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A COMMON FIXED POINT THEOREM FOR WEAKLY COMPATIBLE MAPPINGS IN MENGER PM-SPACES

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Abstract. In present paper we prove a unique common fixed point theorem for four weakly compatible self-mappings in Menger-PM spaces without using the notion of continuity.

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1. Introduction

There have been number of generalizations of metric spaces. One such is probabilistic metric spaces (in brief PM-spaces) introduced by K. Menger [3] in 1942. The study of these spaces expanded rapidly with pioneering work of Schweizer and Sklar [5,6]. Further in 1972, Sehgal [7] initiated study of contraction mappings in PM-Spaces. Since then there have been great developments in fixed point theorems with different conditions on mappings or on spaces itself. The notion of weakly commuting maps was initiated by Sessa [8] in metric spaces. Jungck [6] gave the concept of compatible maps and showed that weakly commuting maps are compatible but converse is not true. Jungck [2] further weakened the notion of compatibility and showed that compatible maps are weakly compatible but the

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converse is not true. Mishra [4] introduced the concept of compatible self-maps in Menger spaces and obtained a common fixed point theorem for four self mappings using compatibility and continuity of two functions. Singh and Jain [9] obtained a common fixed point theorem in Menger spaces through weak compatibility and continuity of one function and thus generalized the results of Mishra [4]. In present paper we prove a unique common fixed point theorem for four self-mappings using weak compatibility and without using continuity. Doing so we establish a unique common fixed point theorem with less number of conditions in comparison of Mishra [4]. Later we extend our result to sequence of mappings whereas B. Singh [9] extended the result of Mishra [4] upto six mappings. In paper let R^+ denotes set of all non-negative real numbers.

2. Preliminaries

Definition 2.1. A mapping $F : R \rightarrow R^+$ is called a distribution function if it is non-decreasing and left continuous with $\inf_{t \in R} F(t) = 0$ and $\sup_{t \in R} F(t) = 1$. Let D denotes the set of all distribution functions whereas H stands for specific distribution function (also known as Heaviside function) defined as

$$H(t) = \begin{cases} 0, & t \leq 0; \\ 1, & t > 0. \end{cases}$$

Definition 2.2. A PM-space is an ordered pair (X, F) consisting of non-empty set X and a mapping F from $X \times X$ into D . The value of F at $(x, y) \in X$ is represented by $F_{x,y}$. The functions $F_{x,y}$ are assumed to satisfy the following conditions:

(PM1) $F_{x,y}(t) = 1$ for all $t > 0$ if and only if $x = y$;

(PM2) $F_{x,y}(0) = 0$;

(PM3) $F_{x,y}(t) = F_{y,x}(t)$;

(PM4) if $F_{x,y}(t) = 1$ and $F_{y,z}(s) = 1$, then $F_{x,z}(t+s) = 1$ for all $x, y \in X$ and $t, s \geq 0$.

Every metric (X, d) space can always be realized as a PM-space by considering F from $X \times X$ into D as $F_{u,v}(s) = H(s - d(u, v))$ for all $u, v \in X$.

Definition 2.3. A mapping $\Delta : [0, 1] \times [0, 1] \rightarrow [0, 1]$ is called a triangular norm (briefly t-norm) if the following conditions are satisfied:

- (1) $\Delta(a, 1) = a$ for all $a \in [0, 1]$;
- (2) $\Delta(a, b) = \Delta(b, a)$;
- (3) $\Delta(c, d) \geq \Delta(a, b)$ for $c \geq a, d \geq b$;
- (4) $\Delta(\Delta(a, b), c) = \Delta(a, \Delta(b, c))$ for all $a, b, c, d \in [0, 1]$.

Examples of t-norm are $\Delta(a, b) = \min(a, b)$, $\Delta(a, b) = ab$ and $\Delta(a, b) = \min(a+b-1, 0)$ etc.

