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Adv. Fixed Point Theory, 7 (2017), No. 4, 572-579

ISSN: 1927-6303

COMMON FIXED POINT THEOREM IN COMPLEX VALUED METRIC SPACES

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Abstract. In this paper, we prove a common fixed point theorem in complex valued metric spaces satisfying rational inequality using compatible and weakly compatible mappings. Our result generalizes the recent result of Nashine et al. [6] and Azam et al. [2].

Keywords. common fixed point; weakly compatible mapping; continuity; complex valued metric spaces.

2010 AMS Subject Classification: 54H25, 47H10.

1. Introduction.

Jungck[3] proved a common fixed point theorem for commuting maps generalizing the Banach's fixed point theorem. Sessa[9] defined weak commutativity and proved common fixed point theorem for weakly commuting mappings.

Further, Jungck[4] introduced the notion of compatibility, which is more general than that of weak commutativity, then various fixed point theorems for compatible mappings satisfying contractive type conditions and assuming continuity of at least one of the mappings, have been obtained by many authors. In 1998, Jungck and Rhoades[5] introduced the notion of weak compatibility and showed that compatible maps are weakly compatible but the converse need not to be true. In 2011, Azam et al.[2], introduced the notion of complex valued metric spaces and established some fixed point results for a pair of mappings for contraction condition satisfying a

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Received October 16, 2016

rational expression. Though complex valued metric spaces form a special class of cone metric space, yet this idea is intended to define rational expressions which are not meaningful in cone metric spaces and thus many results of analysis cannot be generalized to cone metric spaces. Indeed the definition of a cone metric space banks on the underlying Banach space which is not a division Ring. However, in complex valued metric spaces, one can study improvements of a host of result of analysis involving division. One can refer related results in [8,10]. Recently Ahmad et al. [1] prove some common fixed results for the mappings satisfying rational expressions on a closed ball in complex valued metric spaces and Rafiq et al.[7] prove some common fixed point theorems of weakly compatible mappings in complex valued metric spaces.

The aim of paper is to prove a common fixed point theorem using compatible and weakly compatible mappings and continuity in complex valued metric spaces.

2. Basic definitions and preliminaries.

We recall some notations and definitions that will be utilize in our subsequent discussion.

The following definition is recently introduced by Azam et al. [2].

Let \mathbb{C} be the set of complex numbers and $z_1, z_2 \in \mathbb{C}$. Define a partial order \preceq on \mathbb{C} as follows:

$z_1 \preceq z_2$ if and only if $\text{Re}(z_1) \leq \text{Re}(z_2)$, $\text{Im}(z_1) \leq \text{Im}(z_2)$.

Consequently, one can infer that $z_1 \preceq z_2$ if one of the following conditions is satisfied:

- (i) $\text{Re}(z_1) = \text{Re}(z_2)$, $\text{Im}(z_1) < \text{Im}(z_2)$,
- (ii) $\text{Re}(z_1) < \text{Re}(z_2)$, $\text{Im}(z_1) = \text{Im}(z_2)$,
- (iii) $\text{Re}(z_1) < \text{Re}(z_2)$, $\text{Im}(z_1) < \text{Im}(z_2)$,
- (iv) $\text{Re}(z_1) = \text{Re}(z_2)$, $\text{Im}(z_1) = \text{Im}(z_2)$.

In particular, we write $z_1 \prec z_2$ if $z_1 \neq z_2$ and one of (i), (ii), and (iii) is satisfied and we write $z_1 < z_2$ if only (iii) is satisfied. Notice that $0 \preceq z_1 \preceq z_2 \Rightarrow |z_1| < |z_2|$, and

$z_1 \preceq z_2, z_2 \prec z_3 \Rightarrow z_1 < z_3$.

Definition 2.1[2]. Let X be a nonempty set, whereas \mathbb{C} be the set of complex numbers. Suppose that the mapping $d : X \times X \rightarrow \mathbb{C}$, satisfies the following conditions:

- (d₁) $0 \preceq d(x,y)$ for all $x,y \in X$ and $d(x,y) = 0$ if and only if $x = y$;
- (d₂) $d(x,y) = d(y,x)$ for all $x, y \in X$;
- (d₃) $d(x,y) \preceq d(x,z) + d(z,y)$ for all $x, y, z \in X$.

