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COMMON FIXED POINT THEOREM FOR SIX SELFMAPS OF A COMPLETE G-METRIC SPACE

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Abstract: In the present paper, we prove a common fixed point theorem for six weakly compatible selfmaps of a complete G-metric space. As an illustration, we give an example.

Keywords: G-metric space; weakly compatible mappings; fixed point; associated sequence of a point relative to six self maps; implicit relation.

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1. Introduction

Generally fixed point theorems are proved for selfmaps of metric spaces. Fixed point Theorems on metric spaces have important theoretical and practical applications. In 1963 Gahler [1,2] introduced the notion of 2-metric spaces while Dhage[3] initiated the notion of D-metric spaces in 1984. Subsequently several researchers have proved that most of their claims made are not valid. As a probable modification to D-metric spaces Shaban Sedghi, Nabi Shobe and Haiyan

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Zhou [4] introduced D^* metric spaces. In 2006, Zead Mustafa and Brailey Sims [5,6] initiated G -metric spaces. Of these two generalizations, the G -metric space evinced interest in many researchers.

Sessa [7] introduced the concept of weakly commuting mappings as a generalization of commuting maps. This was further generalized by G,Jungck [8,9] in 1986 as compatible mappings. In 1996 Jungck and Rhoades [10] introduced the notion of weakly compatible mappings.

The purpose of this paper is to prove a common fixed point theorem for six weakly compatible selfmaps of a complete G -metric space.

2. Preliminaries

Definition 2.1: [6] Let X be a non-empty set and $G: X^3 \rightarrow [0, \infty)$ be a function satisfying:

$$(G1) \quad G(x, y, z) = 0 \quad \text{if} \quad x = y = z$$

$$(G2) \quad 0 < G(x, x, y) \quad \text{for all} \quad x, y \in X \quad \text{with} \quad x \neq y$$

$$(G3) \quad G(x, x, y) < G(x, y, z) \quad \text{for all} \quad x, y, z \in X \quad \text{with} \quad y \neq z$$

$$(G4) \quad G(x, y, z) = G(\sigma(x, y, z)) \quad \text{for all} \quad x, y, z \in X, \quad \text{where} \quad \sigma(x, y, z) \quad \text{is a permutation of the set} \\ \{x, y, z\} \quad \text{and}$$

$$(G5) \quad G(x, y, z) < G(x, w, w) + G(w, y, z) \quad \text{for all} \quad x, y, z, w \in X$$

Then G is called a G - metric on X and the pair (X, G) is called a G - metric Space.

Example 2.2: Let (X, d) be a metric space. Define $G_m^d: X^3 \rightarrow [0, \infty)$ by

$$G_m^d(x, y, z) = \max\{d(x, y), d(y, z), d(z, x)\} \quad \text{for} \quad x, y, z \in X. \quad \text{Then} \quad (X, G_m^d) \quad \text{is a} \quad G\text{-metric Space.}$$

Lemma 2.3: [6] If (X, G) is a G -metric space then $G(x, y, y) \leq 2G(y, x, x)$ for all $x, y \in X$

Definition 2.4: Let (X, G) be a G -metric Space. A sequence $\{x_n\}$ in X is said to be G -convergent if there is a $x_0 \in X$ such that to each $\varepsilon > 0$ there is a natural number N for which $G(x_n, x_n, x_0) < \varepsilon$ for all $n \geq N$.

Lemma 2.5: [6] Let (X, G) be a G -metric Space, then for a sequence $\{x_n\} \subseteq X$ and point $x \in X$ the following are equivalent.

- (i) $\{x_n\}$ is G -convergent to x .
- (ii) $d_G(x_n, x) \rightarrow 0$ as $n \rightarrow \infty$ (that is $\{x_n\}$ converges to x relative to the metric d_G)
- (iii) $G(x_n, x_n, x) \rightarrow 0$ as $n \rightarrow \infty$
- (iv) $G(x_n, x, x) \rightarrow 0$ as $n \rightarrow \infty$
- (v) $G(x_m, x_n, x) \rightarrow 0$ as $m, n \rightarrow \infty$

Definition 2.6: [6] Let (X, G) be a G -metric space, then a sequence $\{x_n\} \subseteq X$ is said to be G -Cauchy if for each $\varepsilon > 0$, there exists a natural number N such that $G(x_n, x_m, x_l) < \varepsilon$ for all $n, m, l \geq N$.

