_{n}\left(1-\gamma_{n}\right)\left(1-\delta_{n}-c_{n}\right)\left\|w_{n}-y_{n}\right\|^{2} \\
& -b_{n}\left(1-\gamma_{n}\right) \delta_{n}\left(1-4 \delta_{n}^{2} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \\
= & a_{n}\|u-\alpha p\|^{2}+\left(b_{n}+c_{n}\right)\left\|x_{n}-\alpha p\right\|^{2} \\
& +b_{n}\left(1-\gamma_{n}\right)\left(1-\delta_{n}-c_{n}\right)\left\|w_{n}-y_{n}\right\|^{2} \\
& -b_{n}\left(1-\gamma_{n}\right) \delta_{n}\left(1-4 \delta_{n}^{2} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} . \tag{3.13}
\end{align*}
$$

Using conditions (i) and (ii), we obtain

$$
\begin{align*}
1-4 \delta_{n}^{2} L^{2}-2 \delta_{n} & \geq 1-4 c^{2} L^{2}-2 c>0 \\
b_{n} \gamma_{n}\left(1-c_{n}-\delta_{n}\right) & =b_{n} \gamma_{n}\left(a_{n}+b_{n}-\delta_{n}\right) \leq 0  \tag{3.14}\\
a_{n}+b_{n}+c_{n} & =1
\end{align*}
$$

Putting (3.14) into (3.13), we obtain

$$
\begin{aligned}
\left\|x_{n+1}-\alpha p\right\|^{2} & \leq a_{n}\|u-\alpha p\|^{2}+\left(1-a_{n}\right)\left\|x_{n}-\alpha p\right\|^{2} \\
& \leq \max \left\{\|u-\alpha p\|^{2},\left\|x_{n}-\alpha p\right\|^{2}\right\}, \forall n \in(0, N)
\end{aligned}
$$

Using mathematical induction, we see that

$$
\begin{align*}
\left\|x_{n+1}-\alpha p\right\|^{2} & \leq \max \left\{\|u-\alpha p\|^{2},\left\|x_{n}-\alpha p\right\|^{2}\right\} \\
& =\left\|x_{0}-\alpha p\right\|^{2}, \forall n \in\{0, N\} \tag{3.15}
\end{align*}
$$

Hence, $\left\{x_{n}\right\}$ is bounded. This completes the proof.

Theorem 3.2. Let $H_{1}$ and $H_{2}$ be two Hilbert spaces and $C, Q$ be two nonempty, closed and convex subsets of $H_{1}$ and $H_{2}$ respectively. Let $F_{1}: C \times C \longrightarrow R$ and $F_{2}: Q \times Q \longrightarrow R$ be two bifunctions satisfying Assumption G. Let $A: C \longrightarrow H_{1}$ be a continous monotone mapping and $B: Q \longrightarrow H_{2}$ be a bounded linear operator. Let $S: C \longrightarrow C B(C)$ be L-Lipschitz $\alpha$-hemicontractive multivalued mapping. Assume that $\Theta=F(S) \cap \Omega \cap V I(C A)$ is nonempty and $S \alpha p=\alpha p$ for all $p \in \Theta$ and for some $\alpha \geq 1$.Let $x_{o}, u \in C$ be arbitrary and let $x_{n}$ be a sequence in $C$ generated by

$$
\left.\begin{array}{l}
z_{n}=T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x_{n},  \tag{3.16}\\
y_{n}=J_{t} z_{n} \\
u_{n}=\left(1-\delta_{n}\right) y_{n}+\delta_{n} v_{n}, \\
x_{n+1}=a_{n} u+b_{n}\left[\left(1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}\right]+c_{n} y_{n},
\end{array}\right\}
$$

for all $n \geq 0$, where $v_{n} \in S y_{n}$ and $w_{n} \in S u_{n}$ are such that $\left\|v_{n}-w_{n}\right\| \leq 2 D\left(S y_{n}-S u_{n}\right), s, r, t>$ $0, \lambda \in\left(0, \frac{1}{d}\right), d=B B^{\star}$, where $B^{\star}$ is the adjoint of $B, a_{n}, \delta_{n} \subset(0,1)$ and $b_{n}, c_{n} \subset[a, b]$ for some $a, b \in(0,1)$ satisfying the following conditions:
i. $a_{n}+b_{n}+c_{n}=1$,
ii. $a_{n}+b_{n} \leq \delta_{n} \leq c<\frac{1}{\sqrt{1+4 L^{2}+1}}$.

Then, the sequence $\left\{x_{n}\right\}$ converges strongly to $\alpha p \in \Theta$, where $\alpha p=P_{\Theta}(u)$

Proof. We note that $P_{\Theta}$ is well defined because $\Theta$ is nonempty, closed and convex subset of $C$, and from (3.1), it follows that the sequence $\left\{x_{n}\right\}$ is bounded and so are the sequences $\left\{u_{n}\right\}$ and $\left\{z_{n}\right\}$. Now, let $\alpha p \in \Theta$. Then, since $T_{s}^{F_{1}}$ is nonexpansive, we have

$$
\begin{aligned}
\left\|z_{n}-\alpha p\right\|^{2} & =\left\|T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x_{n}-\alpha p\right\|^{2} \\
& =\left\|T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x_{n}-T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) \alpha p\right\|^{2} \\
& \leq\left\|\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x_{n}-\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) \alpha p\right\|^{2} \\
& =\left\|x_{n}-\alpha p-\lambda\left(B^{\star}\left(1-T_{r}^{F_{2}}\right) B x_{n}-B^{\star}\left(1-T_{r}^{F_{2}}\right) B \alpha p\right)\right\|^{2},
\end{aligned}
$$

which by Lemma 2.3(i) gives

$$
\begin{aligned}
\left\|z_{n}-\alpha p\right\|^{2} \leq & \left\|x_{n}-\alpha p\right\|^{2}+\lambda^{2}\left\|B^{\star}\left(1-T_{r}^{F_{2}}\right) B x_{n}-B^{\star}\left(1-T_{r}^{F_{2}}\right) B \alpha p\right\|^{2} \\
& -2 \lambda\left\langle x_{n}-\alpha p, B^{\star}\left(1-T_{r}^{F_{2}}\right) B x_{n}-B^{\star}\left(1-T_{r}^{F_{2}}\right) B \alpha p\right\rangle .
\end{aligned}
$$

