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## SOME FIXED POINTS RESULTS USING $(\psi, \varphi)$ GENERALIZED WEAKLY CONTRACTIVE MAP ON A GENERALIZED 2-METRIC SPACE

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**Abstract.** The main purpose of this paper is to define a generalized 2-metric and prove the existence and uniqueness of fixed points for  $(\psi, \varphi)$  generalized weakly contractive mappings in a generalized 2-metric space.

**Keywords:** fixed points; weak contraction; sub-linear.

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### 1. INTRODUCTION

The study of fixed point theorems for self maps satisfying different contraction conditions is the center of rigorous research activities. Dutta et al. introduced  $(\psi, \varphi)$ -weakly contractive maps in 2008 and obtained some fixed point results for such contractions, [4]. Later, G. V. R. Babu et al. introduced  $(\psi, \varphi)$ -almost weakly contractive maps in  $G$ -metric space, [1]. Fixed points of contractive maps on  $S$ -metric spaces were studied by several authors and since then, several contractions have been considered for proving fixed point theorems, [6, 2, 3, 10]. The authors D. Venkatesh et al. further proved some fixed point outcomes in  $S_b$ -metric spaces using  $(\psi, \varphi)$ -generalized weakly contractive maps in  $S_b$ -metric spaces, [7].

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The concept of an area of a triangle in  $\mathbb{R}^2$  inspired, Gähler to introduced the concept of a 2-metric, as a generalization of the metric, [5].

**Definition 1.1.** [5] *Let  $X$  be a non-empty set and  $d : X \times X \times X \rightarrow [0, \infty)$  be a map satisfying the following properties*

(i) *If  $x, y, z \in X$  then  $d(x, y, z) = 0$  only if at least two of the three points are the same.*

(ii) *For  $x, y \in X$  such that  $x \neq y$  there exists a point  $z \in X$  such that  $d(x, y, z) \neq 0$ .*

(iii) *symmetry property: for  $x, y, z \in X$ ,*

$$d(x, y, z) = d(x, z, y) = d(y, x, z) = d(y, z, x) = d(z, x, y) = d(z, y, x).$$

(iv) *rectangle inequality:*

$$d(x, y, z) \leq d(x, y, t) + d(y, z, t) + d(z, x, t)$$

*for  $x, y, z, t \in X$ .*

*Then  $d$  is a 2-metric and  $(X, d)$  is a 2-metric space.*

**Definition 1.2.** *Let  $X$  be a non-empty set and  $d : X \times X \times X \rightarrow [0, \infty)$  be a map satisfying the following properties:*

(i) *If  $x, y, z \in X$  then  $d(x, y, z) = 0$  only if at least two of the three points are the same.*

(ii) *For  $x, y \in X$  such that  $x \neq y$  there exists a point  $z \in X$  such that  $d(x, y, z) \neq 0$ .*

(iii) *symmetry property: for  $x, y, z \in X$ ,*

$$d(x, y, z) = d(x, z, y) = d(y, x, z) = d(y, z, x) = d(z, x, y) = d(z, y, x).$$

(iv) *modified rectangle inequality: there exists  $\alpha, \beta, \gamma \geq 1$  such that*

$$d(x, y, z) \leq \alpha d(x, y, t) + \beta d(y, z, t) + \gamma d(z, x, t)$$

*for  $x, y, z, t \in X$ .*

*Then  $d$  is a generalized 2-metric and  $(X, d)$  is a generalized 2- metric space.*

*If  $\alpha = \beta = \gamma = 1$  then a generalized 2-metric is a 2-metric.*

**Definition 1.3.** Let  $(X, d)$  be a generalized 2-metric space. Let  $x, y \in X$  and  $\varepsilon > 0$ . Then the subset

$$B_\varepsilon(x, y) = \{z \in X; d(x, y, z) < \varepsilon\}$$

of  $X$  is called a generalized 2-ball centered at  $x, y$  with radius  $\varepsilon$ . A topology can be generated in  $X$  by taking the collection of all generalized 2-balls as a subbasis, which we call the generalized 2-metric topology and is denoted by  $\tau$ . Thus  $(X, \tau)$  is a generalized 2-metric topological space. Members of  $\tau$  are called 2-open sets. From the property of the metric it can easily be seen that  $B_\varepsilon(x, y) = B_\varepsilon(y, x)$  for  $\varepsilon > 0$ .