Note that every G -convergent sequence in a G -metric space (X, G) is G -Cauchy.

Definition 2.7: [6] A G -metric space (X, G) is said to be G -complete if every G -Cauchy sequence in (X, G) is G -convergent in (X, G)

Definition 2.8: Let f and g are self maps of a G -metric space (X, G) such that

$$\lim_{n \rightarrow \infty} G(fgx_n, gfx_n, gfx_n) = 0 \text{ for every sequence } \{x_n\} \text{ in } X \text{ with } \lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} gx_n = t \text{ for some } t \in X.$$

Then the functions f and g are said to be compatible.

Definition 2.9: [11] Suppose f and g are self maps of a G -metric space (X, G) . The pair f and g is said to be weakly compatible if $G(fgx, gfx, gfx) = 0$ whenever $G(fx, gx, gx) = 0$

Definition 2.10: A function $\phi: (\mathbb{R}^+)^4 \rightarrow \mathbb{R}^+$ which is continuous and increasing in each coordinate with $\phi(t, t, t, t) < t$ for every $t \in \mathbb{R}^+$ is called an Implicit relation.

The set all implicit relations is denoted by Φ

Definition 2.11: Suppose f, g, h, R, S and T be self maps of a G -metric space such that $f(X) \subseteq R(X), g(X) \subseteq S(X)$ and $h(X) \subseteq T(X)$. For x_0 in X , If $\{x_n\}$ is a sequence in X such that $fx_{3n} = Rx_{3n+1}, gx_{3n+1} = Sx_{3n+2}, hx_{3n+2} = Tx_{3n+3}, n \geq 0$. Then $\{x_n\}$ is called an associated sequence of x_0 relative to selfmaps f, g, h, R, S and T

3. Main results

Theorem 3.1. Let f, g, h, R, S and T be self maps of a complete G -metric space (X, G) with following conditions

(i) $f(X) \subseteq R(X), g(X) \subseteq S(X), h(X) \subseteq T(X)$ and

(ii) one of $f(X), g(X)$ and $h(X)$ is closed subset of X

(iii) $G(fx, gy, hz) \leq q\phi(G(Tx, Ry, Sz), G(Tx, Ry, gy), G(Ry, Sz, hz), G(Sz, Tx, fx))$ for every

$x, y, z \in X$ some $0 < q < \frac{1}{2}$ and $\phi \in \Phi$

(iv) The pairs $(f, T), (g, R)$ and (h, S) are weakly compatible

Then f, g, h, R, S and T have a unique common fixed point in X .

Proof. Let $x_0 \in X$ be an arbitrary point. Then we can construct a sequence $\{x_n\}$ in X such that

$$y_{3n} = fx_{3n} = Rx_{3n+1}, \quad y_{3n+1} = gx_{3n+1} = Sx_{3n+2}, \quad y_{3n+2} = hx_{3n+2} = Tx_{3n+3}, \quad \text{for } n = 0, 1, 2, \dots$$

Let $G_m = G(y_m, y_{m+1}, y_{m+2})$

If $m = 3n$ then we have

$$\begin{aligned}
G_{3n} &= G(y_{3n}, y_{3n+1}, y_{3n+2}) \\
&= G(fx_{3n}, gx_{3n+1}, hx_{3n+2}) \\
&\leq q\phi(G(Tx_{3n}, Rx_{3n+1}, Sx_{3n+2}), G(Tx_{3n}, Rx_{3n+1}, gx_{3n+1}), G(Rx_{3n+1}, Sx_{3n+2}, hx_{3n+2}), G(Sx_{3n+2}, Tx_{3n}, fx_{3n})) \\
&\leq q\phi(G(y_{3n-1}, y_{3n}, y_{3n+1}), G(y_{3n-1}, y_{3n}, y_{3n+1}), G(y_{3n}, y_{3n+1}, y_{3n+2}), G(y_{3n+1}, y_{3n-1}, y_{3n})) \\
&= q\phi(G_{3n-1}, G_{3n-1}, G_{3n}, G_{3n-1})
\end{aligned}$$

we now prove that $G_{3n} \leq G_{3n-1}$ for every $n \in \mathbb{N}$

If $G_{3n} > G_{3n-1}$ for some $n \in \mathbb{N}$ by above inequality we have $G_{3n} < qG_{3n}$ which is a contradiction since $0 < q < \frac{1}{2}$

