# NOOR ITERATION FOR FIXED POINT AND VARIATIONAL INCLUSION PROBLEMS 

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#### Abstract

In this article, Noor iteration is considered for finding a common element in the set of fixed points of a non-expansive mapping and in the set of solutions of a variational inclusion problem. Strong convergence theorems are established in the framework of Hilbert spaces.


Keywords: monotone operator; nonexpansive mapping; fixed point; Noor iteration.
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## 1. Introduction-Preliminaries

Variational inclusion problems are being used as mathematical programming models to study a large number of optimization problems arising in finance, economics, network, transportation, and engineering sciences; see [1-21] and the references therein.

Let $H$ be a real Hilbert space $H$ and $A$ a mapping on $H$. Recall that $A$ is said to be monotone if

$$
\langle A x-A y, x-y\rangle \geq 0, \quad \forall x, y \in H
$$

[^0]$A$ is said to be $\alpha$-strongly monotone if there exists a constant $\alpha>0$ such that
$$
\langle A x-A y, x-y\rangle \geq \alpha\|x-y\|^{2}, \quad \forall x, y \in H
$$
$A$ is said to be $\alpha$-strongly anti-monotone if there exists a constant $\alpha>0$ such that
$$
\langle A x-A y, x-y\rangle \leq(-\alpha)\|x-y\|^{2}, \quad \forall x, y \in H
$$
$A$ is said to be $L$-Lipschitz continuous if there exits a constant such that $L>0$ such that
$$
\|A x-A y\| \leq L\|x-y\|, \quad \forall x, y \in H
$$
$A$ is said to be nonexpansive if
$$
\|A x-A y\| \leq\|x-y\|, \quad \forall x, y \in H .
$$
$A$ is said to be strictly pseudocontractive if
$$
\|A x-A y\|^{2} \leq\|x-y\|^{2}+\kappa\|(I-A) x-(I-A) y\|^{2}, \quad \forall x, y \in H .
$$

Let $C$ be a nonempty, closed and convex subset of $H$. Recall that the classical variational inequality problem is to find $u \in C$ such that

$$
\begin{equation*}
\langle A u, v-u\rangle \geq 0, \quad \forall v \in C . \tag{1.1}
\end{equation*}
$$

One can see that the variational inequality problem (1.1) is equivalent to a fixed point problem. $u \in C$ is a solution of the variational inequality (1.1) if and only if $u \in C$ is a fixed point of the mapping $P_{C}(I-\lambda A)$, where $I$ is the identity mapping and $\lambda>0$ is a constant.

Recently, Noor and Huang [15] consider a three-step iterative method for finding a common element in the set of fixed points of a non-expansive mapping and in the set of solutions of the variational inequality problem (1.1) in a real Hilbert space. To be more precise, they introduced the following algorithm:

$$
\left\{\begin{array}{l}
x_{0} \in C \\
z_{n}=\left(1-c_{n}\right) x_{n}+c_{n} S P_{C}\left(x_{n}-\rho T x_{n}\right) \\
y_{n}=\left(1-b_{n}\right) x_{n}+b_{n} S P_{C}\left(y_{n}-\rho T y_{n}\right) \\
x_{n+1}=\left(1-a_{n}\right) x_{n}+a_{n} S P_{C}\left(y_{n}-\rho T y_{n}\right), \quad \forall n \geq 0
\end{array}\right.
$$

where $\left\{a_{n}\right\},\left\{b_{n}\right\}$ and $\left\{c_{n}\right\}$ are sequences in $[0,1]$ for all $n \geq 0, S$ is a non-expansive mapping and $T$ is a monotone-type operator. They showed that the sequence $\left\{x_{n}\right\}$ generated by the above iterative sequence converges strongly to a common element in the set of fixed points of a nonexpansive mapping $S$ and in the set of solutions of the variational inequality problem (1.1); see [15] for details.

In [16], Noor and Huang considered the following variational inclusion problem. Find an $u \in H$ such that

$$
\begin{equation*}
0 \in A u+T u \tag{1.2}
\end{equation*}
$$

where $T$ and $A$ are monotone operators. They also consider the following three-step iterative algorithm:

$$
\left\{\begin{array}{l}
x_{0} \in H \\
z_{n}=\left(1-c_{n}\right) x_{n}+c_{n} S J_{A}\left(x_{n}-\rho T x_{n}\right) \\
y_{n}=\left(1-b_{n}\right) x_{n}+b_{n} S J_{A}\left(y_{n}-\rho T y_{n}\right), \\
x_{n+1}=\left(1-a_{n}\right) x_{n}+a_{n} S J_{A}\left(y_{n}-\rho T y_{n}\right), \quad \forall n \geq 0
\end{array}\right.
$$

where $\left\{a_{n}\right\},\left\{b_{n}\right\}$ and $\left\{c_{n}\right\}$ are sequences in $[0,1]$ for all $n \geq 0, S$ is a non-expansive mapping, $J_{A}=(I+\rho A)^{-1}$. They showed that the sequence $\left\{x_{n}\right\}$ generated by the above iterative sequence converges strongly to a common element in the set of fixed points of a non-expansive mapping $S$ and in the set of solutions of the variational inclusion problem (1.2); see [16] for details.