**Example 1.4.** Let  $X = [0, 1]$  and define

$$(1) \quad d(x, y, z) = \begin{cases} 0 & , \text{ only if at least two of the three points are the same} \\ e^{|x-y|+|y-z|+|z-x|} & , \text{ otherwise} \end{cases}$$

For  $x, y, z \in X$  and using Jensen's inequality, we get

$$\begin{aligned} d(x, y, z) &= e^{|x-y|+|y-z|+|z-x|} \\ &= e^{\frac{1}{2}|x-y|+\frac{1}{3}|y-z|+\frac{1}{6}|z-x|} e^{\frac{1}{2}|x-y|+\frac{2}{3}|y-z|+\frac{5}{6}|z-x|} \\ &\leq e^2 e^{\frac{1}{2}|x-y|+\frac{1}{3}|y-z|+\frac{1}{6}|z-x|} \\ &\leq e^2 \left\{ \frac{1}{2} e^{|x-y|} + \frac{1}{3} e^{|y-z|} + \frac{1}{6} e^{|z-x|} \right\} \\ &\leq e^2 \left\{ \frac{1}{2} e^{|x-y|+|y-t|+|t-x|} + \frac{1}{3} e^{|z-y|+|y-t|+|t-z|} + \frac{1}{6} e^{|z-x|+|x-t|+|t-z|} \right\} \\ &= \alpha d(x, y, t) + \beta d(z, y, t) + \gamma d(z, x, t) \end{aligned}$$

where  $\alpha = \frac{1}{2}e^2 \geq 1$ ,  $\beta = \frac{1}{3}e^2 \geq 1$  and  $\gamma = \frac{1}{6}e^2 \geq 1$ . It follows that  $d$  is a generalized 2-metric.

**Definition 1.5.** Let  $\{x_n\}_{n \in \mathbb{N}}$  be a sequence in a generalized 2-metric space  $(X, d)$ .

a) the sequence  $\{x_n\}_{n \in \mathbb{N}}$  is convergent to  $x \in X$  iff for all  $\xi \in X$ ,

$$\lim_{n \rightarrow \infty} d(x_n, x, \xi) = 0.$$

b) the sequence  $\{x_n\}_{n \in \mathbb{N}}$  is a Cauchy sequence in  $X$  iff for all  $\xi \in X$ ,

$$\lim_{n,m \rightarrow \infty} d(x_n, x_m, \xi) = 0.$$

## 2. MAIN RESULT

**Definition 2.1.** [8] A function  $\psi : [0, \infty) \rightarrow [0, \infty)$  is an altering distance function if it satisfies:

(i)  $\psi$  is continuous and non-decreasing.

(ii)  $\psi(t) = 0 \iff t = 0$ .

To this prove uniqueness and existence of a fixed point the definition was amended to include:

(iii)  $\psi$  is sublinear function.

Denote the class of all altering distances functions by  $\Psi$ .

**Definition 2.2.** Let  $(X, d)$  be a generalized 2–metric space and  $T : X \rightarrow X$  is a contraction if there exists  $0 \leq \lambda < 1$  such that

$$d(Tx, Ty, \xi) \leq \lambda d(x, y, \xi)$$

for all  $x, y, \xi \in X$ .

In [9], authors have proved a similar result in a  $b_2$  metric space with the additional property that the set is partially ordered.