Then d is called a complex valued metric on X , and (X,d) is called a complex valued metric space.

Definition 2.2[2]. Let (X, d) be a complex valued metric space and $B \subseteq X$.

- (i) $b \in B$ is called an interior point of a set B whenever there is $0 < r \in \mathbb{C}$ such that $N(b, r) \subseteq B$, where $N(b, r) = \{y \in X: d(b, y) < r\}$.
- (ii) A point $x \in X$ is called a limit point of B whenever for every $0 < r \in \mathbb{C}$, $N(x, r) \cap (B \setminus \{x\}) \neq \phi$.
- (iii) A subset $A \subseteq X$ is called open whenever each element of A is an interior point of A whereas a subset $B \subseteq X$ is called closed whenever each limit point of B belongs to B .

The family

$$F = \{N(x, r) : x \in X, 0 < r\}$$

is a sub-basis for a topology on X . We denote this complex topology by τ_c . Indeed, the topology τ_c is Hausdorff.

Definition 2.3[2]. Let (X, d) be a complex valued metric space and $\{x_n\}_{n \geq 1}$ be a sequence in X and $x \in X$. We say that

- (i) the sequence $\{x_n\}_{n \geq 1}$ converges to x if for every $c \in \mathbb{C}$ with $0 < c$ there is $n_0 \in \mathbb{N}$ such that for all $n > n_0$, $d(x_n, x) < c$. We denote this by $\lim_n x_n$ or $x_n \rightarrow x$, as $n \rightarrow \infty$,
- (ii) the sequence $\{x_n\}_{n \geq 1}$ is Cauchy sequence if for every $c \in \mathbb{C}$ with $0 < c$ there is $n_0 \in \mathbb{N}$ such that for all $n > n_0$, $d(x_n, x_{n+m}) < c$,
- (iii) the metric space (X, d) is a complete complex valued metric space if every Cauchy sequence is convergent.

Definition 2.4. If f and g are mappings from a metric space (X, d) into itself, are called commuting on X , if $d(fgx, gfx) = 0$ for all $x \in X$.

Definition 2.5[9]. If f and g are mappings from a metric space (X, d) into itself, are called weakly commuting on X , if $d(fgx, gfx) \leq d(fx, gx)$ for all $x \in X$.

Definition 2.6[4]. If f and g are mappings from a metric space (X, d) into itself, are called compatible on X , if $\lim_{n \rightarrow \infty} d(fgx_n, gfx_n) = 0$, whenever $\{x_n\}$ is a sequence in X such that

$$\lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} gx_n = x, \text{ for some point } x \in X.$$

Definition 2.6[5]. Let f and g be two self-maps defined on a set X , then f and g are said to be weakly compatible if they commute at coincidence point.

Lemma 2.1 [2]. Let (X, d) be a complex valued metric space and $\{x_n\}$ be a sequence in X . Then $\{x_n\}$ converges to x if and only if $|d(x_n, x)| \rightarrow 0$ as $n \rightarrow \infty$.

Lemma 2.2 [2]. Let (X, d) be a complex valued metric space and $\{x_n\}$ be a sequence in X . Then $\{x_n\}$ is a Cauchy sequence if and only if $|d(x_n, x_{n+m})| \rightarrow 0$ as $n, m \rightarrow \infty$.

Lemma 2.3 [4]. Let f and g be compatible mappings from a metric space (X, d) into itself. Suppose that $\lim_{n \rightarrow \infty} f x_n = \lim_{n \rightarrow \infty} g x_n = x$ for some $x \in X$.

Then $\lim_{n \rightarrow \infty} g f x_n = f x$, if f is continuous.

3. Main Results.

Our result generalizes the recent result of Nashine et al. [6] and Azam et al. [2].

Theorem 3.1. Let (X, d) be a complete complex valued metric space and mappings f, g, S and $T: X \rightarrow X$ satisfying

$$(3.1.1) \quad S \subset g, \quad T \subset f;$$

$$(3.1.2) \quad \text{and} \quad d(Sx, Ty) \lesssim \alpha d(fx, gy) + \beta \left\{ \frac{d(fx, Sx) d(gy, Ty)}{d(fx, Ty) + d(gy, Sx) + d(fx, gy)} \right\}$$

for all x, y in X such that $x \neq y$, $d(fx, Ty) + d(gy, Sx) + d(fx, gy) \neq 0$ where α, β are nonnegative reals with $\alpha + \beta < 1$.