Definition 2.4. A Menger space is a triplet (X, F, Δ) , where (X, F) is a PM-space, Δ is t-norm and the following condition hold:

$$(PM5) F_{x,z}(t+s) \geq \Delta(F_{x,y}(t), F_{y,z}(s)) \text{ holds for all } x, y, z \in X \text{ and } t, s \geq 0.$$

Definition 2.5. A sequence $\{p_n\}$ in a Menger space (X, F, Δ) is said to converge to a point p in X if for every $\epsilon > 0$ and $\lambda > 0$, there is an integer $N(\epsilon, \lambda)$ such that $F_{p_n,p}(\epsilon) > 1 - \lambda$, for all $n \geq N(\epsilon, \lambda)$. The sequence is said to be Cauchy sequence if for every $\epsilon > 0$ and $\lambda > 0$, there is an integer $N(\epsilon, \lambda)$ such that $F_{p_n,p_m}(\epsilon) > 1 - \lambda$, for all $n, m \geq N(\epsilon, \lambda)$.

Definition 2.6. Self mappings A and S of a Menger space (X, F, Δ) are said to be compatible if $F_{ASx_n, SAx_n}(\epsilon) \rightarrow 1$ for all $\epsilon > 0$ when $\{x_n\}$ is a sequence in X such that $Ax_n, Sx_n \rightarrow u$ for some $u \in X$ as $n \rightarrow \infty$.

Definition 2.7. Self mappings A and S of a Menger space (X, F, Δ) are said to be weakly compatible if they commute at their coincidence point that is, $Ax = Sx$ for $x \in X$ implies $ASx = SAx$.

Lemma 2.1. [9] Let (X, F, Δ) be a Menger Space. If there exist $h \in (0, 1)$ such that $F_{u,v}(ht) \geq F_{u,v}(t)$ for all $u, v \in X$ then $u = v$.

Let Φ be the class of all real-valued continuous functions $\phi : (R^+)^4 \rightarrow R$, non-decreasing in first argument and satisfying the following conditions:

$$\text{for all } x, y \geq 0, \phi(x, y, x, y) \geq 0 \text{ or } \phi(x, y, y, x) \geq 0 \text{ implies } x \geq y \tag{2.1}$$

$$\phi(x, x, 1, 1) \geq 0 \text{ for all } x \geq 1 \tag{2.2}$$

Example 2.1. Define $\phi : (R^+)^4 \rightarrow R$ as $\phi(x_1, x_2, x_3, x_4) = 2x_1 - \max\{2x_2, x_3/2, x_4/2\}$. Let $x, y \geq 0$ such that $\phi(x, y, x, y) \geq 0$ implies $2x - \max\{2y, x/2, y/2\} \geq 0$ implies $2x -$

$\max\{2y, x/2\} \geq 0$. If $\max\{2y, x/2\} = 2y$, then $2x - 2y \geq 0$ implies $x \geq y$. If $\max\{2y, x/2\} = x/2$ then $2x - x/2 \geq 0$ implies $2x \geq x/2 \geq 2y$ implies $x \geq y$. Similarly $x \geq y$ can be proved when $x, y \geq 0$ such that $\phi(x, y, y, x) \geq 0$. Let $x \geq 1$, then $\phi(x, x, 1, 1) = 2x - \max\{2x, 1/2, 1/2\} = 2x - 2x = 0$. Hence $\phi \in \Phi$.

3. Main results

Theorem 3.1 Let A, B, S and T be self mappings on a complete Menger Space (X, F, Δ) where $\Delta = \min$ and satisfying

$$(3.1) \quad A(X) \subseteq T(X), B(X) \subseteq S(X).$$

$$(3.2) \quad \text{Pairs } (A, S) \text{ and } (B, T) \text{ are weakly compatible.}$$

$$(3.3) \quad \phi(F_{Au, Bv}(ht), F_{Su, Tv}(t), F_{Au, Su}(t), F_{Bv, Tv}(ht)) \geq 0.$$

for all $u, v \in X, t > 0, h \in (0, 1)$. Then A, B, S and T have a unique common fixed point in X .

Proof: Define sequences $\langle x_n \rangle$ and $\langle y_n \rangle$ in X such that $y_{2n+1} = Ax_{2n} = Tx_{2n+1}$ and $y_{2n+2} = Bx_{2n+1} = Sx_{2n+2}$ for $n = 0, 1, 2, \dots$

Putting $u = x_{2n}, v = x_{2n+1}$ in (3.3) we get

$$\phi(F_{Ax_{2n}, Bx_{2n+1}}(ht), F_{Sx_{2n}, Tx_{2n+1}}(t), F_{Ax_{2n}, Sx_{2n}}(t), F_{Bx_{2n+1}, Tx_{2n+1}}(ht)) \geq 0.$$

$$\phi(F_{y_{2n+1}, y_{2n+2}}(ht), F_{y_{2n}, y_{2n+1}}(t), F_{y_{2n+1}, y_{2n}}(t), F_{y_{2n+2}, y_{2n+1}}(ht)) \geq 0.$$