Since $B^{\star}\left(1-T_{r}^{F_{2}}\right) B$ is $\frac{1}{2 d}$-inversely strongly monotone, we have

$$
\begin{align*}
\left\|z_{n}-\alpha p\right\|^{2} \leq & \left\|x_{n}-\alpha p\right\|^{2}+\lambda^{2}\left\|B^{\star}\left(1-T_{r}^{F_{2}}\right) B x_{n}-B^{\star}\left(1-T_{r}^{F_{2}}\right) B \alpha p\right\|^{2} \\
& -\frac{\lambda}{d}\left\|B^{\star}\left(1-T_{r}^{F_{2}}\right) B x_{n}-B^{\star}\left(1-T_{r}^{F_{2}}\right) B \alpha p\right\|^{2} \\
= & \left\|x_{n}-\alpha p\right\|^{2}+\lambda^{2}\left\|B^{\star}\left(1-T_{r}^{F_{2}}\right) B x_{n}-B^{\star}\left(B \alpha p-T_{r}^{F_{2}} B \alpha p\right)\right\|^{2} \\
& -\frac{\lambda}{d}\left\|B^{\star}\left(1-T_{r}^{F_{2}}\right) B x_{n}-B^{\star}\left(B \alpha p-T_{r}^{F_{2}} B \alpha p\right)\right\|^{2} . \tag{3.17}
\end{align*}
$$

Since $B \alpha p=T_{r}^{F_{2}} B \alpha p$, (3.17) becomes

$$
\begin{align*}
\left\|z_{n}-\alpha p\right\|^{2} \leq & \left\|x_{n}-\alpha p\right\|^{2}+\lambda^{2}\left\|B^{\star}\left(1-T_{r}^{F_{2}}\right) B x_{n}\right\|^{2} \\
& -\frac{\lambda}{d}\left\|B^{\star}\left(1-T_{r}^{F_{2}}\right) B x_{n}\right\|^{2} \\
= & \left\|x_{n}-\alpha p\right\|^{2}+\lambda\left(\lambda-\frac{1}{d}\right)\left\|B^{\star}\left(1-T_{r}^{F_{2}}\right) B x_{n}\right\|^{2} . \tag{3.18}
\end{align*}
$$

Also, from (3.16), we get

$$
\begin{aligned}
\left\|x_{n+1}-\alpha p\right\|^{2} & \left.=\| a_{n} u+b_{n}\left[1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}\right]+c_{n} y_{n}-\alpha p \|^{2} \\
& \left.=\| a_{n}(u-\alpha p)+b_{n}\left[\left(1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}\right)-\alpha p\right]+c_{n}\left(y_{n}-\alpha p\right) \|^{2} \\
& \left.=\| b_{n}\left[\left(1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}\right)-\alpha p\right]+c_{n}\left(y_{n}-\alpha p\right)+a_{n}(u-\alpha p) \|^{2}
\end{aligned}
$$

which by Lemma 2.3(ii) gives

$$
\begin{aligned}
\left\|x_{n+1}-\alpha p\right\|^{2} \leq & \left.\| b_{n}\left[\left(1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}\right)-\alpha p\right]+c_{n}\left(y_{n}-\alpha p\right) \|^{2} \\
& +2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle,
\end{aligned}
$$

and by Lemma 2.2, we obtain

$$
\begin{aligned}
\left\|x_{n+1}-\alpha p\right\|^{2} \leq & b_{n}\left\|\left(1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}-\alpha p\right\|^{2}+c_{n}\left\|y_{n}-\alpha p\right\|^{2} \\
& -c_{n} b_{n}\left\|\left(1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}-y_{n}\right\|^{2}+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle \\
= & b_{n}\left\|\left(1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}-\gamma_{n}(\alpha p)+\gamma_{n}(\alpha p)-\alpha p\right\|^{2}+c_{n}\left\|y_{n}-\alpha p\right\|^{2} \\
& -c_{n} b_{n}\left\|\left(1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}-\gamma_{n} y_{n}+\gamma_{n} y_{n}-y_{n}\right\|^{2}+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle \\
= & b_{n}\left\|\left(1-\gamma_{n}\right)\left(w_{n}-\alpha p\right)+\gamma_{n}\left(x_{n}-\alpha p\right)\right\|^{2}+c_{n}\left\|y_{n}-\alpha p\right\|^{2} \\
& -c_{n} b_{n}\left\|\left(1-\gamma_{n}\right)\left(w_{n}-y_{n}\right)+\gamma_{n}\left(x_{n}-y_{n}\right)\right\|^{2}+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle \\
= & b_{n}\left[\left(1-\gamma_{n}\right)\left\|w_{n}-\alpha p\right\|^{2}+\gamma_{n}\left\|x_{n}-\alpha p\right\|^{2}-\gamma_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-x_{n}\right\|^{2}\right] \\
& +c_{n}\left\|y_{n}-\alpha p\right\|^{2}-c_{n} b_{n}\left[\left(1-\gamma_{n}\right)\left\|w_{n}-x_{n}\right\|^{2}+\gamma_{n}\left\|x_{n}-y_{n}\right\|^{2}\right. \\
& \left.-\gamma_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-x_{n}\right\|^{2}\right]+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle \\
= & b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-\alpha p\right\|^{2}+b_{n} \gamma_{n}\left\|x_{n}-\alpha p\right\|^{2} \\
& +c_{n}\left\|y_{n}-\alpha p\right\|^{2}+b_{n} \gamma_{n}\left(1-\gamma_{n}\right)\left(c_{n}-1\right)\left\|w_{n}-x_{n}\right\|^{2} \\
& -c_{n} b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-y_{n}\right\|^{2}-c_{n} b_{n} \gamma_{n}\left\|x_{n}-y_{n}\right\|^{2} \\
& +2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle .
\end{aligned}
$$

Using (3.4), (3.16) and (3.11) into (3.19), we obtain

$$
\begin{align*}
\left\|x_{n+1}-\alpha p\right\|^{2} \leq & b_{n}\left(1-\gamma_{n}\right)\left[\left\|x_{n}-\alpha p\right\|^{2}+\left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2}-\delta_{n}\left(1-4 \delta_{n}^{2} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2}\right] \\
& +b_{n} \gamma_{n}\left\|x_{n}-\alpha p\right\|^{2}+c_{n}\left\|z_{n}-\alpha p\right\|^{2}+b_{n} \gamma_{n}\left(1-\gamma_{n}\right)\left(c_{n}-1\right)\left\|w_{n}-x_{n}\right\|^{2} \\
& -c_{n} b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-y_{n}\right\|^{2}-c_{n} b_{n} \gamma_{n}\left\|x_{n}-y_{n}\right\|^{2}+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle \\
= & b_{n}\left(1-\gamma_{n}\right)\left\|x_{n}-\alpha p\right\|^{2}+b_{n}\left(1-\gamma_{n}\right)\left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2} \\
& -\delta_{n} b_{n}\left(1-\gamma_{n}\right)\left(1-4 \delta_{n}^{2} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2}+b_{n} \gamma_{n}\left\|x_{n}-\alpha p\right\|^{2} \\
& +c_{n}\left\|z_{n}-\alpha p\right\|^{2}+b_{n} \gamma_{n}\left(1-\gamma_{n}\right)\left(c_{n}-1\right)\left\|w_{n}-x_{n}\right\|^{2}-c_{n} b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-y_{n}\right\|^{2} \\
\text { (3.20) } \quad & -c_{n} b_{n} \gamma_{n}\left\|x_{n}-y_{n}\right\|^{2}+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle . \tag{3.20}
\end{align*}
$$