**Definition 2.3.** Let  $(X, d)$  be a generalized 2–metric space and a mapping  $T : X \rightarrow X$  is a  $(\psi, \varphi)$  generalized almost weakly contraction if it satisfies the inequality

$$\begin{aligned} & \beta \psi(d(Tx, Ty, \xi)) \\ & \leq \psi \left( \max \left\{ d(x, y, \xi), \frac{d(x, Tx, \xi)d(y, Ty, \xi)}{1+d(x, y, \xi)}, \frac{d(x, Tx, \xi)d(y, Ty, \xi)}{1+d(Tx, Ty, \xi)} \right\} \right) \\ & - \varphi \left( \max \left\{ d(x, y, \xi), \frac{d(x, Tx, \xi)d(y, Ty, \xi)}{1+d(x, y, \xi)}, \frac{d(x, Tx, \xi)d(y, Ty, \xi)}{1+d(Tx, Ty, \xi)} \right\} \right) \\ (2) \quad & + \mu \min \{d(x, Tx, \xi), d(x, Ty, \xi), d(y, Tx, \xi), d(y, Ty, \xi)\} \end{aligned}$$

where  $x, y, z \in X$ ,  $\mu \geq 0$  and  $\psi, \varphi \in \Psi$ .

**Theorem 2.4.** Let  $(X, d)$  be a generalized complete 2–metric space and  $T : X \rightarrow X$  be a  $(\psi, \varphi)$  generalized almost weakly contractive mapping. Then  $T$  has a unique fixed point.

*Proof.* Let  $x_0 \in X$  and define a sequence  $\{x_n\}_{n \in \mathbb{N}}$  in  $X$  by

$$x_n = Tx_{n-1},$$

for all  $n \in \mathbb{N}$ . If  $x_n = x_{n+1}$  for some  $n \in \mathbb{N}$  then we have a fixed point. We assume that  $x_n \neq x_{n+1}$  and we shall show that the sequence  $\{d(x_n, x_{n+1}, \xi)\}_{n \in \mathbb{N}}$  is a decreasing sequence of real numbers. By (2), we get

$$\begin{aligned} & \psi(d(x_n, x_{n+1}, \xi)) \\ &= \psi(d(Tx_{n-1}, Tx_n, \xi)) \\ &\leq \frac{1}{\beta} \left[ \psi \left( \max \left\{ d(x_{n-1}, x_n, \xi), \frac{d(x_{n-1}, Tx_{n-1}, \xi)d(x_n, Tx_n, \xi)}{1+d(Tx_{n-1}, Tx_n, \xi)}, \frac{d(x_{n-1}, Tx_{n-1}, \xi)d(x_n, Tx_n, \xi)}{1+d(x_{n-1}, x_n, \xi)} \right\} \right) \right. \\ &\quad \left. - \varphi \left( \max \left\{ d(x_{n-1}, x_n, \xi), \frac{d(x_{n-1}, Tx_{n-1}, \xi)d(x_n, Tx_n, \xi)}{1+d(Tx_{n-1}, Tx_n, \xi)}, \frac{d(x_{n-1}, Tx_{n-1}, \xi)d(x_n, Tx_n, \xi)}{1+d(x_{n-1}, x_n, \xi)} \right\} \right) \right] \\ (3) \quad & + \mu \min \{d(x_{n-1}, Tx_n, \xi), d(x_n, Tx_n, \xi), d(x_{n-1}, Tx_{n-1}, \xi), d(x_n, Tx_{n-1}, \xi)\} \end{aligned}$$