Similarly, we can prove that $G_{3n+1} \leq G_{3n}$ and $G_{3n+2} \leq G_{3n+1}$

Hence $G_n \leq G_{n-1}$ for all $n \geq 1$

This gives

$$\begin{aligned}
G(y_n, y_{n+1}, y_{n+2}) &< qG(y_{n-1}, y_n, y_{n+1}) \\
&< q^2G(y_{n-2}, y_{n-1}, y_n) \\
&\dots\dots\dots \\
&< q^nG(y_0, y_1, y_2)
\end{aligned}$$

We have $G(y_n, y_n, y_{n+1}) \leq qG(y_n, y_{n+1}, y_{n+2}) < q^nG(y_0, y_1, y_2)$

We now claim that $\{y_n\}$ is Cauchy sequence.

For every $m, n \in \mathbb{N}$ with $m > n$ we have

$$\begin{aligned}
G(y_n, y_m, y_m) &< G(y_n, y_{n+1}, y_{n+1}) + G(y_{n+1}, y_m, y_m) \\
&\leq G(y_n, y_{n+1}, y_{n+1}) + G(y_{n+1}, y_{n+2}, y_{n+2}) + \dots\dots + G(y_{m-1}, y_m, y_m) \\
&\leq 2[G(y_{n+1}, y_n, y_n) + G(y_{n+2}, y_{n+1}, y_{n+1}) + \dots\dots + G(y_m, y_{m-1}, y_{m-1})] \\
&= 2[G(y_n, y_n, y_{n+1}) + G(y_{n+1}, y_{n+1}, y_{n+2}) + \dots\dots + G(y_{m-1}, y_{m-1}, y_m)] \\
&< 2[q^nG(y_0, y_1, y_2) + q^{n+1}G(y_0, y_1, y_2), \dots\dots + q^{m-1}G(y_0, y_1, y_2)] \\
&= 2[q^n + q^{n+1} + \dots\dots + q^{m-1}]G(y_0, y_1, y_2) \\
&< 2 \cdot \frac{q^n}{1-q} G(y_0, y_1, y_2) \rightarrow 0 \text{ as } n \rightarrow \infty
\end{aligned}$$

Proving that $\{y_n\}$ is a Cauchy sequence and since X is complete, there exists a z in X such

That $\lim_{n \rightarrow \infty} y_n = z$. this implies

$$\lim_{n \rightarrow \infty} y_n = \lim_{n \rightarrow \infty} fx_{3n} = \lim_{n \rightarrow \infty} gx_{3n+1} = \lim_{n \rightarrow \infty} hx_{3n+2} = \lim_{n \rightarrow \infty} Rx_{3n+1} = \lim_{n \rightarrow \infty} Sx_{3n+2} = \lim_{n \rightarrow \infty} Tx_{3n+3} = z$$

Suppose $h(X)$ be a closed subset of X . Hence there exists $u \in X$ such that $Tu = z$

We shall prove that $fu = z$. If $fu \neq z$ then $G(fu, z, z) > 0$

By (iii) of the Theorem 3.1 we have

$$G(fu, gx_{3n+1}, hx_{3n+2}) \leq q\phi(G(Tu, Rx_{3n+1}, Sx_{3n+2}), G(Tu, Rx_{3n+1}, gx_{3n+1}), G(Rx_{3n+1}, Sx_{3n+2}, hx_{3n+2}), G(Sx_{3n+2}, Tu, fu))$$

on letting $n \rightarrow \infty$ we obtain

$$\begin{aligned} G(fu, z, z) &\leq q\phi(G(Tu, z, z), G(Tu, z, z), G(z, z, z), G(z, Tu, fu)) \\ &= q\phi(G(z, z, z), G(z, z, z), G(z, z, z), G(z, z, fu)) \end{aligned}$$