(3.18) and (3.20) imply that

$$
\begin{aligned}
& \left\|x_{n+1}-\alpha p\right\|^{2} \leq b_{n}\left(1-\gamma_{n}\right)\left\|x_{n}-\alpha p\right\|^{2}+b_{n}\left(1-\gamma_{n}\right)\left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2} \\
& -\delta_{n} b_{n}\left(1-\gamma_{n}\right)\left(1-4 \delta_{n}^{2} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2}+b_{n} \gamma_{n}\left\|x_{n}-\alpha p\right\|^{2} \\
& +c_{n}\left[\left\|x_{n}-\alpha p\right\|^{2}+\lambda\left(\lambda-\frac{1}{d}\right)\left\|B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right\|^{2}\right]+b_{n} \gamma_{n}\left(1-\gamma_{n}\right)\left(c_{n}-1\right)\left\|w_{n}-x_{n}\right\|^{2} \\
& -c_{n} b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-y_{n}\right\|^{2}-c_{n} b_{n} \gamma_{n}\left\|x_{n}-y_{n}\right\|^{2}+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle \\
= & \left(b_{n}+c_{n}\right)\left\|x_{n}-\alpha p\right\|^{2}+b_{n}\left(1-\gamma_{n}\right)\left(1-c_{n}-\delta_{n}\right)\left\|w_{n}-y_{n}\right\|^{2} \\
& -\delta_{n} b_{n}\left(1-\gamma_{n}\right)\left(1-4 \delta_{n}^{2} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \\
& \left.+c_{n} \lambda\left(\lambda-\frac{1}{d}\right)\left\|B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right\|^{2}\right]+b_{n} \gamma_{n}\left(1-\gamma_{n}\right)\left(c_{n}-1\right)\left\|w_{n}-x_{n}\right\|^{2} \\
& -c_{n} b_{n} \gamma_{n}\left\|x_{n}-y_{n}\right\|^{2}+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle \\
\leq & \left(b_{n}+c_{n}\right)\left\|x_{n}-\alpha p\right\|^{2}+b_{n}\left(1-\gamma_{n}\right)\left(1-c_{n}-\delta_{n}\right)\left\|w_{n}-y_{n}\right\|^{2} \\
& -\delta_{n} b_{n}\left(1-\gamma_{n}\right)\left(1-4 \delta_{n}^{2} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \\
& \left.+c_{n} \lambda\left(\lambda-\frac{1}{d}\right)\left\|B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right\|^{2}\right] \\
& -c_{n} b_{n} \gamma_{n}\left\|x_{n}-y_{n}\right\|^{2}+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle
\end{aligned}
$$

Using (3.14), condition (i) and (ii), and the fact that $\lambda \in\left(0, \frac{1}{d}\right)$, we get

$$
\begin{align*}
\left\|x_{n+1}-\alpha p\right\|^{2} \leq & \left.\left(1-a_{n}\right)\left\|x_{n}-\alpha p\right\|^{2}+c_{n} \lambda\left(\lambda-\frac{1}{d}\right)\left\|B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right\|^{2}\right] \\
& +2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle . \tag{3.21}
\end{align*}
$$

Then, we complete the proof by the next two cases:
Case 1: Suppose that there exists a positive integer $n_{0}$ such that $\left\{\left\|x_{n}-\alpha p\right\|\right\}$ is decreasing for all $n \geq n_{0}$. Then, the sequence $\left\{\left\|x_{n}-\alpha p\right\|\right\}$ is convergent, and from (3.21), we have

$$
\begin{aligned}
c_{n} \lambda\left(\frac{1}{d}-\lambda\right)\left\|B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right\|^{2} \leq & \left(1-a_{n}\right)\left\|x_{n}-\alpha p\right\|^{2}-\left\|x_{n+1}-\alpha p\right\|^{2} \\
& +2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle .
\end{aligned}
$$

Hence, assumption of $\left\{c_{n}\right\}$, convergence of $\left\{\left\|x_{n}-\alpha p\right\|\right\}$ and the fact that $a_{n} \rightarrow 0$ as $n \rightarrow \infty$ imply that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right\|=0 \tag{3.22}
\end{equation*}
$$

and hence

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \| x_{n}-\left(x_{n}-\lambda B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n} \|=0\right. \tag{3.23}
\end{equation*}
$$

And since $T_{s}^{F_{1}}$ is firmly nonexpansive and $\left(I-\lambda B^{\star}\left(I-T_{r}^{F_{2}}\right) B\right)$ is nonexpansive, using (3.16) and Lemma 2.3(i), we obtain

$$
\begin{aligned}
\left\|z_{n}-\alpha p\right\|^{2}= & \left\|T_{s}^{F_{1}}\left(I-\lambda B^{\star}\left(I-T_{r}^{F_{2}}\right) B\right) x_{n}-T_{s}^{F_{1}} \alpha p\right\|^{2} \\
\leq & \left\langle z_{n}-\alpha p,\left(I-\lambda B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right)-\alpha p\right\rangle \\
= & \left\|z_{n}-\alpha p\right\|\left\|\left(I-\lambda B^{\star}\left(I-T_{r}^{F_{2}}\right) B\right) x_{n}-\alpha p\right\| \\
\leq & \frac{1}{2}\left\{\left\|z_{n}-\alpha p\right\|^{2}+\left\|\left(I-\lambda B^{\star}\left(I-T_{r}^{F_{2}}\right) B\right) x_{n}-\alpha p\right\|^{2}\right. \\
& -\|\left(z_{n}-\left(I-\lambda B^{\star}\left(I-T_{r}^{F_{2}}\right) B\right) x_{n} \|^{2}\right\}
\end{aligned}
$$

$$
\begin{aligned}
= & \frac{1}{2}\left\{\left\|z_{n}-\alpha p\right\|^{2}+\left\|x_{n}-\alpha p\right\|^{2}+\lambda^{2}\left\|B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right\|^{2}\right. \\
& -2 \lambda\left\langle x_{n}-\alpha p, B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right\rangle-\left\|z_{n}-x_{n}\right\|^{2}-\lambda^{2}\left\|B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right\|^{2} \\
& \left.+2 \lambda\left\langle z_{n}-x_{n}, B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right\rangle\right\} \\
\leq & \frac{1}{2}\left\{\left\|z_{n}-\alpha p\right\|^{2}+\left\|x_{n}-\alpha p\right\|^{2}-\left\|z_{n}-x_{n}\right\|^{2}+2 \lambda\left\langle z_{n}-x_{n}, B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right\rangle\right\} .
\end{aligned}
$$