since  $\frac{1}{\beta} < 1$ , we get

$$\begin{aligned} & \psi(d(x_n, x_{n+1}, \xi)) \\ &= \psi(d(Tx_{n-1}, Tx_n, \xi)) \\ &\leq \psi \left( \max \left\{ d(x_{n-1}, x_n, \xi), \frac{d(x_{n-1}, Tx_{n-1}, \xi)d(x_n, Tx_n, \xi)}{1+d(Tx_{n-1}, Tx_n, \xi)}, \frac{d(x_{n-1}, Tx_{n-1}, \xi)d(x_n, Tx_n, \xi)}{1+d(x_{n-1}, x_n, \xi)} \right\} \right) \\ &\quad - \varphi \left( \max \left\{ d(x_{n-1}, x_n, \xi), \frac{d(x_{n-1}, Tx_{n-1}, \xi)d(x_n, Tx_n, \xi)}{1+d(Tx_{n-1}, Tx_n, \xi)}, \frac{d(x_{n-1}, Tx_{n-1}, \xi)d(x_n, Tx_n, \xi)}{1+d(x_{n-1}, x_n, \xi)} \right\} \right) \\ (4) \quad & + \mu \min \{d(x_{n-1}, Tx_n, \xi), d(x_n, Tx_n, \xi), d(x_{n-1}, Tx_{n-1}, \xi), d(x_n, Tx_{n-1}, \xi)\} \end{aligned}$$

Inequality (4), can be reduced since

$$\begin{aligned} & \min \{d(x_{n-1}, Tx_n, \xi), d(x_n, Tx_n, \xi), d(x_{n-1}, Tx_{n-1}, \xi), d(x_n, Tx_{n-1}, \xi)\} \\ &= \min \{d(x_{n-1}, x_{n+1}, \xi), d(x_n, x_{n+1}, \xi), d(x_{n-1}, x_n, \xi), d(x_n, x_n, \xi)\} \\ (5) \quad & = 0. \end{aligned}$$

Using (5), inequality (4) reduces to

$$\begin{aligned} & \psi(d(x_n, x_{n+1}, \xi)) \\ (6) \quad & \leq \psi(\max \{d(x_{n-1}, x_n, \xi), d(x_n, x_{n+1}, \xi)\}) - \varphi(\max \{d(x_{n-1}, x_n, \xi), d(x_n, x_{n+1}, \xi)\}) \end{aligned}$$

Inequality (6) further reduces, if we assume that

$$\max \{d(x_{n-1}, x_n, \xi), d(x_n, x_{n+1}, \xi)\} = d(x_{n-1}, x_n, \xi)$$

for otherwise, we assume that

$$\max \{d(x_{n-1}, x_n, \xi), d(x_n, x_{n+1}, \xi)\} = d(x_n, x_{n+1}, \xi).$$

In the latter case, inequality (6), reduces to

$$\psi(d(x_n, x_{n+1}, \xi)) \leq \psi(d(x_n, x_{n+1}, \xi)) - \varphi(d(x_n, x_{n+1}, \xi))$$

(7)

It follows that  $0 \leq -\varphi(d(x_n, x_{n+1}, \xi))$  which leads to a contradiction. Thus  $\max \{d(x_{n-1}, x_n, \xi), d(x_n, x_{n+1}, \xi)\} = d(x_{n-1}, x_n, \xi)$ . Hence, we have

$$\psi(d(x_n, x_{n+1}, \xi)) \leq \psi(d(x_{n-1}, x_n, \xi)) - \varphi(d(x_{n-1}, x_n, \xi))$$

(8)

$$\leq \psi(d(x_{n-1}, x_n, \xi))$$

It follows that  $\{d(x_n, x_{n+1}, \xi)\}_{n \in \mathbb{N}}$  is a decreasing sequence.

We next shall show that  $\lim_{n \rightarrow \infty} d(x_n, x_{n+1}, \xi) = 0$ . Suppose that

$\lim_{n \rightarrow \infty} d(x_n, x_{n+1}, \xi) = r$  where  $r > 0$  then taking limit as  $n \rightarrow \infty$  in inequality (7) we get

(9)

$$\psi(r) \leq \psi(r) - \varphi(r)$$

which is a contradiction unless we have that  $r = 0$  thus

$$\lim_{n \rightarrow \infty} d(x_n, x_{n+1}, \xi) = 0.$$

We next shall prove that  $\{x_n\}_{n \in \mathbb{N}}$  is a Cauchy sequence in  $X$ . From the modified rectangular inequality we obtain,

$$\begin{aligned} d(x_n, x_m, \xi) &\leq \alpha d(x_n, x_m, x_{n+1}) + \beta d(x_m, \xi, x_{n+1}) + \gamma d(\xi, x_n, x_{n+1}) \\ &\leq \alpha d(x_n, x_{n+1}, x_m) + \beta \alpha d(x_m, x_{m+1}, \xi) + \beta^2 d(x_{n+1}, x_{m+1}, \xi) \\ &\quad + \beta \gamma d(x_m, x_{m+1}, x_{n+1}) + \gamma d(x_n, x_{n+1}, \xi) \end{aligned}$$