(3.1.3) Suppose that one of S or f is continuous, pair (S, f) is compatible and (T, g) is weak compatible,

(3.1.4) or one of T or g is continuous, pair (S, f) is weak compatible and (T, g) is compatible.

Then f, g, S and T have a unique common fixed point in X .

Proof. Suppose x_0 be an arbitrary point in X . We define a sequence $\{y_{2n}\}$ in X such that

$$\begin{aligned} y_{2n} &= Sx_{2n} = gx_{2n+1} \\ y_{2n+1} &= Tx_{2n+1} = fx_{2n+2} \quad ; n=0,1,2,\dots \end{aligned}$$

Then,

$$\begin{aligned} d(y_{2n}, y_{2n+1}) &= d(Sx_{2n}, Tx_{2n+1}) \\ &\lesssim \alpha d(fx_{2n}, gx_{2n+1}) + \beta \left\{ \frac{d(fx_{2n}, Sx_{2n}) d(gx_{2n+1}, Tx_{2n+1})}{d(fx_{2n}, Tx_{2n+1}) + d(gx_{2n+1}, Sx_{2n}) + d(fx_{2n}, gx_{2n+1})} \right\} \\ &\lesssim \alpha d(y_{2n-1}, y_{2n}) + \beta \left\{ \frac{d(y_{2n-1}, y_{2n}) d(y_{2n}, y_{2n+1})}{d(y_{2n-1}, y_{2n+1}) + d(y_{2n}, y_{2n}) + d(y_{2n-1}, y_{2n})} \right\} \\ &\lesssim \alpha d(y_{2n-1}, y_{2n}) + \beta \left\{ \frac{d(y_{2n-1}, y_{2n}) d(y_{2n}, y_{2n+1})}{d(y_{2n}, y_{2n+1})} \right\} \\ &\lesssim \alpha d(y_{2n-1}, y_{2n}) + \beta d(y_{2n-1}, y_{2n}) \end{aligned}$$

$$d(y_{2n}, y_{2n+1}) \lesssim (\alpha + \beta) d(y_{2n-1}, y_{2n})$$

similarly, we can show that

$$d(y_{2n+1}, y_{2n+2}) \lesssim (\alpha + \beta) d(y_{2n}, y_{2n+1}).$$

If $(\alpha + \beta) = \delta < 1$, then

$$|d(y_{2n+1}, y_{2n+2})| \lesssim \delta |d(y_{2n}, y_{2n+1})| \lesssim \dots \lesssim \delta^{2n+1} |d(y_0, y_1)|$$

so that for any $m > n$,

$$\begin{aligned} |d(y_{2n}, y_{2m})| &\lesssim |d(y_{2n}, y_{2n+1}) + d(y_{2n+1}, y_{2n+2}) + \dots + d(y_{2m-1}, y_{2m})| \\ &\lesssim (\delta^{2n} + \delta^{2n+1} + \dots + \delta^{2m-1}) |d(y_0, y_1)| \\ &\lesssim \frac{\delta^{2n}}{1-\delta} |d(y_0, y_1)| \rightarrow 0 \text{ as } m, n \rightarrow \infty. \end{aligned}$$

Hence $\{y_{2n}\}$ is a cauchy sequence and since X is complete, sequence $\{y_{2n}\}$ converges to point t in X and its subsequences $Sx_{2n}, Tx_{2n+1}, fx_{2n+2}$, and gx_{2n+1} of sequence $\{y_{2n}\}$ also converges to point t .

Let f is continuous and since S and f are compatible on X . Then by lemma (2.3), we have f^2x_{2n} and $Sfx_{2n} \rightarrow ft$ as $n \rightarrow \infty$.