Using (2.1) we get

$$F_{y_{2n+1}, y_{2n+2}}(ht) \geq F_{y_{2n}, y_{2n+1}}(t)$$

$$\text{We can write } F_{y_n, y_{n+1}}(t) \geq F_{y_{n-1}, y_n}\left(\frac{t}{h}\right) \text{ for } n = 2, 3, \dots \quad (3.4)$$

Let ϵ, λ be positive reals. Then for $m > n$ by (PM5) we have

$$\begin{aligned} F_{y_n, y_m}(\epsilon) &\geq \Delta(F_{y_n, y_{n+1}}(\epsilon - h\epsilon), F_{y_{n+1}, y_m}(h\epsilon)) \\ &\geq \Delta(F_{y_1, y_2}\left(\frac{\epsilon - h\epsilon}{h^{n-1}}\right), F_{y_{n+1}, y_m}(h\epsilon)) && \text{by (3.4)} \\ &\geq \Delta(F_{y_1, y_2}\left(\frac{\epsilon - h\epsilon}{h^{n-1}}\right), \Delta(F_{y_{n+1}, y_{n+2}}(h\epsilon - h^2\epsilon), F_{y_{n+2}, y_m}(h^2\epsilon))) \\ &\geq \Delta(F_{y_1, y_2}\left(\frac{\epsilon - h\epsilon}{h^{n-1}}\right), \Delta(F_{y_1, y_2}\left(\frac{h\epsilon - h^2\epsilon}{h^n}\right), F_{y_{n+2}, y_m}(h^2\epsilon))) \\ &\geq \Delta(\Delta(F_{y_1, y_2}\left(\frac{\epsilon - h\epsilon}{h^{n-1}}\right), F_{y_1, y_2}\left(\frac{\epsilon - h\epsilon}{h^{n-1}}\right)), F_{y_{n+2}, y_m}(h^2\epsilon)) \\ &\geq \Delta(F_{y_1, y_2}\left(\frac{\epsilon - h\epsilon}{h^{n-1}}\right), F_{y_{n+2}, y_m}(h^2\epsilon)) \end{aligned}$$

Repeated use of these arguments gives

$$\begin{aligned} &\geq \Delta(F_{y_1,y_2}(\frac{\epsilon-h\epsilon}{h^{n-1}}), F_{y_{m-1},y_m}(h^{m-1-n}\epsilon)) \\ &\geq \Delta(F_{y_1,y_2}(\frac{\epsilon-h\epsilon}{h^{n-1}}), F_{y_1,y_2}(\frac{h^{m-1-n}\epsilon}{h^{m-2}})) \\ &\geq \Delta(F_{y_1,y_2}(\frac{\epsilon-h\epsilon}{h^{n-1}}), F_{y_1,y_2}(\frac{\epsilon-h\epsilon}{h^{n-1}})) \\ &\geq F_{y_1,y_2}(\frac{\epsilon-h\epsilon}{h^{n-1}}) \end{aligned}$$

if N be chosen that $F_{y_1,y_2}(\frac{\epsilon-h\epsilon}{h^{N-1}}) > 1 - \lambda$ it follows that $F_{y_n,y_m}(\epsilon) > 1 - \lambda$ for all $n \geq N$. Hence $\{y_n\}$ is a Cauchy sequence in X which is complete so let $\{y_n\}$ converges to point z in X . Its subsequences $\{Ax_{2n}\}, \{Tx_{2n+1}\}, \{Bx_{2n+1}\}, \{Sx_{2n+2}\}$ also converges to z . Since $B(X) \subseteq S(X)$ there exist a point $p \in X$ such that $z = Sp$. Using (3.3) we have

$$\phi(F_{Ap,Bx_{2n+1}}(ht), F_{Sp,Tx_{2n+1}}(t), F_{Ap,Sp}(t), F_{Bx_{2n+1},Tx_{2n+1}}(ht)) \geq 0.$$

$$\text{Taking } n \rightarrow \infty, \phi(F_{Ap,z}(ht), F_{Sp,z}(t), F_{Ap,Sp}(t), F_{z,z}(ht)) \geq 0.$$

$$\phi(F_{Ap,z}(ht), F_{z,z}(t), F_{Ap,z}(t), F_{z,z}(ht)) \geq 0.$$

$$\phi(F_{Ap,z}(ht), 1, F_{Ap,z}(t), 1) \geq 0.$$

ϕ is non-decreasing in first argument gives $\phi(F_{Ap,z}(t), 1, F_{Ap,z}(t), 1) \geq 0$.