(10)

Using properties of the altering distance functions we get,

$$\begin{aligned}
 & \psi(d(x_n, x_m, \xi)) \\
 & \leq \alpha\psi(d(x_n, x_{n+1}, x_m)) + \beta\alpha\psi(d(x_m, x_{m+1}, \xi)) + \beta^2\psi(d(x_{n+1}, x_{m+1}, \xi)) \\
 & \quad + \beta\gamma\psi(d(x_m, x_{m+1}, x_{n+1})) + \gamma\psi(d(x_n, x_{n+1}, \xi))
 \end{aligned}
 \tag{11}$$

Using inequality (2) in (11) we get

$$\begin{aligned}
 & \psi(d(x_n, x_m, \xi)) \\
 & \leq \alpha\psi(d(x_n, x_{n+1}, x_m)) + \beta\alpha\psi(d(x_m, x_{m+1}, \xi)) \\
 & \quad + \beta\psi\left(\max\left\{d(x_n, x_m, \xi), \frac{d(x_n, Tx_n, \xi)d(x_m, Tx_m, \xi)}{1+d(Tx_n, Tx_m, \xi)}, \frac{d(x_n, Tx_n, \xi)d(x_m, Tx_m, \xi)}{1+d(x_n, x_m, \xi)}\right\}\right) \\
 & \quad - \beta\varphi\left(\max\left\{d(x_n, x_m, \xi), \frac{d(x_n, Tx_n, \xi)d(x_m, Tx_m, \xi)}{1+d(Tx_n, Tx_m, \xi)}, \frac{d(x_n, Tx_n, \xi)d(x_m, Tx_m, \xi)}{1+d(x_n, x_m, \xi)}\right\}\right) \\
 & \quad + \beta\mu \min\{d(x_n, Tx_n, \xi), d(x_n, Tx_m, \xi), d(x_m, Tx_n, \xi), d(x_m, Tx_m, \xi)\} \\
 & \quad + \beta\gamma\psi(d(x_m, x_{m+1}, x_{n+1})) + \gamma\psi(d(x_n, x_{n+1}, \xi))
 \end{aligned}
 \tag{12}$$

Taking  $m, n \rightarrow \infty$  we get,

$$\begin{aligned}
 & \lim_{m, n \rightarrow \infty} \max\left\{d(x_n, x_m, \xi), \frac{d(x_n, Tx_n, \xi)d(x_m, Tx_m, \xi)}{1+d(Tx_n, Tx_m, \xi)}, \frac{d(x_n, Tx_n, \xi)d(x_m, Tx_m, \xi)}{1+d(x_n, x_m, \xi)}\right\} \\
 & = \lim_{m, n \rightarrow \infty} \max\left\{d(x_n, x_m, \xi), \frac{d(x_n, x_{n+1}, \xi)d(x_m, x_{m+1}, \xi)}{1+d(x_{n+1}, x_{m+1}, \xi)}, \frac{d(x_n, x_{n+1}, \xi)d(x_m, x_{m+1}, \xi)}{1+d(x_n, x_m, \xi)}\right\} \\
 & = \lim_{m, n \rightarrow \infty} d(x_n, x_m, \xi)
 \end{aligned}
 \tag{13}$$

and

$$\begin{aligned}
 & \lim_{m, n \rightarrow \infty} \min\{d(x_n, Tx_n, \xi), d(x_n, Tx_m, \xi), d(x_m, Tx_n, \xi), d(x_m, Tx_m, \xi)\} \\
 & = \lim_{m, n \rightarrow \infty} \min\{d(x_n, x_{n+1}, \xi), d(x_n, x_{m+1}, \xi), d(x_m, x_{n+1}, \xi), d(x_m, x_{m+1}, \xi)\} \\
 & = 0
 \end{aligned}
 \tag{14}$$