Thus,

$$
\begin{equation*}
\left\|z_{n}-\alpha p\right\|^{2} \leq\left\|x_{n}-\alpha p\right\|^{2}-\left\|z_{n}-x_{n}\right\|^{2}+2 \lambda\left\langle z_{n}-x_{n}, B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right\rangle . \tag{3.24}
\end{equation*}
$$

Now, from (3.4) and (3.20), we get

$$
\begin{align*}
\left\|x_{n+1}-\alpha p\right\|^{2} \leq & b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-\alpha p\right\|^{2}+\gamma_{n} b_{n}\left\|x_{n}-\alpha p\right\|^{2}+c_{n}\left\|z_{n}-\alpha p\right\|^{2} \\
& -c_{n} b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-y_{n}\right\|^{2}+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle . \tag{3.25}
\end{align*}
$$

Substituting (3.11) and (3.24) into (3.25), we obtain

$$
\begin{align*}
\left\|x_{n+1}-\alpha p\right\|^{2} \leq & b_{n}\left(1-\gamma_{n}\right)\left[\left\|x_{n}-\alpha p\right\|^{2}+\left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2}\right. \\
& \left.-\delta_{n}\left(1-4 \delta_{n} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2}\right]+\gamma_{n} b_{n}\left\|x_{n}-\alpha p\right\|^{2} \\
& +c_{n}\left[\left\|x_{n}-\alpha p\right\|^{2}-\left\|z_{n}-x_{n}\right\|^{2}+2 \lambda\left\langle z_{n}-x_{n}, B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right\rangle\right] \\
& -c_{n} b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-y_{n}\right\|^{2}+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle \\
= & \left(b_{n}+c_{n}\right)\left\|x_{n}-\alpha p\right\|^{2}+b_{n}\left(1-\gamma_{n}\right)\left(1-c_{n}-\delta_{n}\right)\left\|w_{n}-y_{n}\right\|^{2} \\
& -b_{n} \delta_{n}\left(1-\gamma_{n}\right)\left(1-4 \delta_{n} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2}-c_{n}\left\|z_{n}-x_{n}\right\|^{2} \\
& +2 c_{n} \lambda\left\langle z_{n}-x_{n}, B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right\rangle+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle . \tag{3.26}
\end{align*}
$$

It follows from condition (i),(3.14) and (3.26) that

$$
\begin{aligned}
c_{n}\left\|z_{n}-x_{n}\right\|^{2} \leq & \left(1-a_{n}\right)\left\|x_{n}-\alpha p\right\|^{2}-\left\|x_{n+1}-\alpha p\right\|^{2}+2 c_{n} \lambda\left\|z_{n}-x_{n}\right\|\left\|B^{\star}\left(I-T_{r}^{F_{2}}\right) B x_{n}\right\| \\
& +2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle .
\end{aligned}
$$

Hence, since $\left\{x_{n}\right\}$ and $\left\{z_{n}\right\}$ are bounded and $a_{n} \rightarrow 0$ as $n \rightarrow \infty$, from (3.22) and the assumption of $c_{n}$, we obtain that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|z_{n}-x_{n}\right\|=0 \tag{3.27}
\end{equation*}
$$

On the other hand, since $J_{t}$ is firmly nonexpansive, it follows from lemma 2.3(i) and (3.16) that

$$
\begin{align*}
\left\|y_{n}-\alpha p\right\|^{2} & =\left\|J_{t} z_{n}-J_{t} \alpha p\right\|^{2} \\
& \leq\left\langle y_{n}-\alpha p, z_{n}-\alpha p\right\rangle \\
& =\frac{1}{2}\left\{\left\|y_{n}-\alpha p\right\|^{2}+\left\|z_{n}-\alpha p\right\|^{2}-\left\|z_{n}-y_{n}\right\|^{2}\right\} . \tag{3.28}
\end{align*}
$$

(3.3) and (3.28) imply that

$$
\begin{align*}
\left\|y_{n}-\alpha p\right\|^{2} & \leq\left\|z_{n}-\alpha p\right\|^{2}-\left\|z_{n}-y_{n}\right\|^{2} \\
& \leq\left\|x_{n}-\alpha p\right\|^{2}-\left\|z_{n}-y_{n}\right\|^{2} \tag{3.29}
\end{align*}
$$

Substituting (3.11) and (3.28) into (3.25), we get

$$
\begin{aligned}
\left\|x_{n+1}-\alpha p\right\|^{2} \leq & b_{n}\left(1-\gamma_{n}\right)\left[\left\|x_{n}-\alpha p\right\|^{2}+\left(1-\delta_{n}\right)\left\|y_{n}-w_{n}\right\|^{2}\right. \\
& \left.-\delta_{n}\left(1-4 \delta_{n} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2}\right]+\gamma_{n} b_{n}\left\|x_{n}-\alpha p\right\|^{2} \\
& +c_{n}\left[\left\|x_{n}-\alpha p\right\|^{2}-\left\|z_{n}-y_{n}\right\|^{2}\right]-c_{n} b_{n}\left(1-\gamma_{n}\right)\left\|w_{n}-y_{n}\right\|^{2} \\
& +2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle \\
= & \left(b_{n}+c_{n}\right)\left\|x_{n}-\alpha p\right\|^{2}+b_{n}\left(1-\gamma_{n}\right)\left(1-c_{n}-\delta_{n}\right)\left\|w_{n}-y_{n}\right\|^{2} \\
& -b_{n} \delta_{n}\left(1-\gamma_{n}\right)\left(1-4 \delta_{n} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2}-c_{n}\left\|z_{n}-y_{n}\right\|^{2} \\
& +2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle
\end{aligned}
$$

which from condition (i) and (3.14) yield

$$
\begin{aligned}
\left\|x_{n+1}-\alpha p\right\|^{2} \leq & \left(1-a_{n}\right)\left\|x_{n}-\alpha p\right\|^{2}-b_{n} \delta_{n}\left(1-\gamma_{n}\right)\left(1-4 \delta_{n} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \\
& -c_{n}\left\|z_{n}-y_{n}\right\|^{2}+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle
\end{aligned}
$$