By (2.1), $F_{Ap,z}(t) \geq 1$ which gives $Ap=z$. Therefore $Ap = Sp = z$. Since A and S weakly compatible mappings we have $SAP = ASp$ implies $Az = Sz$. From (3.3) we get

$$\phi(F_{Az,Bx_{2n+1}}(ht), F_{Sz,Tx_{2n+1}}(t), F_{Az,Sz}(t), F_{Bx_{2n+1},Tx_{2n+1}}(ht)) \geq 0.$$

$$\text{Taking } n \rightarrow \infty, \phi(F_{Az,z}(ht), F_{Sz,z}(t), F_{Az,Sz}(t), F_{z,z}(ht)) \geq 0.$$

$$\phi(F_{Az,z}(ht), F_{Az,z}(t), 1, 1) \geq 0.$$

ϕ is non-decreasing in first argument gives $\phi(F_{Az,z}(t), F_{Az,z}(t), 1, 1) \geq 0$.

By (2.2) $F_{Az,z}(t) \geq 1$ implies $Az = z$. Therefore $Az = Sz = z$. As $A(X) \subseteq T(X)$ there exist a point $q \in X$ such that $z = Tq$. By (3.3) we get

$$\phi(F_{Ax_{2n},Bq}(ht), F_{Sx_{2n},Tq}(t), F_{Ax_{2n},Sx_{2n}}(t), F_{Bq,Tq}(ht)) \geq 0.$$

$$\text{Taking } n \rightarrow \infty, \phi(F_{z,Bq}(ht), F_{z,z}(t), F_{z,z}(t), F_{Bq,z}(ht)) \geq 0.$$

$$\phi(F_{z,Bq}(ht), 1, 1, F_{Bq,z}(ht)) \geq 0.$$

By (2.1), $F_{z,Bq}(ht) \geq 1$ implies $z = Bq$. Therefore $z = Bq = Tq$. Similarly as B and T are weakly compatible mappings so $BTq = TBq$ implies $Bz = Tz$. Using (3.3) we get

$$\phi(F_{Ax_{2n},Bz}(ht), F_{Sx_{2n},Tz}(t), F_{Ax_{2n},Sx_{2n}}(t), F_{Bz,Tz}(ht)) \geq 0.$$

$$\text{Taking } n \rightarrow \infty, \phi(F_{z,Bz}(ht), F_{z,Tz}(t), F_{z,z}(t), F_{Bz,Tz}(ht)) \geq 0.$$

$$\phi(F_{z,Bz}(ht), F_{z,Bz}(t), F_{z,z}(t), F_{Bz,Bz}(ht)) \geq 0.$$

$$\phi(F_{z,Bz}(ht), F_{z,Bz}(t), 1, 1) \geq 0.$$

ϕ is non-decreasing in first argument gives $\phi(F_{z,Bz}(t), F_{z,Bz}(t), 1, 1) \geq 0$.

By (2.2), $z = Bz$. Therefore $z = Bz = Tz$. Hence $z = Bz = Tz = Az = Bz$. Therefore mappings A, B, S and T have a common fixed point in X . Let z_1 be another common fixed point of mappings A, B, S and T . Then $z_1 = Bz_1 = Tz_1 = Az_1 = Bz_1$. From (3.3) we get

$$\phi(F_{Az,Bz_1}(ht), F_{Sz,Tz_1}(t), F_{Az,Sz}(t), F_{Bz_1,Tz_1}(ht)) \geq 0.$$

$$\phi(F_{z,z_1}(ht), F_{z,z_1}(t), F_{z,z}(t), F_{z_1,z_1}(ht)) \geq 0.$$

$$\phi(F_{z,z_1}(ht), F_{z,z_1}(t), 1, 1) \geq 0.$$

ϕ is non-decreasing in first argument gives $\phi(F_{z,z_1}(t), F_{z,z_1}(t), 1, 1) \geq 0$.

