STABILITY ANALYSIS OF $SLIVR$ COVID-19 EPIDEMIC MODEL WITH QUARANTINE POLICY

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Abstract. In this paper, we present a mathematical model illustrating the dynamics of the COVID-19 disease with vaccination and quarantine strategies. The presented model contains five equations that describe the interaction between individuals who are susceptible, exposed, infected, vaccinated, and recovered. We start the study by verifying the positivity and boundedness of solutions. The existence and the stability of both disease-free equilibrium and endemic equilibrium are proved. Finally, numerical simulations are performed to demonstrate the behavior of the infection over time and to say the influence of quarantine and vaccination on both the COVID-19 dynamics and the basic reproduction number $\mathcal{R}_0$ for controlling the disease’s spread.

Keywords: COVID-19; epidemic model; stability; quarantine policy.

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1. INTRODUCTION

SARS-CoV-2, a coronavirus discovered in 2019, has produced a respiratory disease pandemic known as COVID-19. The virus spreads between people through direct contact or via contaminated surfaces. This disease is currently spreading rapidly in many countries, and the global number of COVID-19 cases is rapidly increasing.

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Mathematical modelling in epidemiology is a source of knowledge for understanding the spread of an disease and an effective tool for controlling and predicting the dynamics of diseases such as Cancer [1], VIH [2], influenza [3], Tuberculosis [4], HBV [5], COVID-19 [11, 12, 13] and the co-infection of COVID-19 and HBV [6], other researchers are interested in modeling multi-strain diseases [7, 8, 10, 9]. Many active studies are currently being conducted to investigate various epidemic models applied to the spread of COVID-19 by scientists all over the world. Ian et al. [14] developed a susceptible-infected-removed (SIR) model that provides a theoretical framework to investigate the time evolution of different populations and monitor diverse significant parameters for the spread of the disease COVID-19 in various communities. In addition, the SARS-COV-2 virus has a long incubation period, which refers to the time between being exposed to the virus and developing symptoms. The average incubation period is 6 days, with recorded variations ranging from 2 to 27 days [15]. As a result, many earlier studies considered a new compartment to the classic SIR in model to account for the exposed population. An SLIR model was implemented by Shaobo et al. [19], to analyse the spread of COVID-19 in Hubei province. Additionally many mathematical models were constructed to study the outbreak of COVID-19 in many countries [16, 17, 18].

Countries worldwide have implemented strict and adequate precautions to prevent and control the spread of COVID-19, including early detection approaches and social distancing [20] to limit contact between individuals as much as possible, as well as medical treatment, to reduce the number of infected citizens. Vaccination is a crucial strategy in fighting against many previously infected diseases. Recently, authors in [21] constructed a $SLIR$ model by considering vaccination and isolation factors as model parameters. Moreover, Amouch et al. [22] proposed a new epidemiological mathematical model for the spread of the COVID-19 disease with a special focus on the transmissibility of individuals with severe symptoms, mild symptoms, and asymptomatic symptoms and take into consideration the vaccination of a portion of susceptible individuals. More recently, a COVID-19 vaccine epidemic model has been tackled [23]. In this work, we continue the investigation of the effect of vaccination by taking into account the effect of quarantine measures on SLIVR COVID-19 epidemic model presented in [23]. Therefore, the
SLIVR COVID-19 epidemic model is formulated as follows

\[
\begin{align*}
\frac{dS(t)}{dt} &= \Lambda - \beta (1 - \rho) (S(t) + \alpha L(t)) \frac{I(t)}{N} - (r_v + d) S(t) + w_v V(t) + l_m R(t), \\
\frac{dL(t)}{dt} &= \beta (1 - \rho) (S(t) + \alpha L(t)) \frac{I(t)}{N} - (d + r_s) L(t), \\
\frac{dI(t)}{dt} &= r_s L(t) - (d + d_0 + r_c) I(t), \\
\frac{dV(t)}{dt} &= r_v S(t) - (d + w_v) V(t), \\
\frac{dR(t)}{dt} &= r_c I(t) - (d + l_m) R(t),
\end{align*}
\]

with

\[
S(0) \geq 0, L(0) \geq 0, I(0) \geq 0, V(0) \geq 0, R(0) \geq 0.
\]