(3.30) implies that

$$
\begin{aligned}
b_{n} \delta_{n}\left(1-\gamma_{n}\right)\left(1-4 \delta_{n} L^{2}-2 \delta_{n}\right)\left\|y_{n}-v_{n}\right\|^{2} \leq & \left(1-a_{n}\right)\left\|x_{n}-\alpha p\right\|^{2}-\left\|x_{n+1}-\alpha p\right\|^{2} \\
& -c_{n}\left\|z_{n}-y_{n}\right\|^{2}+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle
\end{aligned}
$$

Hence, the assumption that $a_{n} \rightarrow 0$ as $n \rightarrow \infty$ and (3.14) imply that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|y_{n}-v_{n}\right\|=0 \tag{3.31}
\end{equation*}
$$

Since $v_{n} \in S y_{n}$, using (3.31), we get

$$
\begin{equation*}
\lim _{n \rightarrow \infty} d\left(y_{n}, S y_{n}\right)=0 \tag{3.32}
\end{equation*}
$$

In addition, from (3.30), we also have

$$
c_{n}\left\|z_{n}-y_{n}\right\|^{2} \leq\left(1-a_{n}\right)\left\|x_{n}-\alpha p\right\|^{2}-\left\|x_{n+1}-\alpha p\right\|^{2}+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle,
$$

and, because $a_{n} \rightarrow 0$ as $n \rightarrow \infty$, it follows from the assumption of $\left\{c_{n}\right\}$ that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|y_{n}-z_{n}\right\|=0 \tag{3.33}
\end{equation*}
$$

From the Lipschitz condition of $S$ and (3.30), we get

$$
\begin{align*}
\left\|y_{n}-w_{n}\right\| & \leq\left\|y_{n}-v_{n}\right\|+\left\|v_{n}-w_{n}\right\| \\
& \leq\left\|y_{n}-v_{n}\right\|+2 D\left(S y_{n}, S u_{n}\right) \\
& \leq\left\|y_{n}-v_{n}\right\|+2 L\left\|y_{n}-u_{n}\right\| \\
& =\left(1+2 L \delta_{n}\right)\left\|y_{n}-v_{n}\right\| \rightarrow 0 \text { as } n \rightarrow \infty . \tag{3.34}
\end{align*}
$$

Observe that

$$
\begin{aligned}
\left\|x_{n+1}-x_{n}\right\| & \leq\left\|x_{n+1}-y_{n}\right\|+\left\|y_{n}-x_{n}\right\| \\
& =\left\|a_{n} u+b_{n}\left[\left(1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}\right]+c_{n} y_{n}-y_{n}\right\|+\left\|y_{n}-x_{n}\right\| \\
& =\left\|a_{n}\left(u-y_{n}\right)-b_{n}\left(1-\gamma_{n}\right)\left(y_{n}-w_{n}\right)-\gamma_{n} b_{n}\left(y_{n}-x_{n}\right)\right\|+\left\|y_{n}-x_{n}\right\| \\
& \leq a_{n}\left\|u-y_{n}\right\|+b_{n}\left(1-\gamma_{n}\right)\left\|y_{n}-w_{n}\right\|+\gamma_{n} b_{n}\left\|y_{n}-x_{n}\right\|+\left\|y_{n}-x_{n}\right\| \\
& =a_{n}\left\|u-y_{n}\right\|+b_{n}\left(1-\gamma_{n}\right)\left\|y_{n}-w_{n}\right\|+\left(1+\gamma_{n} b_{n}\right)\left\|y_{n}-x_{n}\right\|,
\end{aligned}
$$

which, from (3.27), (3.33), (3.34) and the fact that $a_{n} \rightarrow 0$ as $n \rightarrow \infty$, gives

$$
\begin{align*}
\left\|x_{n+1}-x_{n}\right\| \leq & a_{n}\left\|u-y_{n}\right\|+b_{n}\left(1-\gamma_{n}\right)\left\|y_{n}-w_{n}\right\|+\left(1+\gamma_{n} b_{n}\right)\left\|z_{n}-y_{n}\right\| \\
& +\left(1+\gamma_{n} b_{n}\right)\left\|z_{n}-x_{n}\right\| \rightarrow 0 \text { as } n \rightarrow \infty . \tag{3.35}
\end{align*}
$$

Moreover, from (3.14) and (3.30), we get

$$
\begin{equation*}
\left\|x_{n+1}-\alpha p\right\|^{2} \leq\left(1-a_{n}\right)\left\|x_{n}-\alpha p\right\|^{2}+2 a_{n}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle \tag{3.36}
\end{equation*}
$$

Now, let $\alpha p=P_{\Theta}(u)$. Then, we show that $\limsup _{n \rightarrow \infty}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle \leq 0$.
Since the sequence $\left\{x_{n+1}\right\}$ is bounded in a real Hilbert space $H_{1}$, we can choose a subsequence $\left\{x_{n_{i}+1}\right\}$ of $\left\{x_{n+1}\right\}$ such that $x_{n_{i}+1} \rightharpoonup \omega$ as $n \rightarrow \infty$ and

$$
\limsup _{n \rightarrow \infty}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle=\lim _{n \rightarrow \infty}\left\langle u-\alpha p, x_{n+1}-\alpha p\right\rangle
$$

Since $C$ is closed and convex, $C$ is weakly closed. So, we have $\omega$ in $C$ and from (3.35), we find that $x_{n_{i}} \rightharpoonup \omega$ as $i \rightarrow \infty$, and thus it follows from (3.27) and (3.33) that $z_{n_{i}} \rightharpoonup \omega$ and $y_{n_{i}} \rightharpoonup \omega$ as $i \rightarrow \infty$

Next, we claim that $\omega \in \Theta$. From (3.32) and the hypothesis that $(I-S)$ is demiclosed at zero, we obtain that $\omega \in F$.

Since $\left(I-\lambda B^{\star}\left(I-T_{r}^{F_{2}}\right) B\right)$ is nonexpansive, from (3.23) and demiclosedness principle for nonexpansive mapping, we have

$$
\left(I-\lambda B^{\star}\left(I-T_{r}^{F_{2}}\right) B\right) \omega=\omega
$$

which implies that

$$
B^{\star}\left(I-T_{r}^{F_{2}}\right) B \omega=0
$$

Thus, using (2.1), we obtain that $B \omega=T_{r}^{F_{2}} \omega$, hence $B \omega \in E P\left(F_{2}\right)$. In addition, from (3.27), we get

$$
\lim _{n \rightarrow \infty}\left\|x_{n}-T_{s}^{F_{1}}\left(I-\lambda B^{\star}\left(I-T_{r}^{F_{2}}\right) B\right) x_{n}\right\|=\lim _{n \rightarrow \infty}\left\|x_{n}-z_{n}\right\|=0 .
$$

Hence, since $T_{s}^{F_{1}}\left(I-\lambda B^{\star}\left(I-T_{r}^{F_{2}}\right) B\right)$ is nonexpansive, from the demiclosedness of nonexpansive mapping, we obtain that

$$
T_{s}^{F_{1}}\left(I-\lambda B^{\star}\left(I-T_{r}^{F_{2}}\right) B\right) \omega=\omega
$$

This, with the fact that $B \omega=T_{r}^{F_{2}} B \omega$, gives $\omega=T_{s}^{F_{1}} \omega$ and hence $\omega \in E P\left(F_{1}\right)$. Therefore, $\omega \in \Omega$.