By (2.2), $F_{z,z_1} \geq 1$ implies $z = z_1$. Hence z is a unique fixed point of mappings A, B, S and T .

Remark 3.1. In Theorem 3.1 we have used less number of conditions in comparison of Mishra [4] in the sense that continuity of functions has not been used. Also one more notable point is that we have used weak compatibility in comparison of compatibility in Mishra [4].

Corollary 3.1. Let A, S and T be self mappings on a complete Menger Space (X, F, Δ) where $\Delta = \min$ and satisfying

$$(3.5) \quad A(X) \subseteq T(X) \cap S(X).$$

(3.6) Pairs (A, S) and (A, T) are weakly compatible.

$$(3.7) \quad \phi(F_{Au,Av}(ht), F_{Su,Tv}(t), F_{Au,Su}(t), F_{Av,Tv}(ht)) \geq 0.$$

for all $u, v \in X, t > 0, h \in (0, 1)$. Then A, S and T have a unique common fixed point in X .

Corollary 3.2. Let A and S be self mappings on a complete Menger Space (X, F, Δ) where $\Delta = \min$ and satisfying

$$(3.8) \quad A(X) \subseteq S(X).$$

(3.9) Pairs (A, S) is weakly compatible.

$$(3.10) \quad \phi(F_{Au,Av}(ht), F_{Su,Sv}(t), F_{Au,Su}(t), F_{Av,Sv}(ht)) \geq 0.$$

for all $u, v \in X, t > 0, h \in (0, 1)$. Then A and S have a unique common fixed point in X .

Corollary 3.3. If in hypotheses of Theorem 3.1, condition (3.3) is replaced by the following condition

$F_{Au, Bv}(ht) \geq \min\{F_{Su, Tv}(t), F_{Au, Su}(t), F_{Bv, Tv}(t)\}$. Then mappings A, B, S and T have a unique common fixed point in X .

Proof: By following the proof of Theorem 3.1 and using Lemma 2.1.

Example 3.1. Let $X = R$ with the metric $d(u, v) = |u - v|$ and define $F_{u,v}(s) = H(s - d(u, v))$ for all $u, v \in X$. clearly (X, F, \min) is a Menger space. Let A, B, S and T be self-mappings from X into itself defined as $T(x) = 2x + 1$ for all $x \in X, S(x) = x$ for all $x \in X, A(x) = B(x) = -1$ for all $x \in X$.

Then we see that

(1) $A(X) \subseteq T(X)$ and $B(X) \subseteq S(X)$.

(2) pairs (A, S) and (B, T) are weakly compatible.

(3) Let $\phi : (R^+)^4 \rightarrow R$ be defined as $\phi(x_1, x_2, x_3, x_4) = x_1 - x_2$. Then $\phi \in \Phi$ and condition (3.3) of Theorem 3.1 is satisfied for $h \in (0, 1)$ and $t > 0$. Thus all conditions of Theorem 3.1 is satisfied and -1 is a unique common fixed point of mappings A, B, S and T .

4. An application

Theorem 4.1 Let (X, F, \min) be complete Menger space. Let A, B, S and T be mappings from $X \times X$ into X such that

(3.11) $A(X \times \{v\}) \subseteq T(X \times \{v\}), B(X \times \{v\}) \subseteq S(X \times \{v\})$ for all $v \in X$.

(3.12) $A(S(u, v), v) = S(A(u, v), v)$ for all $(u, v) \in C[A, S]$ where $C[A, S]$ denotes collection of coincidence points of A and S .

$B(T(u_1, v_1), v_1) = T(B(u_1, v_1), v_1)$ for all $(u_1, v_1) \in C[B, T]$ where $C[B, T]$ denotes collection of coincidence points of B and T .

(3.13) $\phi(F_{A(u,v), B(u_1, v_1)}(ht), F_{S(u,v), T(u_1, v_1)}(t), F_{A(u,v), S(u,v)}(t), F_{B(u_1, v_1), T(u_1, v_1)}(ht)) \geq 0$.

for all $u, v, u_1, v_1 \in X, t > 0, h \in (0, 1)$. Then there exist exactly one point p in X such that $A(p, v) = B(p, v) = S(p, v) = T(p, v) = p$ for all $v \in X$.