Consider

$$d(Sfx_{2n}, Tx_{2n+1}) \lesssim \alpha d(f^2x_{2n}, gx_{2n+1}) + \beta \left\{ \frac{d(f^2x_{2n}, Sfx_{2n}) d(gx_{2n+1}, Tx_{2n+1})}{d(f^2x_{2n}, Tx_{2n+1}) + d(gx_{2n+1}, Sfx_{2n}) + d(f^2x_{2n}, gx_{2n+1})} \right\}.$$

Letting $n \rightarrow \infty$, we get

$$d(ft, t) \lesssim \alpha d(ft, t) + \beta \left\{ \frac{d(ft, ft) d(t, t)}{d(ft, t) + d(t, ft) + d(ft, t)} \right\}$$

$$(1-\alpha)d(ft, t) \lesssim 0 \text{ so that } ft = t.$$

Again consider

$$d(St, Tx_{2n+1}) \lesssim \alpha d(ft, gx_{2n+1}) + \beta \left\{ \frac{d(ft, St) d(gx_{2n+1}, Tx_{2n+1})}{d(ft, Tx_{2n+1}) + d(gx_{2n+1}, St) + d(ft, gx_{2n+1})} \right\}.$$

Letting $n \rightarrow \infty$, we get

$$d(St, t) \lesssim \alpha d(t, t) + \beta \left\{ \frac{d(t, St) d(t, t)}{d(t, t) + d(t, t) + d(t, t)} \right\}$$

$$d(St, t) \lesssim 0 \text{ so that } St = t.$$

Now since $S \subset g$ and there exists another point u in X , such that $t = St = gu$.

Consider

$$d(t, Tu) = d(St, Tu)$$

$$d(t, Tu) \lesssim \alpha d(ft, gu) + \beta \left\{ \frac{d(ft, St) d(gu, Tu)}{d(ft, Tu) + d(gu, St) + d(ft, gu)} \right\}$$

$$d(t, Tu) \lesssim \alpha d(t, t) + \beta \left\{ \frac{d(t, t) d(t, Tu)}{d(t, Tu) + d(t, t) + d(t, t)} \right\}$$

$d(t, Tu) \lesssim 0$ so that $Tu = t$.

Since T and g are weak compatible on X and $Tu = gu$ and $Tgu = gTu$.

Consider

$$d(t, gt) = d(St, Tt)$$

$$d(t, gt) \lesssim \alpha d(ft, gt) + \beta \left\{ \frac{d(ft, St)d(gt, Tt)}{d(ft, Tt) + d(gt, St) + d(ft, gt)} \right\}$$

$$d(t, gt) \lesssim \alpha d(t, gt) + \beta \left\{ \frac{d(t, t)d(gt, Tt)}{d(t, Tt) + d(gt, t) + d(t, gt)} \right\}$$

$(1 - \alpha) d(t, gt) \lesssim 0$ so that $gt = t$.

Hence $ft = gt = St = Tt = t$.

Thus t is a common fixed point of f, g, S and T .

Similarly, we can show that t is a common fixed point of f, g, S and T , when S is continuous.

For the 'or' part, let T is continuous and since T and g are compatible on X . Then by lemma (2.3) we have

$$T^2 x_{2n} \text{ and } gTx_{2n} = Tt \text{ as } n \rightarrow \infty.$$

Consider

$$d(Sx_{2n}, T^2x_{2n}) \lesssim \alpha d(fx_{2n}, gTx_{2n}) + \beta \left\{ \frac{d(fx_{2n}, Sx_{2n})d(gTx_{2n}, T^2x_{2n})}{d(fx_{2n}, T^2x_{2n}) + d(gTx_{2n}, Sx_{2n}) + d(fx_{2n}, gTx_{2n})} \right\}.$$

Letting $n \rightarrow \infty$, we get

$$d(t, Tt) \lesssim \alpha d(t, Tt) + \beta \left\{ \frac{d(t, t)d(Tt, Tt)}{d(t, Tt) + d(Tt, t) + d(t, Tt)} \right\}$$

$(1 - \alpha) d(t, Tt) \lesssim 0$ so that $Tt = t$.

Now since $T \subset f$, there exists a point v in X , such that $t = Tt = fv$.