On the other hand, from (3.33) we have

$$
\lim _{n \rightarrow \infty}\left\|z_{n_{i}}-J_{t} z_{n}\right\|=\lim _{n \rightarrow}\left\|z_{n}-y_{n}\right\|=0
$$

Since $z_{n_{i}} \rightharpoonup \omega$ and $J_{t}$ is nonexpansive, then $\left(I-J_{t}\right)$ is demiclosed at zero and so, we get that $\omega=J_{t} \omega$ and hence $\omega \in \operatorname{VI}(C, A)$. Therefore, $\omega \in \Theta$. Thus, since $\alpha q=P_{\Theta}(u)$ and $x_{n_{i}+1} \rightharpoonup \omega$, from the property of metric projection $P_{C}$ given in (2.2), we have

$$
\begin{align*}
\limsup _{n \rightarrow \infty}\left\langle u-\alpha q, x_{n+1}-\alpha q\right\rangle & =\lim _{n \rightarrow \infty}\left\langle u-\alpha q, x_{n+1}-\alpha q\right\rangle \\
& =\left\langle u-\alpha q, x_{n+1}-\alpha q\right\rangle \leq 0 \tag{3.37}
\end{align*}
$$

Furthermore, since $\alpha p$ was arbitrary, $\alpha q \in \Theta$, then from (3.36), (3.37) and lemma 2.5, we get that

$$
\left\|x_{n}-\alpha q\right\|=0 \text { as } n \rightarrow \infty
$$

Consequently $x_{n} \rightarrow \alpha q=P_{\Theta}(u)$.

Case 2. Suppose there exists a subsequence $n_{j}$ of $n$ such that

$$
\left\|x_{n_{j}}-\alpha p\right\| \leq\left\|x_{n_{j}+1}-\alpha p\right\|,
$$

for all $j \in N$. Then, by lemma 2.7, there exists a nondecreasing sequence $\left\{m_{k}\right\} \subset N$ such that $m_{k} \rightarrow \infty$ and

$$
\begin{equation*}
\left\|x_{m_{k}}-\alpha p\right\| \leq\left\|x_{m_{k}+1}-\alpha p\right\| \text { and }\left\|x_{k}-\alpha p\right\| \leq\left\|x_{m_{k}+1}-\alpha p\right\|, \tag{3.38}
\end{equation*}
$$

for all $k \in N$. Thus, from condition (i), (3.14),(3.26), (3.30),(3.38) and the hypothesis that $a_{n} \rightarrow 0$ as $n \rightarrow \infty$, we get

$$
\left\|z_{m_{k}}-x_{m_{k}}\right\| \rightarrow o,\left\|y_{m_{k}}-v_{m_{k}}\right\| \rightarrow o \text { and }\left\|y_{m_{k}}-z_{m_{k}}\right\| \rightarrow o \text { as } k \rightarrow \infty .
$$

Then, since $\alpha q=P_{\Theta}(u)$, following the same procedure as in Case 1, we get

$$
\begin{equation*}
\limsup _{k \rightarrow \infty}\left\langle u-\alpha q, x_{m_{k}+1}-\alpha q\right\rangle \leq 0 \tag{3.39}
\end{equation*}
$$

Now, since $\alpha q \in \Theta$, from (3.30) and (3.33), we have that

$$
\begin{equation*}
\left\|x_{m_{k}+1}-\alpha q\right\|^{2} \leq\left(1-a_{m_{k}}\right)\left\|x_{m_{k}}-\alpha q\right\|^{2}+2 a_{m_{k}}\left\langle u-\alpha q, x_{m_{k}+1}-\alpha q\right\rangle \tag{3.40}
\end{equation*}
$$

and hence (3.38) and (3.40) imply that

$$
\begin{aligned}
a_{m_{k}}\left\|x_{m_{k}}-\alpha q\right\|^{2} & \leq\left\|x_{m_{k}}-\alpha q\right\|^{2}-\left\|x_{m_{k}+1}-\alpha q\right\|^{2}+2 a_{m_{k}}\left\langle u-\alpha q, x_{m_{k}+1}-\alpha q\right\rangle \\
& \leq 2 a_{m_{k}}\left\langle u-\alpha q, x_{m_{k}+1}-\alpha q\right\rangle
\end{aligned}
$$

Hence, in view of the fact that $a_{m_{k}}>0$, we have that

$$
\left\|x_{m_{k}}-\alpha q\right\|^{2} \leq 2\left\langle u-\alpha q, x_{m_{k}+1}-\alpha q\right\rangle .
$$

Hence, using (3.39), we obtain that $\left\|x_{m_{k}}-\alpha q\right\| \rightarrow 0$ as $k \rightarrow \infty$. This together with (3.40) implies that $\left\|x_{m_{k}+1}-\alpha q\right\| \rightarrow 0$ as $k \rightarrow \infty$. Because $\left\|x_{k}-\alpha p\right\| \leq\left\|x_{m_{k}+1}-\alpha p\right\|$, for all $k \in N$, we have that $x_{k} \rightarrow \alpha q$. Therefore, from the above two Cases, we deduce that the sequence $\left\{x_{n}\right\}$ converges strongly to $\alpha q=P_{\Theta}(u)$. This completes the proof.