Proof: For a fixed $v \in X$ and $v = v_1$, (3.11), (3.12), (3.13) corresponds to (3.1), (3.2), (3.3) of Theorem 3.1 so by Theorem 3.1 for each $v \in X$ there exist unique point $u(v)$ in X such that

$$A(u(v), v) = S(u(v), v) = B(u(v), v) = T(u(v), v) = u(v)$$

Now for every v, v_1 in X from (3.13) we get

$$\phi(F_{A(u(v),v),B(u(v_1),v_1)}(ht), F_{S(u(v),v),T(u(v_1),v_1)}(t),$$

$$F_{A(u(v),v),S(u(v),v)}(t), F_{B(u(v_1),v_1),T(u(v_1),v_1)}(ht)) \geq 0.$$

$$\phi(F_{u(v),u(v_1)}(ht), F_{u(v),u(v_1)}(t), F_{u(v),u(v)}(t), F_{u(v_1),u(v_1)}(ht)) \geq 0.$$

$$\phi(F_{u(v),u(v_1)}(ht), F_{u(v),u(v_1)}(t), 1, 1) \geq 0.$$

ϕ is non-decreasing in first argument gives

$$\phi(F_{u(v),u(v_1)}(t), F_{u(v),u(v_1)}(t), 1, 1) \geq 0.$$

By (2.2) $F_{u(v),u(v_1)}(t) \geq 1$ implies $u(v) = u(v_1)$. Hence $u(\cdot)$ is some point $p \in X$ and so $A(p, v) = B(p, v) = S(p, v) = T(p, v) = p$ for all $v \in X$.

Theorem 4.2 Let S, T and $\{A_i\}_{i \in N}$ be self mappings on a complete Menger Space (X, F, Δ) where $\Delta = \min$ and satisfying

$$(3.14) \quad A_i(X) \subseteq T(X), A_{i+1}(X) \subseteq S(X).$$

$$(3.15) \quad \text{Pairs } (A_i, S) \text{ and } (A_{i+1}, T) \text{ are weakly compatible.}$$

$$(3.16) \quad \phi(F_{A_i u, A_{i+1} v}(ht), F_{S u, T v}(t), F_{A_i u, S u}(t), F_{A_{i+1} v, T v}(ht)) \geq 0.$$

for all $u, v \in X, t > 0, h \in (0, 1)$. Then S, T and $\{A_i\}_{i \in N}$ have a unique common fixed point in X .

Proof: Let $i = 1$, we get hypothesis of Theorem 3.1 for maps A_1, A_2, T and S . By using Theorem 3.1 we get z is a unique common fixed point of maps A_1, A_2, T and S . Now z is a unique common fixed point of T, S, A_1 and T, S, A_2 . Otherwise, if z_1 is a second fixed point of T, S and A_1 then by (3.3) we have

$$\phi(F_{A_1 z_1, A_2 z}(ht), F_{S z_1, T z}(t), F_{A_1 z_1, S z_1}(t), F_{A_2 z, T z}(ht)) \geq 0.$$

$$\phi(F_{z_1, z}(ht), F_{z_1, z}(t), F_{z_1, z_1}(t), F_{z, z}(ht)) \geq 0.$$

$$\phi(F_{z_1, z}(ht), F_{z_1, z}(t), 1, 1) \geq 0.$$

By (2.2) we get $F_{z_1, z} \geq 1$ implies $z_1 = z$.

Similarly we can show z is a unique common fixed point of mappings T, S, A_2 .

Now by putting $i = 2$, we get hypothesis of same theorem for maps T, S, A_2 and A_3 . Consequently there exist a unique common fixed point for maps T, S, A_2 and A_3 . Let this point be z_2 . Similarly z_2 is a unique common fixed point of T, S, A_2 and T, S, A_3 . Thus $z = z_2$. Hence we get z is a unique common fixed point for maps T, S, A_1, A_2 and A_3 . Continuing in this way we see that z is a unique common fixed point for S, T and $\{A_i\}_{i \in N}$.

Remark 4.1. B. Singh [9] generalized the result of Mishra [4] to six mappings by using weak compatibility and continuity of one function and we have extended our result to sequence of mappings without using continuity of any function.

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