If $G(fu, z, z) > 0$ then we have $G(fu, z, z) < qG(fu, z, z)$

Which leads to a contradiction since $0 < q < \frac{1}{2}$, hence $G(fu, z, z) = 0$ implies $fu = z$

Since the pair (f, T) is weakly compatible, then we have $fTu = Tfu$. This gives $fz = Tz$

Now we show that $fz = z$

If $fz \neq z$ then by (iii) of the Theorem 3.1 we have

$$G(fz, gx_{3n+1}, hx_{3n+2}) \leq q\phi(G(Tz, Rx_{3n+1}, Sx_{3n+2}), G(Tz, Rx_{3n+1}, gx_{3n+1}), G(Rx_{3n+1}, Sx_{3n+2}, hx_{3n+2}), G(Sx_{3n+2}, Tz, fz))$$

On letting $n \rightarrow \infty$ and using that fact $fz = Tz$, we get

$$G(fz, z, z) \leq q\phi(G(fz, z, z), G(fz, z, z), G(z, z, z), G(z, fz, fz))$$

Since $G(z, fz, fz) \leq 2G(fz, z, z)$ and ϕ is increasing in each co-ordinate then

$$G(fz, z, z) \leq q\phi(2G(fz, z, z), 2G(fz, z, z), 2G(fz, z, z), 2G(fz, z, z)) < 2qG(fz, z, z)$$

Which is a contradiction since $0 < q < \frac{1}{2}$ and hence $fz = z$

Showing that $fz = Tz = z$

Since $fz = z$ and $f(X) \subseteq R(X)$, then there exists $v \in X$ such that $Rv = z$

Now we shall prove that $gv = z$

If $gv \neq z$ then $G(z, gv, z) > 0$. Now by (iii) of the Theorem 3.1 we have

$$\begin{aligned} G(z, gv, hx_{3n+2}) &= G(fz, gv, hx_{3n+2}) \\ &\leq q\phi(G(Tz, Rv, Sx_{3n+2}), G(Tz, Rv, gv), G(Rv, Sx_{3n+2}, hx_{3n+2}), G(Sx_{3n+2}, Tz, fz)) \end{aligned}$$

on letting $n \rightarrow \infty$ we have

$$\begin{aligned} G(z, gv, z) &\leq q\phi(G(z, z, z), G(z, z, gv), G(z, z, z), G(z, z, z)) \\ &= q\phi(0, G(z, z, gv), 0, 0) \\ &\leq q\phi(G(z, gv, z), G(z, gv, z), G(z, gv, z), G(z, gv, z)) \\ &< qG(z, z, gz) \end{aligned}$$

Which is a contradiction since $0 < q < \frac{1}{2}$ and hence $gv = z$

Since the pair (g, R) is weakly compatible then we have $gRv = Rgv$. Hence $gz = Rz$

We now show that $gz = z$. If $gz \neq z$, then by (iii) of the Theorem 3.1 we have

$$G(fz, gz, hx_{3n+2}) \leq q\phi(G(Tz, Rz, Sx_{3n+2}), G(Tz, Rz, gz), G(Rz, Sx_{3n+2}, hx_{3n+2}), G(Sx_{3n+2}, Tz, fz))$$

on letting $n \rightarrow \infty$ we get

$$\begin{aligned} G(fz, gz, z) &\leq q\phi(G(Tz, Rz, z), G(Tz, Rz, gz), G(Rz, z, z), G(z, Tz, fz)) \\ G(z, gz, z) &\leq q\phi(G(z, gz, z), G(z, gz, gz), G(gz, z, z), G(z, z, z)) \\ &\leq q\phi(2G(z, gz, z), 2G(z, gz, z), 2G(z, gz, z), G(z, gz, z)) \\ &< 2qG(z, gz, z) \end{aligned}$$

Which is a contradiction since $0 < q < \frac{1}{2}$, and hence $gz = z$

Therefore $gz = Rz = z$

Since $gz = z$ and $g(X) \subseteq S(X)$, then there exists $w \in X$ such that $Sw = z$