This model includes six variables: susceptible individuals (\(S\)), the population that can make contact with the infection, the exposed individuals (\(L\)), the population exposed to the virus but without developing clinical symptoms. The infectious individuals (\(I\)), the population with fully developed corona-virus symptoms. The vaccinated individuals (\(V\)), and finally removed individuals (\(R\)). All model parameters are assumed to be positive and are described as follows: \(\Lambda\) denotes the population recruitment rate and \(d\) is natural mortality in all compartments. \(\beta\) represent the effective contact rate, \(\alpha\) represents relative transmissibility rate. \(r_s\) represents rate of infection development with symptoms, \(d_0\) is death rate due to infection and \(r_c\) is rate of recovery from infection. \(r_v\) denote vaccination rate, \(w_v\) is vaccine waning rate and \(l_m\) is loss of disease acquired immunity. The parameter \(\rho\) represent the efficiency of quarantine in reducing the latent and infected individuals. The flowchart of our model is illustrated in Fig. 1.

The current work is divided into different sections. In the following section, we will demonstrate the existence, the positivity and boundedness results. In Section 3, we will establish both the local and global stability of both equilibrium. In Section 4, we will present some numerical simulations to verify the theoretical results. The conclusion is stated in Section 5.
2. The Problem Wellposedness and Steady States

In this section, we will prove that the system is biologically meaningful and mathematically well posed. To do this, it is required to prove that the solutions of the system of ordinary differential equation (1) are positive and bounded for all time.

2.1. Existence, positivity and boundedness.

Proposition 2.1. For all non-negative initial condition, the solutions of the system (1) exist, non-negative and remain bounded for all $t > 0$. Moreover,

$$\lim_{t \to +\infty} N(t) \leq \frac{\Lambda}{d}.$$  

Proof. In order to prove the positivity result, we will show that any solution starting from non-negative orthant $\mathbb{R}^5_+$ remains there forever.
Let

\[ T = \sup \{ \tau > 0 : \forall t \in [0, \tau] \text{ such that } S(t) \geq 0, \quad L(t) \geq 0, \quad I(t) \geq 0, \quad V(t) \geq 0, \quad R(t) \geq 0 \} \]

Let us now show that \( T = +\infty \). Suppose the contrary. By continuity of solutions, we have \( S(T) = 0 \) or \( L(T) = 0 \) or \( I(T) = 0 \) or \( V(T) = 0 \) or \( R(T) = 0 \).

- If \( S(T) = 0 \) before the other variables \( L, I, V, R \), becomes zero. Hence,

\[
\frac{dS}{dt} = \lim_{t \to T^-} \frac{S(T) - S(t)}{T - t} = \lim_{t \to T^-} \frac{-S(t)}{T - t} \leq 0.
\]

Using the first equation of system (1), we obtain

\[
\frac{dS(T)}{dt} = \Lambda - (r_v + d)S(T) + \frac{r_v L(T) + d L(T)}{N} = \Lambda - \frac{dN}{T} + \frac{w v V(T) + l_m R(T)}{T},
\]

So, \( \frac{dS(T)}{dt} > 0 \). Which presents a contradiction.

- If \( L(T) = 0 \) before the other variables \( S, I, V, R \), becomes zero. Hence,

\[
\frac{dL}{dt} = \lim_{t \to T^-} \frac{L(T) - L(t)}{T - t} = \lim_{t \to T^-} \frac{-L(t)}{T - t} \leq 0.
\]

Using the first equation of system (1), we obtain

\[
\frac{dL(T)}{dt} = \beta (1 - \rho)(I(T) + \alpha L(T)) - \frac{dN}{T} - (d + r_s)L(T),
\]

So, \( \frac{dL(T)}{dt} > 0 \). Which presents a contradiction. Similar proof for \( I(t), V(t), R(t) \).

Therefore, \( T \) could not be finite, which implies that \( S, L, I, V \) and \( R \) are all positive for all positive time. This proof the positivity of solutions.