Consider

$$d(Sv, T^2x_{2n}) \lesssim \alpha d(fv, gTx_{2n}) + \beta \left\{ \frac{d(fv, Sv)d(gTx_{2n}, T^2x_{2n})}{d(fv, T^2x_{2n}) + d(gTx_{2n}, Sv) + d(fv, gTx_{2n})} \right\}.$$

Letting $n \rightarrow \infty$, we get

$$d(Sv, Tt) \lesssim \alpha d(t, Tt) + \beta \left\{ \frac{d(t, Sv)d(Tt, Tt)}{d(t, Tt) + d(Tt, Sv) + d(t, Tt)} \right\}$$

$$d(Sv, t) \lesssim \alpha d(t, t)$$

$d(Sv, t) \lesssim 0$ so that $Sv = t$.

Since S and f are weakly compatible on X and $Sv = fv$ and $Sfv = fSv$

impiles that $St = Sfv = fSv = ft$.

Now consider

$$d(St, Tx_{2n+1}) \lesssim \alpha d(ft, gx_{2n+1}) + \beta \left\{ \frac{d(ft, St)d(gx_{2n+1}, Tx_{2n+1})}{d(ft, Tx_{2n+1})+d(gx_{2n+1}, St)+d(ft, gx_{2n+1})} \right\}.$$

Letting $n \rightarrow \infty$, we get

$$d(St, t) \lesssim \alpha d(St, t) + \beta \left\{ \frac{d(St, St)d(t, t)}{d(St, t)+d(t, St)+d(St, t)} \right\}$$

$$(1 - \alpha) d(St, t) \lesssim 0 \text{ so that } St = t.$$

Now since $S \subset g$, there exists a point w in X , such that $t = St = gw$.

Now

$$\begin{aligned} d(t, Tw) &= d(St, Tw) \\ &\lesssim \alpha d(ft, gw) + \beta \left\{ \frac{d(ft, St)d(gw, Tw)}{d(ft, Tw)+d(gw, St)+d(ft, gw)} \right\} \\ &\lesssim \alpha d(t, t) + \beta \left\{ \frac{d(t, t)d(t, Tw)}{d(t, Tw)+d(t, t)+d(t, t)} \right\} \end{aligned}$$

$$d(t, Tw) \lesssim 0 \text{ so that } t = Tw.$$

Since T and g are compatible on X and $Tw = gw = t$ and $d(gTw, Tgw) = 0$

implies that $gt = gTw = Tgw = Tt$.

Hence $St = Tt = ft = gt = t$.

Therefore, t is common fixed point of f, g, S and T .

Similarly, we can show that t is also common fixed point of f, g, S and T , when g is continuous.

Now, we prove the uniqueness of t .

Suppose that $w \neq t$ be another common fixed point of f, g, S and T .

Then

$$\begin{aligned} d(t, w) &= d(St, Tw) \\ d(t, w) &\lesssim \alpha d(ft, gw) + \beta \left\{ \frac{d(ft, St)d(gw, Tw)}{d(ft, Tw)+d(gw, St)+d(ft, gw)} \right\} \\ &\lesssim \alpha d(t, w) + \beta \left\{ \frac{d(t, t)d(w, w)}{d(t, w)+d(w, t)+d(t, w)} \right\} \end{aligned}$$

$$d(t, w) \lesssim \alpha d(t, w)$$

$(1 - \alpha)d(t, w) \lesssim 0$, which is a contradiction. Hence $t = w$.

Therefore, t is unique common fixed point of f, g, S and T .

By setting $f = g = I$ we get the following corollary:

Corollary 3.2. Let (X, d) be a complete complex valued metric space and mappings $S, T: X \rightarrow X$ satisfy:

$$(3.2.1) \quad S \subset T$$

$$(3.2.2) \text{ and } d(Sx, Ty) \lesssim \alpha d(x, y) + \beta \left\{ \frac{d(x, Sx) d(y, Ty)}{d(x, Ty) + d(y, Sx) + d(x, y)} \right\}$$

for all x, y in X such that $x \neq y$, $d(x, Ty) + d(y, Sx) + d(x, y) \neq 0$. where α, β are nonnegative reals with $\alpha + \beta < 1$. If pair (S, T) is weakly compatible. Then S and T have unique common fixed point in X .

Conflict of Interests

The authors declare that there is no conflict of interests.

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