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## COMMON FIXED POINT THEOREMS FOR SIX MAPPINGS SATISFYING $\psi$ -WEAKLY CONTRACTIVE CONDITIONS IN $G$ -METRIC SPACE

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**Abstract.** In this paper, we introduce some common fixed point theorems for six mappings satisfying  $\psi$ - and  $(\psi, \varphi)$ -weakly contractive conditions in  $G$ -metric spaces. And we introduce an example to support the validity of our results.

**Keywords:**  $G$ -metric space; common fixed point;  $\psi$ -weakly contractive conditions; weakly compatible mappings

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### 1. Introduction

In 2006, Mustafa and Sims [1] introduced the generalized structure of metric spaces, called  $G$ -metric spaces. Afterwards, numerous fixed point theorems in this generalized structure relative to one, two or three mappings were proved by different authors(see[5-7]). 2015, Zeqing Liu and Xiaoping Zhang et al[8] introduced the existence and uniqueness of common fixed points for four mappings satisfying  $\psi$ - and  $(\psi, \varphi)$ -weakly contractive conditions in metric spaces which was motivated by the results in [9-12]. In this paper, we extended and generalize the

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results in [8] and introduce some common fixed point theorems for six mappings satisfying  $\psi$ - and  $(\psi, \varphi)$ -weakly contractive conditions in  $G$ -metric spaces.

## 2. Previous notations and results

We recall the definitions of  $G$ -metric space, the notion of convergence and other results that will be needed in the sequel.

**Definition 2.1**<sup>[1]</sup> Let  $X$  be a nonempty set. Suppose that  $G: X \times X \times X \rightarrow [0, +\infty)$  is a function satisfying the following conditions:

(G1)  $G(x, y, z) = 0$  if and only if  $x = y = z$ ;

(G2)  $0 < G(x, x, y)$  for all  $x, y \in X$  with  $x \neq y$ ;

(G3)  $G(x, x, y) \leq G(x, y, z)$  for all  $x, y, z \in X$  with  $y \neq z$ ;

(G4)  $G(x, y, z) = G(x, z, y) = G(y, z, x) = \dots$  (symmetry in all three variables);

(G5)  $G(x, y, z) \leq G(x, a, a) + G(a, y, z)$  for all  $x, y, z, a \in X$  (rectangle inequality).

Then  $G$  is called a  $G$ -metric on  $X$  and  $(X, G)$  is called a  $G$ -metric space.

This notion of  $G$ -metric was introduced by Mustafa and Sims [1] in 2006. It can be shown that if  $(X, d)$  is a metric space one can define  $G$ -metric on  $X$  by

$$G(x, y, z) = \max\{d(x, y), d(y, z), d(z, x)\} \text{ or } G(x, y, z) = d(x, y) + d(y, z) + d(z, x).$$

**Definition 2.2**<sup>[1]</sup> Let  $(X, G)$  be a  $G$ -metric space and  $\{x_n\}$  be a sequence in  $X$ . We say that  $\{x_n\}$  is  $G$ -convergent to a point  $x \in X$  or  $\{x_n\}$   $G$ -converges to  $x$  if, for any  $\varepsilon > 0$ , there exists  $k \in \mathbb{N}$  such that  $G(x, x_n, x_m) < \varepsilon$  for all  $m, n \geq k$ , that is,  $\lim_{n, m \rightarrow +\infty} G(x, x_n, x_m) = 0$ . In this case, we write  $x_n \rightarrow x (n \rightarrow \infty)$  or  $\lim_{n \rightarrow +\infty} x_n = x$ .

**Proposition 2.1**<sup>[1]</sup> Let  $(X, G)$  be a  $G$ -metric space. The following are equivalent:

- (1)  $\{x_n\}$  is  $G$ -convergent to  $x$ ;
- (2)  $G(x_n, x_n, x) \rightarrow 0$  as  $n \rightarrow +\infty$ ;
- (3)  $G(x_n, x, x) \rightarrow 0$  as  $n \rightarrow +\infty$ ;
- (4)  $G(x_n, x_m, x) \rightarrow 0$  as  $n, m \rightarrow +\infty$ .

**Definition 2.3**<sup>[1]</sup> Let  $(X, G)$  be a  $G$ -metric space and  $\{x_n\}$  be a sequence in  $X$ . We say that

$\{x_n\}$  is a  $G$ -Cauchy sequence if, for any  $\varepsilon > 0$ , there exists  $k \in \mathbb{N}$  such that  $G(x_n, x_m, x_l)$  for all  $m, n, l \geq k$ , that is,  $G(x_n, x_m, x_l) \rightarrow 0$  as  $n, m, l \rightarrow +\infty$ .