Motivated by the recent research work, we continue to study the problem of finding a solution of the problem by a Noor iteration.

Lemma 1.1 [22] Suppose that $\left\{\delta_{n}\right\}$ is a nonnegative sequence satisfying the following inequality

$$
\delta_{n+1} \leq\left(1-\lambda_{n}\right) \delta_{n}, \quad \forall n \geq 0
$$

where $\left\{\lambda_{n}\right\}$ is a sequence in $[0,1]$ such that $\sum_{n=0}^{\infty} \lambda_{n}=\infty$. Then $\lim _{n \rightarrow \infty} \delta_{n}=0$.
Lemma 1.2 [21] Let $H$ be a Hilbert space. An element $u \in H$ is a solution of the problem (1.3) if and only if $u \in H$ is a fixed point of the mapping $J_{A}(I+\rho T)$, where $J_{A}=(I+\rho A)^{-1}, I$ is the identity mapping and $T$ is a strongly anti-monotone mapping.

Lemma 1.3. Let $H$ be a Hilbert space and $S: H \rightarrow H$ a nonexpansive mapping with a fixed point. Assume that $F(S) \cap S(A, T) \neq \emptyset$. If $u \in F(S) \cap S(A, T)$, then $u=S J_{A}(I+\rho T) u$.

Proof. Fix $u \in F(S) \cap S(A, T)$. From Lemma 1.2, we see that $u=J_{A}(I+\rho T) u$. We also have $u=S u$. It follows that $u=J_{A}(I+\rho T)=S u=S J_{A}(I+\rho T)$. This completes the proof.

## 2. Main results

Theorem 2.1. Let $H$ be a Hilbert space, A a maximal monotone mapping on $H$ and $T$ an $\alpha$ strongly anti-monotone and $\beta$-Lipschitz continuous mapping on $H$. Let $R: H \rightarrow H$ be a strictly pseudocontractive mapping with a fixed point and let $\left\{x_{n}\right\}$ be a sequence generated by the following manner:

$$
\left\{\begin{array}{l}
x_{0} \in H \\
z_{n}=\left(1-c_{n}\right) x_{n}+c_{n}(\alpha I+(1-\alpha) R) J_{A}\left(x_{n}+\rho T x_{n}\right), \\
y_{n}=\left(1-b_{n}\right) x_{n}+b_{n}(\alpha I+(1-\alpha) R) J_{A}\left(z_{n}+\rho T z_{n}\right), \\
x_{n+1}=\left(1-a_{n}\right) x_{n}+a_{n}(\alpha I+(1-\alpha) R) J_{A}\left(y_{n}+\rho T y_{n}\right), \quad \forall n \geq 0
\end{array}\right.
$$

where $\left\{a_{n}\right\},\left\{b_{n}\right\}$ and $\left\{c_{n}\right\}$ are sequences in $[0,1]$ for all $n \geq 0, J_{A}=(I+\rho A)^{-1}$ and $\rho$ is a constant satisfying the restriction $0<\rho<\frac{2 \alpha}{\beta^{2}}$. Assume that $\kappa \in[\alpha, 1) F(R) \cap S(A, T) \neq \emptyset$ and $\sum_{n=0}^{\infty} a_{n}=\infty$. Then the sequence $\left\{x_{n}\right\}$ converges strongly to a point in $F(R) \cap S(A, T)$.

Proof. Put $S:=\alpha I+(1-\alpha) R$. From Zhou [23], we see that $S$ is nonexpansive with $F(R)=$ $F(S)$. Let $x^{*} \in F(S) \cap S(A, T)$. It follows from (2.1) that

$$
\begin{aligned}
\left\|x_{n+1}-x^{*}\right\| & =\left\|\left(1-a_{n}\right)\left(x_{n}-x^{*}\right)+a_{n}\left(S J_{A}\left(y_{n}+\rho T y_{n}\right)-S J_{A}\left(x^{*}+\rho T x^{*}\right)\right)\right\| \\
& \leq\left(1-a_{n}\right)\left\|x_{n}-x^{*}\right\|+a_{n}\left\|J_{A}\left(y_{n}+\rho T y_{n}\right)-J_{A}\left(x^{*}+\rho T x^{*}\right)\right\| \\
& \leq\left(1-a_{n}\right)\left\|x_{n}-x^{*}\right\|+a_{n}\left\|y_{n}-x^{*}+\rho\left(T y_{n}-T x^{*}\right)\right\| .
\end{aligned}
$$