If, in Theorem 3.2, we assume that $S$ is a single-valued Lipschitz $\alpha$-hemicontractive mapping, then we obtain the following results:

Corollary 3.3. Let $H_{1}$ and $H_{2}$ be two Hilbert spaces and $C, Q$ be two nonempty, closed and convex subsets of $H_{1}$ and $H_{2}$ respectively. Let $F_{1}: C \times C \longrightarrow R$ and $F_{2}: K \times K \longrightarrow R$ be two bifunctions satisfying Assumption $G$. Let $A: C \longrightarrow H_{1}$ be a continous monotone mapping and $B: Q \longrightarrow H_{2}$ be a bounded linear operator. Let $S: C \longrightarrow C B(C)$ be L-Lipschitz $\alpha$-hemicontractive mapping. Assume that $\Theta=F(S) \cap \Omega \cap V I(C A)$ is nonempty and $S \alpha p=\alpha p$ for all $p \in \Theta$ and for some $\alpha \geq 1$. Let $x_{o}, u \in C$ be arbitrary and let $x_{n}$ be a sequence in $C$ generated by

$$
\begin{align*}
& z_{n}=T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x_{n} \\
& y_{n}=J_{t} z_{n}  \tag{3.41}\\
& u_{n}=\left(1-\delta_{n}\right) y_{n}+\delta_{n} v_{n} \\
& x_{n+1}=a_{n} u+b_{n}\left[\left(1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}\right]+c_{n} y_{n}
\end{align*}
$$

for all $n \geq 0$, where $v_{n} \in S y_{n}$ and $w_{n} \in S u_{n}$ are such that $\left\|v_{n}-w_{n}\right\| \leq 2 D\left(S y_{n}-S u_{n}\right), s, r, t>$ $0, \lambda \in\left(0, \frac{1}{d}\right), d=B B^{\star}$, where $B^{\star}$ is the adjoint of $B, a_{n}, \delta_{n} \subset(0,1)$ and $b_{n}, c_{n} \subset[a, b]$ for some $a, b \in(0,1)$ satisfying the following conditions:
i. $a_{n}+b_{n}+c_{n}=1$
ii. $a_{n}+b_{n} \leq \delta_{n} \leq c<\frac{1}{\sqrt{1+4 L^{2}}+1}$

Then, the sequence $\left\{x_{n\}}\right.$ converges strongly to $\alpha p \in \Theta$, where $\alpha p=P_{\Theta}(u)$

If, in Theorem 3.2, we assume that $A \equiv 0$, then we find the following result on split equilibrium and fixed point problem for Lipschitz $\alpha$-hemicontractive multivalued mapping:

Corollary 3.4. Let $H_{1}$ and $H_{2}$ be two Hilbert spaces and $C, Q$ be two nonempty, closed and convex subsets of $H_{1}$ and $H_{2}$ respectively. Let $F_{1}: C \times C \longrightarrow R$ and $F_{2}: K \times K \longrightarrow R$ be two bifunctions satisfying Assumption G. Let $A: C \longrightarrow H_{1}$ be a continous monotone mapping and $B: Q \longrightarrow H_{2}$ be a bounded linear operator. Let $S: C \longrightarrow C B(C)$ be L-Lipschitz $\alpha$-hemicontractive mapping. Assume that $\Theta=F(S) \cap \Omega$ is nonempty and $S \alpha p=\alpha$ for all $p \in \Theta$ and for some $\alpha \geq 1$.Let $x_{o}, u \in C$ be arbitrary and let $x_{n}$ be a sequence in $C$ generated by

$$
\begin{align*}
& z_{n}=T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x_{n} \\
& u_{n}=\left(1-\delta_{n}\right) y_{n}+\delta_{n} v_{n}  \tag{3.42}\\
& x_{n+1}=a_{n} u+b_{n}\left[\left(1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}\right]+c_{n} y_{n}
\end{align*}
$$

for all $n \geq 0$, where $v_{n} \in S y_{n}$ and $w_{n} \in S u_{n}$ are such that $\left\|v_{n}-w_{n}\right\| \leq 2 D\left(S y_{n}-S u_{n}\right), s, r,>$ $0, \lambda \in\left(0, \frac{1}{d}\right), d=B B^{\star}$, where $B^{\star}$ is the adjoint of $B, a_{n}, \delta_{n} \subset(0,1)$ and $b_{n}, c_{n} \subset[a, b]$ for some $a, b \in(0,1)$ satisfying the following conditions:
i. $a_{n}+b_{n}+c_{n}=1$
ii. $a_{n}+b_{n} \leq \delta_{n} \leq c<\frac{1}{\sqrt{1+4 L^{2}}+1}$

Then, the sequence $\left\{x_{n}\right\}$ converges strongly to $\alpha p \in \Theta$, where $\alpha p=P_{\Theta}(u)$

If, in Theorem 3.2, we assume that $H_{1}=H_{2}, C=Q, B \equiv 1$ and $F_{2} \equiv 0$, then we obtain the following corollary:

Corollary 3.5. Let $H_{1}$ a real Hilbert spaces and $C$ be a nonempty, closed and convex subsets of $H_{1}$. Let $F_{1}: C \times C \longrightarrow R$ be a bifunctions satisfying Assumption $G$ and let $A: C \longrightarrow H_{1}$ be a continous monotone mapping . Let $S: C \longrightarrow C B(C)$ be L-Lipschitz $\alpha$-hemicontractive multivalued mapping. Assume that $\Theta=F(S) \cap E P\left(F_{1}\right) \cap V I(C A)$ is nonempty, closed and convex, S $\alpha p=\alpha p$ for all $p \in \Theta$ and for some $\alpha \geq 1$. Let $x_{o}, u \in C$ be arbitrary and let $x_{n}$ be a sequence in C generated by

$$
\begin{align*}
& z_{n}=T_{s}^{F_{1}} x_{n} \\
& y_{n}=J_{t} z_{n}  \tag{3.43}\\
& u_{n}=\left(1-\delta_{n}\right) y_{n}+\delta_{n} v_{n} \\
& x_{n+1}=a_{n} u+b_{n}\left[\left(1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}\right]+c_{n} y_{n}
\end{align*}
$$

for all $n \geq 0$, where $v_{n} \in S y_{n}$ and $w_{n} \in S u_{n}$ are such that $\left\|v_{n}-w_{n}\right\| \leq 2 D\left(S y_{n}-S u_{n}\right), s, r, t>0$, $a_{n}, \delta_{n} \subset(0,1)$ and $b_{n}, c_{n} \subset[a, b]$ for some $a, b \in(0,1)$ satisfying the following conditions:
i. $a_{n}+b_{n}+c_{n}=1$
ii. $a_{n}+b_{n} \leq \delta_{n} \leq c<\frac{1}{\sqrt{1+4 L^{2}}+1}$

Then, the sequence $\left\{x_{n}\right\}$ converges strongly to $\alpha p \in \Theta$, where $\alpha p=P_{\Theta}(u)$

If, in Corollary 3.3, we assume that $S$ is an identity mapping, then we get the following result on variational inequality and split equilibrium problems:

Corollary 3.6. Let $H_{1}$ and $H_{2}$ be two Hilbert spaces and $C, Q$ be two nonempty, closed and convex subsets of $H_{1}$ and $H_{2}$ respectively. Let $F_{1}: C \times C \longrightarrow R$ and $F_{2}: K \times K \longrightarrow R$ be two bifunctions satisfying Assumption G. Let $A: C \longrightarrow H_{1}$ be a continous monotone mapping and $B: Q \longrightarrow H_{2}$ be a bounded linear operator. . Assume that $\Theta=\Omega \cap V I(C A)$ is nonempty and $S \alpha p=\alpha p$ for all $p \in \Theta$ and for some $\alpha \geq 1$.Let $x_{o}, u \in C$ be arbitrary and let $x_{n}$ be a sequence in C generated by

$$
\begin{align*}
& z_{n}=T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x_{n} \\
& y_{n}=J_{t} z_{n}  \tag{3.44}\\
& x_{n+1}=a_{n} u+b_{n} \gamma_{n} x_{n}+c_{n} y_{n}
\end{align*}
$$

for all $n \geq 0$, where $v_{n} \in S y_{n}$ and $w_{n} \in S u_{n}$ are such that $\left\|v_{n}-w_{n}\right\| \leq 2 D\left(S y_{n}-S u_{n}\right), s, r, t>$ $0, \lambda \in\left(0, \frac{1}{d}\right), d=B B^{\star}$, where $B^{\star}$ is the adjoint of $B, a_{n}, \delta_{n} \subset(0,1)$ and $b_{n}, c_{n} \subset[a, b]$ for some $a, b \in(0,1)$ satisfying the following conditions:
i. $a_{n}+b_{n}+c_{n}=1$
ii. $a_{n}+b_{n} \leq \delta_{n} \leq c<\frac{1}{\sqrt{1+4 L^{2}}+1}$

Then, the sequence $\left\{x_{n}\right\}$ converges strongly to $\alpha p \in \Theta$, where $\alpha p=P_{\Theta}(u)$

If, in Corollary 3.5 , we assume that $F_{1} \equiv 0$, then we obtain the following corollary:

Corollary 3.7. Let $H_{1}$ a real Hilbert spaces and $C$ be a nonempty, closed and convex subsets of $H_{1}$. let $A: C \longrightarrow H_{1}$ be a continous monotone mapping . Let $S: C \longrightarrow C B(C)$ be L-Lipschitz $\alpha$-hemicontractive multivalued mapping. Assume that $\Theta=F(S) \cap V I(C A)$ is nonempty, closed and convex, $S \alpha p=\alpha$ por all $p \in \Theta$ and for some $\alpha \geq 1$.Let $x_{o}, u \in C$ be arbitrary and let $x_{n}$ be a sequence in $C$ generated by

$$
\begin{align*}
& y_{n}=J_{t} x_{n} \\
& u_{n}=\left(1-\delta_{n}\right) y_{n}+\delta_{n} v_{n}  \tag{3.45}\\
& x_{n+1}=a_{n} u+b_{n}\left[\left(1-\gamma_{n}\right) w_{n}+\gamma_{n} x_{n}\right]+c_{n} y_{n}
\end{align*}
$$

for all $n \geq 0$, where $v_{n} \in S y_{n}$ and $w_{n} \in S u_{n}$ are such that $\left\|v_{n}-w_{n}\right\| \leq 2 D\left(S y_{n}-S u_{n}\right), s, r, t>0$, $a_{n}, \delta_{n} \subset(0,1)$ and $b_{n}, c_{n} \subset[a, b]$ for some $a, b \in(0,1)$ satisfying the following conditions:
i. $a_{n}+b_{n}+c_{n}=1$
ii. $a_{n}+b_{n} \leq \delta_{n} \leq c<\frac{1}{\sqrt{1+4 L^{2}}+1}$

Then, the sequence $\left\{x_{n}\right\}$ converges strongly to $\alpha p \in \Theta$, where $\alpha p=P_{\Theta}(u)$

If, in Corollary 3.6, we assume that $A \equiv 0$, the we obtain the following corollary on split equilibrium problem:

Corollary 3.8. Let $H_{1}$ and $H_{2}$ be two Hilbert spaces and $C, Q$ be two nonempty, closed and convex subsets of $H_{1}$ and $H_{2}$ respectively. Let $F_{1}: C \times C \longrightarrow R$ and $F_{2}: K \times K \longrightarrow R$ be two bifunctions satisfying Assumption G. Let $B: Q \longrightarrow H_{2}$ be a bounded linear operator. . Assume that $\Omega$ is nonempty and $S \alpha p=\alpha p$ for all $p \in \Theta$ and for some $\alpha \geq 1$. Let $x_{o}, u \in C$ be arbitrary and let $x_{n}$ be a sequence in $C$ generated by

$$
\left.\begin{array}{l}
z_{n}=T_{s}^{F_{1}}\left(1-\lambda B^{\star}\left(1-T_{r}^{F_{2}}\right) B\right) x_{n}  \tag{3.46}\\
y_{n}=J_{t} z_{n} \\
x_{n+1}=a_{n} u+b_{n} \gamma_{n} x_{n}+c_{n} y_{n}
\end{array}\right\}
$$

for all $n \geq 0$, where $v_{n} \in S y_{n}$ and $w_{n} \in S u_{n}$ are such that $\left\|v_{n}-w_{n}\right\| \leq 2 D\left(S y_{n}-S u_{n}\right), s, r, t>$ $0, \lambda \in\left(0, \frac{1}{d}\right), d=B B^{\star}$, where $B^{\star}$ is the adjoint of $B, a_{n}, \delta_{n} \subset(0,1)$ and $b_{n}, c_{n} \subset[a, b]$ for some $a, b \in(0,1)$ satisfying the following conditions:
i. $a_{n}+b_{n}+c_{n}=1$
ii. $a_{n}+b_{n} \leq \delta_{n} \leq c<\frac{1}{\sqrt{1+4 L^{2}}+1}$

Then, the sequence $\left\{x_{n}\right\}$ converges strongly to $\alpha p \in \Omega$, where $\alpha p=P_{\Omega}(u)$

We note that, since every $\alpha$-demicontractive mappings are $\alpha$-hemicontractive mappings, the results obtained in this paper for $\alpha$-hemicontractive (single and multivalued) mapping also hold for $\alpha$-demicontractive mappings provided that the indicated conditions are satisfied. Our results extend, improve and unify several recent results in the existing literature (e.g.,[1, 2, 3, 12, 17,18] etc) on approximation of common solution of fixed point problem for nonlinear mappings, classical variational inequality problem and split equilibrium problems. Theorem 3.2 extends the results of Meche and Zegeye [2] from Lipshitz hemicontractive-type mappings to the more general classs of Lipshitz $\alpha$-hemicontractive mappings.

## CONFLICT OF Interests

The author(s) declare that there is no conflict of interests.

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