Now we prove that $hw = z$

If $hw \neq z$, then $G(z, z, hw) > 0$. Now by (iii) of the Theorem 3.1 we have

$$\begin{aligned}
G(z, z, hw) &= G(fz, gz, hw) \leq q\phi(G(Tz, Rz, Sw), G(Tz, Rz, gz), G(Rz, Sw, hw), G(Sw, Tz, fz)) \\
&= q\phi(G(z, z, z), G(z, z, z), G(z, z, hw), G(z, z, z)) \\
&\leq q\phi(G(z, z, hw), G(z, z, hw), G(z, z, hw), G(z, z, hw)) \\
&< qG(z, z, hw)
\end{aligned}$$

Which is a contradiction since $0 < q < \frac{1}{2}$ and hence $hw = z$

Since, the pair (h, S) is weakly compatible then we have $hSw = Shw$ implies $hz = Sz$.

If $hz \neq z$ then from (iii) of the Theorem 3.1 we have

$$\begin{aligned}
G(z, z, hz) &= G(fz, gz, hz) \leq q\phi(G(Tz, Rz, Sz), G(Tz, Rz, gz), G(Rz, Sz, hz), G(Sz, Tz, fz)) \\
&= q\phi(G(z, z, hz), G(z, z, z), G(z, hz, hz), G(hz, z, z)) \\
&\leq q\phi(G(z, z, hz), 0, 2G(hz, z, z), G(hz, z, z)) \\
&= q\phi(2G(z, z, hz), 2G(z, z, hz), 2G(z, z, hz), 2G(z, z, hz)) \\
&< 2qG(z, z, hz)
\end{aligned}$$

Which is a contradiction since $0 < q < \frac{1}{2}$ and hence $hz = z$

Proving that $hz = Sz = z$

Hence z is a common fixed point of f, g, h, R, S and T

The proof is similar when $g(X)$ or $h(X)$ closed subset of X with appropriate changes.

Now we prove the uniqueness of common fixed point. If possible let z' be another common fixed point of f, g, h, R, S and T .

Then from (iii) of the Theorem 3.1 we have

$$\begin{aligned}
G(z, z', z') &= G(fz, gz', hz') \\
&\leq q\phi(G(Tz, Rz', Sz'), G(Tz, Rz', gz'), G(Rz', Sz', hz'), G(Sz', Tz, fz)) \\
&= q\phi(G(z, z', z'), G(z, z', z'), G(z', z', z'), G(z', z, z)) \\
&\leq q\phi(G(z, z', z'), G(z, z', z'), 0, 2G(z, z', z')) \\
&\leq q\phi(2G(z, z', z'), 2G(z, z', z'), 2G(z, z', z'), 2G(z, z', z')) \\
&< 2qG(z, z', z')
\end{aligned}$$

Which is a contradiction since $0 < q < \frac{1}{2}$ and hence $z = z'$

Showing that z is a unique common fixed point of f, g, h, R, S and T .

As an illustration we have the following example.

Example 3.2: Let $X = [0,1]$ with $G(x, y, z) = \max\{|x - y|, |y - z|, |z - x|\}$ for $x, y, z \in X$.

Then G is a G -metric on X .

Define $f : X \rightarrow X, g : X \rightarrow X, h : X \rightarrow X, T : X \rightarrow X, R : X \rightarrow X, S : X \rightarrow X$ by

$$f(x) = g(x) = \begin{cases} \frac{1}{3} \text{ if } x = 0 \\ \frac{1}{2} \text{ if } x \in (0,1] \end{cases} \quad \text{and} \quad h(x) = \begin{cases} \frac{1}{5} \text{ if } x = 0 \\ \frac{1}{2} \text{ if } x \in (0,1] \end{cases}$$

$$R(x) = S(x) = \frac{x+1}{3} \text{ if } x \in [0,1] \text{ and } T(x) = x \text{ if } x \in [0,1]$$

$$f(X) = g(X) = \{\frac{1}{3}, \frac{1}{2}\} \quad h(X) = \{\frac{1}{5}, \frac{1}{2}\} \quad R(X) = S(X) = [\frac{1}{3}, \frac{1}{2}] \quad T(X) = [0,1]$$