To prove the subsequent part of Proposition (2.1), let the total population

\[ N(t) = S(t) + L(t) + I(t) + V(t) + R(t). \]

By adding equations involved in the system (1), we have

\[
\frac{dN}{dt} = \Lambda - dN - d_0 I \leq \Lambda - dN.
\]
By simple manipulation, we have
\[
N(t) \leq N(0)e^{-dt} + e^{-dt}\int_0^t \Lambda e^{-d\xi} d\xi
\]
\[
\leq N(0)e^{-dt} + \frac{\Lambda}{d}\left(1 - e^{-dt}\right)
\]
Thus,
\[
\lim_{t \to +\infty} N(t) \leq \frac{\Lambda}{d}
\]

2.2. Invariant region.

**Proposition 2.2.** The biological feasible region for the transmission dynamic of COVID-19 epidemic model (1) is given by \( \Omega \subset \mathbb{R}_+^5 \), where,
\[
\Omega = \left\{ (S, L, I, V, R) \in \mathbb{R}_+^5 : S + L + I + V + R \leq \frac{\Lambda}{d}\right\}.
\]
Moreover, the closed region defined by \( \Omega \subset \mathbb{R}_+^5 \) is positive invariant for the model (1) with nonnegative initial conditions in \( \mathbb{R}_+^5 \).

**Proof.** As we know that
\[
N(t) = S(t) + L(t) + I(t) + V(t) + R(t),
\]
then,
\[
\frac{dN(t)}{dt} = \Lambda - dN(t) - d_0 I
\]
\[
\leq \Lambda - dN(t),
\]
and
\[
\frac{dN(t)}{dt} \leq 0 \text{ if } N(t) \geq \frac{\Lambda}{d} \text{ for } t \geq 0,
\]
but the solution of (5) is
\[
N(t) \leq N(0)e^{-dt} + \frac{\Lambda}{d}\left(1 - e^{-dt}\right).
\]
Therefore, \( N(t) \leq \frac{\Lambda}{d} \) if \( N(0) \leq \frac{\Lambda}{d} \) as \( t \to \infty \). On the other hand \( N(t) \geq \frac{\Lambda}{d} \) if \( N(0) > \frac{\Lambda}{d} \) as \( t \to \infty \).
Thus, the region \( \Omega \) is positive invariant, and all the solutions trajectories are attracted in \( \mathbb{R}_+^5 \). \( \Box \)
3. Analysis of the Model

In this section, we will first calculate the basic reproduction number $R_0$ for the COVID-19 model (1). Next, we will present the steady states and finally we will demonstrate the local and global stability of all steady states.

3.1. The Basic Reproduction Number. Biologically, the basic reproduction number denoted $R_0$ represents the average number of new infections generated by each infected person in a population where all individuals are susceptible to infection. We will use the next generation matrix to calculate the basic reproduction number $R_0$ [24]. The necessary matrices denoted by $F$ and $Y$ are given by:

$$
F = \begin{pmatrix}
\beta \alpha (1 - \rho) \frac{\Lambda (d + w_v)}{N^0 d (d + w_v + r_v)} & \beta (1 - \rho) \frac{\Lambda (d + w_v)}{N^0 d (d + w_v + r_v)} & 0 \\
0 & 0 & 0 \\
0 & 0 & 0
\end{pmatrix}
$$

and

$$
Y = \begin{pmatrix}
d + r_s & 0 & 0 \\
-r_s & d + d_0 + r_c & 0 \\
0 & 0 & d + w_v
\end{pmatrix}.
$$

Since, $N^0 = \frac{\Lambda}{d}$. Then, $F = \begin{pmatrix}
\beta (1 - \rho) \alpha (d + w_v) & \beta (1 - \rho) (d + w_v) & 0 \\
0 & 0 & 0 \\
0 & 0 & 0
\end{pmatrix}$

and $Y = \begin{pmatrix}
d + r_s & 0 & 0 \\
-r_s & d + d_0 + r_c & 0 \\
0 & 0 & d + w_v
\end{pmatrix}.

Therefore,

$$
FY^{-1} = \begin{pmatrix}
\frac{\beta (1 - \rho) \alpha (d + w_v)}{(d + r_s)(d + w_v + r_v)} + \frac{\beta (1 - \rho) r_s (d + w_v)}{(d + r_s)(d + w_v + r_v)(d + d_0 + r_c)} & \frac{\beta (1 - \rho) (d + w_v)}{(d + w_v + r_v)(d + d_0 + r_c)} & 0 \\
0 & 0 & 0 \\
0 & 0 & 0
\end{pmatrix}.
$$

The basic reproduction number $R_0$ is obtained as the spectral radius of $FY^{-1}$. Hence, we get the following expression of $R_0$.
\[ R_0 = \frac{\beta (1 - \rho) (d + w_v) (r_s + \alpha (d + d_0 + r_c))}{(d + r_s) (d + w_v + r_v) (d + d_0 + r_c)}, \]
\[ R_0 = R_1 + R_2, \]

where \( R_1 = \frac{\beta (1 - \rho) r_s (d + w_v)}{(d + r_s) (d + w_v + r_v) (d + d_0 + r_c)} \) and \( R_2 = \frac{\beta (1 - \rho) \alpha (d + w_v)}{(d + r_s) (d + w_v + r_v)}. \)

### 3.2. Steady states.

In the next Theorem, the steady states of the COVID-19 epidemic model (1) are given.