From the $\alpha$-strongly anti-monotone and $\beta$-Lipschitz assumptions on $T$, we have

$$
\begin{aligned}
& \left\|y_{n}-x^{*}+\rho_{n}\left(T y_{n}-T x^{*}\right)\right\|^{2} \\
& \leq\left\|y_{n}-x^{*}\right\|^{2}-2 \rho \alpha\left\|y_{n}-x^{*}\right\|^{2}+\rho^{2} \beta^{2}\left\|y_{n}-x^{*}\right\|^{2} \\
& =\left(1-2 \rho \alpha+\rho^{2} \beta^{2}\right)\left\|y_{n}-x^{*}\right\|^{2} .
\end{aligned}
$$

That is, $\left\|y_{n}-x^{*}+\rho\left(T y_{n}-T x^{*}\right)\right\| \leq \theta_{n}\left\|y_{n}-x^{*}\right\|$, where $\theta=\sqrt{1-2 \rho \alpha+\rho^{2} \beta^{2}}$. From the assumption $0<\rho<\frac{2 \alpha}{\beta^{2}}$, we see that $\theta<1$.

Next, we estimate $\left\|y_{n}-x^{*}\right\|$. It follows that

$$
\begin{aligned}
\left\|y_{n}-x^{*}\right\| & =\left\|\left(1-b_{n}\right)\left(x_{n}-x^{*}\right)+b_{n}\left(S J_{A}\left(z_{n}+\rho T z_{n}\right)-S J_{A}\left(x^{*}+\rho T x^{*}\right)\right)\right\| \\
& \leq\left(1-b_{n}\right)\left\|x_{n}-x^{*}\right\|+b_{n}\left\|J_{A}\left(z_{n}+\rho T z_{n}\right)-J_{A}\left(x^{*}+\rho T x^{*}\right)\right\| \\
& \leq\left(1-b_{n}\right)\left\|x_{n}-x^{*}\right\|+b_{n}\left\|z_{n}-x^{*}+\rho\left(T z_{n}-T x^{*}\right)\right\| .
\end{aligned}
$$

From the $\alpha$-strongly anti-monotone and $\beta$-Lipschitz assumptions on $T$, we have

$$
\begin{aligned}
& \left\|z_{n}-x^{*}+\rho\left(T z_{n}-T x^{*}\right)\right\|^{2} \\
& \leq\left\|z_{n}-x^{*}\right\|^{2}-2 \rho \alpha\left\|z_{n}-x^{*}\right\|^{2}+\rho^{2} \beta^{2}\left\|z_{n}-x^{*}\right\|^{2} \\
& =\left(1-2 \rho \alpha+\rho^{2} \beta^{2}\right)\left\|z_{n}-x^{*}\right\|^{2}
\end{aligned}
$$

That is, $\left\|z_{n}-x^{*}+\rho\left(T z_{n}-T x^{*}\right)\right\| \leq \theta\left\|z_{n}-x^{*}\right\|$.
Finally, we estimate $\left\|z_{n}-x^{*}\right\|$. It follows that

$$
\begin{aligned}
\left\|z_{n}-x^{*}\right\| & \leq\left(1-c_{n}\right)\left\|x_{n}-x^{*}\right\|+c_{n}\left\|J_{A}\left(x_{n}+\rho T x_{n}\right)-J_{A}\left(x^{*}+\rho T x^{*}\right)\right\| \\
& \leq\left(1-c_{n}\right)\left\|x_{n}-x^{*}\right\|+c_{n}\left\|x_{n}-x^{*}+\rho\left(T x_{n}-T x^{*}\right)\right\|
\end{aligned}
$$

In a similar way, we can obtain that $\left\|x_{n}-x^{*}+\rho\left(T x_{n}-T x^{*}\right)\right\| \leq \theta\left\|x_{n}-x^{*}\right\|$. Notice that $\| z_{n}-$ $x^{*}\left\|\leq\left[1-c_{n}(1-\theta)\right]\right\| x_{n}-x^{*} \|$, It follows that that

$$
\left\|y_{n}-x^{*}\right\| \leq\left(1-b_{n}\left(1-\theta\left(1-c_{n}(1-\theta)\right)\right)\right)\left\|x_{n}-x^{*}\right\| \leq\left\|x_{n}-x^{*}\right\|
$$

It follows that

$$
\begin{aligned}
\left\|x_{n+1}-x^{*}\right\| & \leq\left(1-a_{n}\right)\left\|x_{n}-x^{*}\right\|+a_{n} \theta\left\|y_{n}-x^{*}\right\| \\
& \leq\left[1-a_{n}(1-\theta)\right]\left\|x_{n}-x^{*}\right\| .
\end{aligned}
$$

Applying Lemma 1.1, we can conclude the desired conclusion immediately.

## Conflict of Interests

The author declares that there is no conflict of interests.

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