Clearly $f(X) \subseteq R(X), g(X) \subseteq S(X)$ and $h(X) \subseteq T(X)$

Also $f(X), g(X), h(X)$ are closed subsets of X

The pairs $(f, T), (g, R),$ and (h, S) are commute at their coincident point $\frac{1}{2}$ and hence they are weakly compatible

We now prove the mappings satisfying the condition (iii) of the Theorem 3.1

Case (i): If $x = y = z = 0,$ then

$$G(fx, gy, hz) = \frac{2}{15}, G(Tx, Ry, Sz) = \frac{1}{3}, G(Tx, Ry, gy) = \frac{1}{3}, G(Ry, Sz, hz) = \frac{2}{15}, G(Sz, Tx, fx) = \frac{1}{3}$$

Therefore, the condition (iii) of the Theorem 3.1 holds if $\frac{2}{15} \leq q\phi\left(\frac{2}{15}, \frac{1}{3}, \frac{2}{15}, \frac{1}{3}\right) < q\frac{1}{3}$

This is possible by choosing $q > 0$ such that $\frac{2}{5} < q < \frac{1}{2}$

Proving that the condition (iii) of the Theorem 3.1 satisfied in this case

Case (ii): If $x = y = 0,$ and $z \in (0,1]$ then

$$G(fx, gy, hz) = \frac{1}{6}, G(Tx, Ry, Sz) = \frac{2}{3}, G(Tx, Ry, gy) = \frac{1}{3}, G(Ry, Sz, hz) \leq \frac{1}{3}, G(Sz, Tx, fx) \leq \frac{2}{3}$$

$$\frac{1}{6} \leq q\phi\left(\frac{2}{3}, \frac{1}{3}, \frac{1}{3}, \frac{2}{3}\right) < q\frac{2}{3}$$

Hence the condition (iii) of the Theorem 3.1 holds with q satisfying $\frac{1}{4} < q < \frac{1}{2}$

Case (iii): If $x = z = 0$, and $y \in (0,1]$ then

$$G(fx, gy, hz) = \frac{3}{10}, G(Tx, Ry, Sz) \leq \frac{2}{3}, G(Tx, Ry, gy) \leq \frac{2}{3}, G(Ry, Sz, hz) \leq \frac{7}{15}, G(Sz, Tx, fx) = \frac{2}{15}$$

$$\frac{3}{10} \leq q\phi\left(\frac{2}{3}, \frac{2}{3}, \frac{7}{15}, \frac{2}{15}\right) < q\frac{2}{3}$$

Hence the condition (iii) of the Theorem 3.1 holds with q satisfying $\frac{9}{20} < q < \frac{1}{2}$

Case (iv): If $y = z = 0$, and $x \in (0,1]$ then

$$G(fx, gy, hz) = \frac{3}{10}, G(Tx, Ry, Sz) \leq \frac{2}{3}, G(Tx, Ry, gy) \leq \frac{2}{3}, G(Ry, Sz, hz) = \frac{2}{15}, G(Sz, Tx, fx) \leq \frac{2}{3}$$

$$G(fx, gy, hz) \leq q\phi(G(Tx, Ry, Sz), G(Tx, Ry, gy), G(Ry, Sz, hz), G(Sz, Tx, fx))$$

$$\frac{3}{10} \leq q\phi\left(\frac{2}{3}, \frac{2}{3}, \frac{2}{15}, \frac{2}{3}\right) < q\frac{2}{3}$$

Hence the condition (iii) of the Theorem 3.1 hold with $q > 0$ satisfying $\frac{9}{20} < q < \frac{1}{2}$

Case (v): If $x = 0$, $y \in (0,1]$ and $z \in (0,1]$ then

$$G(fx, gy, hz) = \frac{1}{6}, G(Tx, Ry, Sz) \leq \frac{2}{3}, G(Tx, Ry, gy) \leq \frac{2}{3}, G(Ry, Sz, hz) \leq \frac{1}{3}, G(Sz, Tx, fx) \leq \frac{2}{3}$$

$$G(fx, gy, hz) \leq q\phi(G(Tx, Ry, Sz), G(Tx, Ry, gy), G(Ry, Sz, hz), G(Sz, Tx, fx))$$

$$\frac{1}{6} \leq q\phi\left(\frac{2}{3}, \frac{2}{3}, \frac{1}{3}, \frac{2}{3}\right) < q\frac{2}{3}$$