**Theorem 3.1.** -The COVID-19 epidemic model (1) has a disease free equilibrium defined by
\[ P^0 = (S^0, L^0, I^0, V^0, R^0) = \left( \frac{\Lambda (d + w_v)}{d (d + w_v + r_v)}, 0, \frac{\Lambda r_s}{d (d + w_v + r_v)}, 0 \right). \]

-If \( R_0 < 1 \), then the COVID-19 epidemic model (1) has endemic equilibrium points given by
\[ P^* = (S^*, L^*, I^*, V^*, R^*), \]
\[
\begin{cases} 
S^* = \frac{\Lambda (d + w_v) M_2}{(d + w_v + r_v) [(R_0 - 1) M_1 + d M_2]}, \\
L^* = \frac{\Lambda (d + l_m) (d + d_0 + r_c) (R_0 - 1)}{(R_0 - 1) M_1 + d M_2}, \\
I^* = \frac{r_s \Lambda (d + l_m) (R_0 - 1)}{(R_0 - 1) M_1 + d M_2}, \\
V^* = \frac{\Lambda r_v M_2}{(d + w_v + r_v) ((R_0 - 1) M_1 + d M_2)}, \\
R^* = \frac{r_s r_c \Lambda (R_0 - 1)}{(R_0 - 1) M_1 + d M_2}, 
\end{cases}
\]

where
\[
M_1 = d (d + l_m) (d + r_c) + dr_s (d + r_c + l_m) + d_0 (d + r_s) (d + l_m),
\]
\[
M_2 = (d + l_m) (d + d_0 + r_c) + r_s (d + r_c + l_m).
\]

### 3.3. Local Stability.

**Theorem 3.2.** The disease-free equilibrium, \( P_0 \) is locally asymptotically stable if \( R_0 < 1 \) and else unstable.
Proof. The Jacobian of model (1) at disease-free equilibrium, 

\[ \mathcal{P}_0 = \left( \frac{\Lambda (d + w_v)}{d (d + w_v + r_v)}, 0, 0, \frac{\Lambda r_v}{d (d + w_v + r_v)}, 0 \right) \]

is,

\[
J(\mathcal{P}_0) = \begin{pmatrix}
-d - r_v & -\beta (1 - \rho) \alpha (d + w_v) & -\beta (1 - \rho) (d + w_v) & w_v & l_m \\
0 & -r_s - d + \frac{\beta (1 - \rho) \alpha (d + w_v)}{d + w_v + r_v} & \frac{\beta (1 - \rho) (d + w_v)}{d + w_v + r_v} & 0 & 0 \\
r_v & 0 & 0 & -d - w_v & 0 \\
0 & 0 & r_c & 0 & -l_m - d
\end{pmatrix},
\]

and the corresponding characteristic polynomial is

\[
P(\xi) = (-\xi - l_m - d)(\xi + d)(\xi + d + w_v + r_v)(a_2 \xi^2 + a_1 \xi + a_0),
\]

where

\[
a_2 = 1,
\]

\[
a_1 = d + d_0 + r_c + (r_s + d) (1 - \mathcal{R}_2),
\]

\[
a_0 = (r_s + d) (d + d_0 + r_c) (d + w_v + r_v) (1 - \mathcal{R}_0).
\]

When \( \mathcal{R}_0 < 1 \), the coefficients \( a_0 \) and \( a_1 \) are positive. By Routh-Hurwitz stability criteria, the disease-free equilibrium is locally asymptotically stable in \( \Omega \). □

Theorem 3.3. The endemic equilibrium \( \mathcal{P}^* \) is locally asymptotically stable when \( \mathcal{R}_0 > 1 \). Moreover, \( \mathcal{P}^* \) is otherwise unstable.