Taking  $m, n \rightarrow \infty$  in (12), using (13) and (14) we get

$$\psi\left(\lim_{m, n \rightarrow \infty} d(x_n, x_m, \xi)\right) \leq \beta\psi\left(\lim_{m, n \rightarrow \infty} d(x_n, x_m, \xi)\right) - \beta\varphi\left(\lim_{m, n \rightarrow \infty} d(x_n, x_m, \xi)\right)
 \tag{15}$$

Inequality (15) is only true if  $\lim_{m,n \rightarrow \infty} d(x_n, x_m, \xi) = 0$ . Thus we conclude that  $\{x_n\}_{n \in \mathbb{N}}$  is a Cauchy sequence in  $X$ . Since  $(X, d)$  is complete there exists  $x' \in X$  such that  $\lim_{m,n \rightarrow \infty} d(x_n, x', \xi) = 0$ .

We now show that  $Tx' = x'$ . Replacing  $x_n = x_{n+1}$ ,  $x_m = Tx'$  in inequality (15), we get

$$(16) \quad \psi \left( \lim_{n \rightarrow \infty} d(x_{n+1}, Tx', \xi) \right) \leq \beta \psi \left( \lim_{n \rightarrow \infty} d(x_{n+1}, Tx', \xi) \right) - \beta \varphi \left( \lim_{n \rightarrow \infty} d(x_{n+1}, Tx', \xi) \right)$$

It follows that

$$(17) \quad \psi(d(x', Tx', \xi)) \leq \beta \psi(d(x', Tx', \xi)) - \beta \varphi(d(x', Tx', \xi))$$

which leads to a contradiction, unless we have  $d(x', Tx', \xi) = 0$  i.e.,  $Tx' = x'$ . To prove uniqueness of  $x'$ , we assume that  $x''$  is a fixed point of  $T$  such that  $x' \neq x''$ . From inequality (2),

$$(18) \quad \begin{aligned} & \beta \psi(d(x', x'', \xi)) \\ & \beta \psi(d(Tx', Tx'', \xi)) \\ & \leq \psi \left( \max \left\{ d(x', x'', \xi), \frac{d(x', Tx', \xi)d(x'', Tx'', \xi)}{1+d(x', x'', \xi)}, \frac{d(x', Tx', \xi)d(x'', Tx'', \xi)}{1+d(Tx', Tx'', \xi)} \right\} \right) \\ & - \varphi \left( \max \left\{ d(x', x'', \xi), \frac{d(x', Tx', \xi)d(x'', Tx'', \xi)}{1+d(x', x'', \xi)}, \frac{d(x', Tx', \xi)d(x'', Tx'', \xi)}{1+d(Tx', Tx'', \xi)} \right\} \right) \\ & + \mu \min \{ d(x', Tx', \xi), d(x', Tx'', \xi), d(x'', Tx', \xi), d(x'', Tx'', \xi) \} \end{aligned}$$

It follows that

$$(19) \quad \beta \psi(d(x', x'', \xi)) \leq \psi(d(x', x'', \xi)) - \varphi(d(x', x'', \xi))$$

is a contradiction unless  $d(x', x'', \xi) = 0$  which implies that  $x' = x''$ .  $\square$

**Corollary 2.5.** *Let  $(X, d)$  be a generalized complete 2-metric space and a mapping  $T : X \rightarrow X$  be a self mapping. If there exists  $\psi, \varphi \in \Psi$  such that*

$$(20) \quad \begin{aligned} \beta \psi(d(Tx, Ty, \xi)) & \leq \psi \left( \max \left\{ d(x, y, \xi), \frac{d(x, Tx, \xi)d(y, Ty, \xi)}{1+d(x, y, \xi)}, \frac{d(x, Tx, \xi)d(y, Ty, \xi)}{1+d(Tx, Ty, \xi)} \right\} \right) \\ & - \varphi \left( \max \left\{ d(x, y, \xi), \frac{d(x, Tx, \xi)d(y, Ty, \xi)}{1+d(x, y, \xi)}, \frac{d(x, Tx, \xi)d(y, Ty, \xi)}{1+d(Tx, Ty, \xi)} \right\} \right) \end{aligned}$$

where  $x, y, z \in X$  and  $\psi, \varphi \in \Psi$ . Then  $T$  has a unique fixed point.