Hence the condition (iii) of the Theorem 3.1 hold with $q > 0$ satisfying $\frac{1}{4} < q < \frac{1}{2}$

Case (vi): If $y = 0$, $x \in (0,1]$ and $z \in (0,1]$ then

$$G(fx, gy, hz) = \frac{1}{6}, G(Tx, Ry, Sz) \leq \frac{2}{3}, G(Tx, Ry, gy) \leq \frac{2}{3}, G(Ry, Sz, hz) \leq \frac{1}{3}, G(Sz, Tx, fx) = \frac{2}{3}$$

$$G(fx, gy, hz) \leq q\phi(G(Tx, Ry, Sz), G(Tx, Ry, gy), G(Ry, Sz, hz), G(Sz, Tx, fx))$$

$$\frac{1}{6} \leq q\phi\left(\frac{2}{3}, \frac{2}{3}, \frac{1}{3}, \frac{2}{3}\right) < q\frac{2}{3}$$

Hence the condition (iii) of the Theorem 3.1 hold with $q > 0$ satisfying $\frac{1}{4} < q < \frac{1}{2}$

Case (vii): If $z = 0, x \in (0, 1]$ and $y \in (0, 1]$ then

$$G(fx, gy, hz) = \frac{3}{10}, G(Tx, Ry, Sz) \leq \frac{4}{5}, G(Tx, Ry, gy) \leq \frac{2}{3}, G(Ry, Sz, hz) \leq \frac{7}{15}, G(Sz, Tx, fx) \leq \frac{2}{3}$$

$$G(fx, gy, hz) \leq q\phi(G(Tx, Ry, Sz), G(Tx, Ry, gy), G(Ry, Sz, hz), G(Sz, Tx, fx))$$

$$\frac{3}{10} \leq q\phi\left(\frac{4}{5}, \frac{2}{3}, \frac{7}{15}, \frac{2}{3}\right) < q\frac{4}{5}$$

Hence the condition (iii) of the Theorem 3.1 hold with $q > 0$ satisfying $\frac{3}{8} < q < \frac{1}{2}$

Case (viii): If $x = y \neq 0$, and $z \neq 0$ then $G(fx, gy, hz) = 0$

$$G(fx, gy, hz) = 0 \leq q\phi(G(Tx, Ry, Sz), G(Tx, Ry, gy), G(Ry, Sz, hz), G(Sz, Tx, fx))$$

Hence the condition (iii) of the Theorem 3.1 hold with $q > 0$ satisfying $0 < q < \frac{1}{2}$

From above all cases if we choose $q > 0$ such that $\frac{9}{20} \leq q < \frac{1}{2}$ then the condition (iii) of the

Theorem 3.1 holds

From the above all cases all the conditions of the Theorem 3.1 hold

Hence the selfmaps f, h, g, R, S and T have a unique common fixed point in X

Moreover, $\frac{1}{2}$ is the unique fixed point for all mappings f, h, g, R, S and T .

Corollary 3.3: Let f, g, h, R, S and T be self maps of a complete G -metric space (X, G) with following conditions

(i) $f(X) \subseteq R(X), g(X) \subseteq S(X), h(X) \subseteq T(X)$.

(ii) one of $f(X)$, $g(X)$ and $h(X)$ is closed subset of X

(ii) $G(fx, gy, hz) \leq q\phi(G(Tx, Ry, Sz), G(Tx, Ry, gy), G(Ry, Sz, hz), G(Sz, Tx, fx))$ for every

$x, y, z \in X$ some $0 < q < \frac{1}{2}$ and $\phi \in \Phi$

(iii) $fT = Tf$, $gR = Rg$ and $hS = Sh$

Then f, g, h, R, S and T have a unique common fixed point in X .

Proof: from the fact that the commutativity implies the weakly compatibility of a pair of selfmaps, proof of this corollary follows from the Theorem 3.1

Conflict of Interests

The authors declare that there is no conflict of interests.

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