Proof. The Jacobian of system (1) at \( \mathcal{P}^* = (\mathcal{S}, \mathcal{L}, \mathcal{I}, \mathcal{V}, \mathcal{R}_*) \) is

\[
J(\mathcal{P}^*) = \begin{pmatrix}
-p_{11} & -p_{12} & -p_{13} & w_v & l_m \\
-p_{21} & -p_{22} & p_{23} & 0 & 0 \\
r_v & 0 & 0 & -p_{44} & 0 \\
0 & 0 & r_c & 0 & -p_{55}
\end{pmatrix},
\]

where

\[
p_{11} = d + r_v + \lambda, \quad p_{12} = \beta (1 - \rho) \alpha \frac{d \mathcal{I}_0}{\Lambda \mathcal{R}_0},
\]

\[
p_{13} = \beta (1 - \rho) \frac{d \mathcal{I}_0}{\Lambda \mathcal{R}_0}, \quad p_{21} = \lambda, \quad p_{22} = d + r_s - \beta (1 - \rho) \alpha \frac{d \mathcal{I}_0}{\Lambda \mathcal{R}_0}.
\]
\[ p_{23} = \beta (1 - \rho) \frac{d\mathcal{S}_0}{\mathcal{A}_2}, \quad p_{33} = d + d_0 + r_c, \quad p_{44} = d + w_v, \quad p_{55} = d + l_m. \]

The corresponding characteristics equation is given by

\[ P(\zeta) = \zeta^5 + b_4 \zeta^4 + b_3 \zeta^3 + b_2 \zeta^2 + b_1 \zeta + b_0, \]

where

\[ b_4 = \frac{\Lambda (d + r_s) (d + l_m) (d + d_0 + r_c) (\mathcal{R}_0 - 1)}{dM_2 \mathcal{S}_0} + (d + r_s) \left( 1 - \frac{R_2}{\mathcal{R}_0} \right) + (d + d_0 + r_c), \]

\[ b_3 = p_{12} p_{21} + p_{33} p_{44} + (p_{33} + p_{44}) p_{55} + p_{22} (p_{33} + p_{44} + p_{55}) \]

\[ + p_{11} (p_{22} + p_{33} + p_{44} + p_{55}) - (r_s p_{23} + w_v r_v), \]

\[ b_2 = r_s p_{13} p_{21} + p_{22} p_{33} (p_{44} + p_{55}) + p_{44} p_{55} (p_{11} + p_{22}) + p_{12} p_{21} (p_{33} + p_{44} + p_{55}) \]

\[ + p_{11} (p_{33} p_{44} + (p_{33} + p_{44}) p_{55} + p_{22} (p_{33} + p_{44} + p_{55})) - r_s p_{23} (p_{11} + p_{44} + p_{55}) \]

\[ - w_v r_v (p_{22} + p_{33} + p_{55}), \]

\[ b_1 = p_{33} p_{44} p_{55} (p_{11} + p_{22}) + p_{11} p_{55} (p_{22} p_{33} + (p_{22} + p_{33}) p_{44}) \]

\[ + p_{21} (r_s p_{13} (p_{44} + p_{55}) + p_{12} (p_{33} p_{44} + p_{55} (p_{33} + p_{44}))) + r_s w_v r_v p_{23}, \]

\[ - r_s (p_{23} p_{44} p_{55} + p_{11} p_{23} (p_{44} + p_{55}) + l_m r_c p_{21}) - w_v r_v (p_{22} p_{33} - (p_{22} + p_{33}) p_{55}) \]

\[ b_0 = \frac{(d + l_m) (d + w_v) (d + r_s) (d + d_0 + r_c) M_1 (\mathcal{R}_0 - 1)}{dM_2 \mathcal{S}_0}. \]

The coefficients \( b_4, b_3, b_2, b_1, b_0 \) are positive if \( \mathcal{R}_0 > 1 \).

It is obvious to show that the necessary conditions of Routh-Hurwitz stability criteria for degree five polynomial, \( b_4 b_3 b_2 > b_2^2 + b_4^2 b_1 \) and \( (b_4 b_1 - b_0) (b_4 b_3 b_2 - b_2^2 - b_4^2 b_1) > b_0 (b_4 b_3 - b_2)^2 + b_1 b_0^2 \) holds.

Therefore, the \( P^* \) is locally asymptotically stable in \( \Omega \).

\[ \square \]

3.4. Global stability. The following Theorem investigates the global dynamics of disease-free equilibrium, \( \mathcal{P}_0 \), of the COVID-19 epidemic model described in (1).