*Proof.* Follows from theorem 2.4 by taking  $\mu = 0$ . □

**Corollary 2.6.** *Let  $(X, d)$  be a generalized complete 2-metric space and a mapping  $T : X \rightarrow X$  be a self mapping. If there exists  $\varphi \in \Psi$  such that*

$$\begin{aligned}
 & \beta(d(Tx, Ty, \xi)) \\
 & \leq \left( \max \left\{ d(x, y, \xi), \frac{d(x, Tx, \xi)d(y, Ty, \xi)}{1+d(x, y, \xi)}, \frac{d(x, Tx, \xi)d(y, Ty, \xi)}{1+d(Tx, Ty, \xi)} \right\} \right) \\
 & - \varphi \left( \max \left\{ d(x, y, \xi), \frac{d(x, Tx, \xi)d(y, Ty, \xi)}{1+d(x, y, \xi)}, \frac{d(x, Tx, \xi)d(y, Ty, \xi)}{1+d(Tx, Ty, \xi)} \right\} \right)
 \end{aligned}
 \tag{21}$$

where  $x, y, z \in X$  and  $\varphi \in \Psi$ . Then  $T$  has a unique fixed point.

*Proof.* Follows from theorem 2.4 by taking  $\psi$ - the identity mapping □

**Example 2.7.** *Let  $X = [0, 1]$  and define*

$$(22) \quad d(x, y, z) = \begin{cases} 0 & , \text{ if at least two of the three points are the same} \\ e^{|x-y|+|y-z|+|z-x|} & , \text{ otherwise} \end{cases}$$

*It can be shown that  $d$  is a generalized 2-metric.*

*$d$  is a generalized 2-metric.*

*Let  $T : X \rightarrow X$  be defined by*

$$T(x) = \sin x$$

*then for  $x \neq y \neq z \in X$ ,*

$$\begin{aligned}
 & |Tx - Ty| + |Ty - z| + |z - Tx| \\
 & = |\sin x - \sin y| + |\sin y - \sin(\sin^{-1} z)| + |\sin x - \sin(\sin^{-1} z)| \\
 & \leq |x - y| + |y - \sin^{-1} z| + |x - \sin^{-1} z| \\
 & \leq |x - y| + |y - z| + |x - z|
 \end{aligned}$$

*Since the exponential function is increasing, it follows that*

$$(23) \quad e^{|Tx-Ty|+|Ty-z|+|z-Tx|} \leq e^{|x-y|+|y-z|+|x-z|}$$

Let  $\psi(t) = t$  then it follows that for some  $\beta \geq 1$

$$\begin{aligned} & \beta \psi(d(Tx, Ty, z)) \\ & \leq \psi(d(x, y, z)) \\ & \leq \psi\left(\max\left\{d(x, y, z), \frac{d(x, Tx, z)d(y, Ty, z)}{1+d(x, y, z)}, \frac{d(x, Tx, z)d(y, Ty, z)}{1+d(Tx, Ty, z)}\right\}\right) \end{aligned}$$

It follows from theorem (2.4), that  $T$  has a unique fixed point in  $X$ .

### 3. CONCLUSION

In this paper, we proved the existence and uniqueness of a fixed point for a  $(\psi, \varphi)$ -weakly contractive mapping in a generalized 2-metric space by further imposing a sublinearity property on the class of all altering distance functions.

### CONFLICT OF INTERESTS

The authors declare that there is no conflict of interests.

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