**Theorem 3.4.** The disease-free equilibrium \( \mathcal{P}_0 \) is global asymptotically stable if \( \mathcal{R}_0 < 1 \), otherwise unstable.
Proof. Consider the Lyapunov function given by
\[
\mathcal{F}_0(\mathcal{L}, \mathcal{I}) = \mathcal{L} + g\mathcal{I}, \text{ where } g = \frac{\beta(1 - \rho) (d + w_v)}{(d + w_v + r_v) (d + d_0 + r_c)}.
\]
Hence, the Lyapunov derivative is
\[
\frac{d\mathcal{F}_0}{dt} = \frac{d\mathcal{L}}{dt} + g \frac{d\mathcal{I}}{dt} = \left[\beta(1 - \rho) (\mathcal{I} + \alpha\mathcal{L}) \frac{\partial}{\partial N} - (d + r_s)\mathcal{L}\right] + g \left[r_s\mathcal{L} - (d + d_0 + r_c)\mathcal{I}\right],
\]
Since,
\[
\mathcal{I}(t) \leq \mathcal{I}_0 = \frac{\Lambda(d + w_v)}{d (d + w_v + r_v)} \text{ and } \frac{\Lambda}{d} \leq N(t) \leq \frac{d + w_v}{d + w_v + r_v}
\]
we have
\[
\frac{d\mathcal{F}_0}{dt} \leq \left[\alpha \frac{d + w_v}{d + w_v + r_v} + gr_s - (d + r_s)\right] \mathcal{L} + \left[\beta(1 - \rho) \frac{d + w_v}{d + w_v + r_v} - (d + d_0 + r_c) g\right] \mathcal{I}.
\]
\[
= \left[\beta(1 - \rho) \alpha \frac{d + w_v}{d + w_v + r_v} + \beta(1 - \rho) \frac{(d + w_v)}{(d + w_v + r_v) (d + d_0 + r_c)} r_s - (d + r_s)\right] \mathcal{L},
\]
\[
+ \left[\beta(1 - \rho) \frac{d + w_v}{d + w_v + r_v} - (d + d_0 + r_c) \frac{\beta(1 - \rho) (d + w_v)}{(d + w_v + r_v) (d + d_0 + r_c)}\right] \mathcal{I}.
\]
\[
= (d + r_s) \left[\beta(1 - \rho) \frac{(d + w_v) (r_s + \alpha(d + d_0 + r_c))}{(d + r_s) (d + w_v + r_v) (d + d_0 + r_c)} - 1\right] \mathcal{L},
\]
\[
= (d + r_s) [\mathcal{R}_0 - 1] \mathcal{L}.
\]
If \( \mathcal{R}_0 < 1 \), then \( \frac{d\mathcal{F}_0}{dt} < 0 \). Therefore, by LaSalle’s Invariance Principle, it follows that the disease-free equilibrium point is globally asymptotically stable in \( \Omega \).

The following Theorem investigates the global dynamics of the endemic equilibrium, \( \mathcal{P}^* \), of the COVID-19 epidemic model described in (1).

**Theorem 3.5.** The endemic equilibrium point is globally asymptotically stable if \( \mathcal{R}_0 > 1 \).

Proof. The appropriate Lyapunov function is defined as
\[
\mathcal{F}^*(\mathcal{L}, \mathcal{I}, \mathcal{V}, \mathcal{R}) = (m_1 \mathcal{V} - m_2 \mathcal{P}_s) \ln \left(\frac{\mathcal{I} + \mathcal{V}}{\mathcal{V} + \mathcal{V}_s}\right) - (\mathcal{L}_s + \mathcal{I}_s + \mathcal{R}_s) \ln \left(\frac{\mathcal{L} + \mathcal{I} + \mathcal{R}}{\mathcal{L}_s + \mathcal{I}_s + \mathcal{R}_s}\right),
\]
where
\[
m_1 = \frac{(d + r_s)(d + w_v + r_v)}{r_v}, \quad m_2 = \frac{\beta(1 - \rho)(r_s + \alpha(d + d_0 + r_c))}{d + d_0 + r_c}.
\]
Therefore
\[
\begin{align*}
\frac{d F^*}{dt} &= \frac{(m_1 Y_s - m_2 I_*)}{J + V} \left( \frac{d J}{dt} + \frac{d V}{dt} \right) - \frac{\mathcal{L} + I_* + R_*}{J + I + R} \left( \frac{d \mathcal{L}}{dt} + \frac{d I}{dt} + \frac{d R}{dt} \right).
\end{align*}
\]

From (6), we have
\[
\begin{align*}
\Lambda (d + r_s) M_2 (1 - R_0) &= \frac{(R_0 - 1) M_1 + d M_2}{(R_0 - 1) M_1 + d M_2},
\end{align*}
\]
by using the system (1) and the fact that \( I(t), \mathcal{L}(t), J(t), V(t), R(t) \) are all non-negative for \( t > 0 \), we get
\[
\begin{align*}
\frac{d J}{dt} + \frac{d V}{dt} &\leq \Lambda + l_m \mathcal{R} \quad \text{and} \quad \frac{d \mathcal{L}}{dt} + \frac{d I}{dt} + \frac{d R}{dt} \leq \beta (1 - \rho) (J + \alpha \mathcal{L}).
\end{align*}
\]

From (8) and (9), we have
\[
\frac{d F^*}{dt} \leq \frac{\Lambda M_2 (1 - R_0)}{(R_0 - 1) M_1 + d M_2} \left( \frac{d + r_s}{\mathcal{J} + V} \left( \Lambda + l_m \mathcal{R} \right) + \frac{1}{\mathcal{L} + I + R} \left( \beta (1 - \rho) (J + \alpha \mathcal{L}) \right) \right).
\]

If \( R_0 > 1 \), we have \( \frac{d F^*}{dt} < 0 \). Therefore, according to LaSalle’s Invariance Principle, the endemic equilibrium point \( F^* \) is globally asymptotically stable in \( \Omega \).

4. Numerical Simulations

In this section, we will perform some numerical simulations in order to check the impact of quarantine and vaccination measures in controlling the spread of the COVID-19. Fig. 2 show the evolution of the exposed and infected individuals for the following parameters: \( \Lambda = 8939, \beta = 0.4114, \alpha = 0.3131, d = 1/(67.7 * 365), r_s = 0.0164, d_0 = 0.022, w_v = 0.0057, r_c = 0.1, l_m = 0.1762 \). In the first case, we ignore the effect of quarantine and take the vaccination baseline, \( \rho = 0, r_v = 0.0380 \), the disease persist and the exposed and infected cases reach a very high level (the blue curve). In the second case, we increase the vaccination rate \( r_v \) by 50 percent from the baseline value, \( \rho = 0, r_v = 0.057 \), we can see that the disease persists with a significant reduction in both exposed and infected individuals (the read curve). Furthermore, in the third and the fourth cases, when the quarantine is maximally implemented simultaneously with population vaccination, the disease dies out and the infected, as well as exposed population, decreases very quickly (the yellow and purple curves).
Figure 2. Impact of quarantine and vaccination strategies on exposed and infected population.
The basic reproduction number $R_0$ is affected by the quarantine effectiveness parameter and can be reduced by increasing quarantine efficacy. As a result, the quarantine strategy is critical in controlling COVID-19 disease. The critical value of quarantine effectiveness in the absence of vaccination of the population is estimated from Fig. (3) by 0.95, which means that the disease can converge to a disease-free state after more than 95 percent of the quarantine. However, when the vaccination strategy is considered, the critical value of quarantine efficiency is estimated from Fig. (3) by 0.31, signifying that the disease can converge to a disease-free state with only more than 31 percent of quarantine in the presence of vaccination.

5. **Conclusion**

In this paper, we have studied the mathematical model illustrating the dynamics of the COVID-19 disease with both vaccination and quarantine strategies. This model includes five equations describing the interaction between susceptible, exposed, infected, vaccinated, and recovered individuals. This study is oriented primarily toward to verify the positiveness and the boundedness of solutions that are established to have the well-posedness of the formulation. Furthermore, we have studied the existence and the stability of both disease-free equilibrium and endemic equilibrium, the Disease-free equilibrium always exists, and it is stable when
$R_0 < 1$ but for the endemic equilibrium point exists and is stable when $R_0 > 1$. Finally, the numerical simulations are carried out in order to show the behavior of the infection over time and to proclaim the effect of the quarantine and vaccination on both the COVID-19 dynamics and the basic reproduction number $R_0$ for controlling the spread of the disease. We have concluded that the combination of quarantine and vaccination policies is the key aspect of infection control related to the spread of the COVID-19 outbreak.

**CONFLICT OF INTERESTS**

The authors declare that there is no conflict of interests.

**REFERENCES**