**Proposition 2.2**<sup>[1]</sup> Let  $(X, G)$  be a  $G$ -metric space. Then the following are equivalent:

- (1) The sequence  $\{x_n\}$  is a  $G$ -Cauchy sequence.
- (2) For any  $\varepsilon > 0$ , there exists  $k \in \mathbb{N}$  such that  $G(x_n, x_m, x_m) < \varepsilon$  for all  $m, n \geq k$ .

**Proposition 2.3**<sup>[1]</sup> Let  $(X, G)$  be a  $G$ -metric space. Then,  $f: X \rightarrow X$  is  $G$ -continuous at  $x \in X$  if and only if it is  $G$ -sequentially continuous at  $x$ , that is, whenever  $\{x_n\}$  is  $G$ -convergent to  $x$ ,  $\{f(x_n)\}$  is  $G$ -convergent to  $f(x)$ .

**Definition 2.4**<sup>[1]</sup> A  $G$ -metric space  $(X, G)$  is called  $G$ -complete if every  $G$ -cauchy sequence is  $G$ -convergent in  $(X, G)$ .

**Definition 2.5**<sup>[2]</sup> Let  $(X, G)$  be a  $G$ -metric space. A mapping  $F: X \times X \rightarrow X$  is said to be continuous if for any two  $G$ -convergent sequence  $\{x_n\}$  and  $\{y_n\}$  converging to  $x$  and  $y$  respectively,  $(F(x_n, y_n))$  is  $G$ -convergent to  $F(x, y)$ .

**Definition 2.6**<sup>[3]</sup> A pair of self mappings  $f$  and  $g$  in a metric space  $(X, d)$  are said to be weakly compatible if for all  $t \in X$  the equality  $ft = gt$  implies  $fgt = gft$ .

Throughout this paper,  $\mathbb{N}$  denotes the set of all positive integers,  $\mathbb{R}^+ = [0, +\infty)$ ,  $M(x, y, z) = \max\{G(Ax, By, Cz), G(Ax, Ax, Tx), G(By, By, Sy), G(Cz, Cz, Hz),$

$\frac{1}{2}[G(Ax, By, Cz) + G(Tx, Sy, Hz)]\}$  and

$\Phi_1 = \{\psi: \mathbb{R}^+ \rightarrow \mathbb{R}^+$  is continuous and nondecreasing, and  $\psi(t) = 0$  if and only if  $t = 0\}$ ,

$\Phi_2 = \{\varphi: \mathbb{R}^+ \rightarrow \mathbb{R}^+$  is lower semi-continuous, and  $\varphi(t) = 0$  if and only if  $t = 0\}$ ,

$\Phi_3 = \{\psi: \mathbb{R}^+ \rightarrow \mathbb{R}^+$  is upper semi-continuous, and  $\lim_{n \rightarrow \infty} a_n = 0$  for each sequence  $\{a_n\}_{n \in \mathbb{N}} \subset \mathbb{R}^+$  with  $a_{n+1} \leq \psi(a_n), \forall n \in \mathbb{N}\}$ .

**Lemma 2.1**<sup>[4]</sup> Let  $\psi \in \Phi_3$ . Then  $\psi(0) = 0$  and  $\psi(t) < t$  for all  $t > 0$ .

### 3. Main results

Our main results are as follows.

**Lemma 3.1** Let  $A, B, C, S, T$  and  $H$  be self mappings in a  $G$ -metric space  $(X, G)$  satisfying

$$\psi(G(Tx, Sy, Hz)) \leq \psi(M(x, y, z)) - \varphi(M(x, y, z)), \quad (3.1)$$

where  $(\psi, \varphi) \in \Phi_1 \times \Phi_2$ . Assume that  $I: \mathbb{R}^+ \rightarrow \mathbb{R}^+$  is the identity mapping and

$$\psi_1(t) = (\psi + I)^{-1}(\psi + I - \varphi)(t), \quad \forall t \in \mathbb{R}^+. \quad (3.2)$$

Then  $\psi_1 \in \Phi_3$  and

$$G(Tx, Sy, Hz) \leq \psi_1(M(x, y, z)), \quad \forall x, y, z \in X. \quad (3.3)$$

**Proof**

It follows from  $\psi \in \Phi_1$  that  $\psi + I: \mathbb{R}^+ \rightarrow \mathbb{R}^+$  is continuous and increasing and  $(\psi + I)(t) = 0$  if and only if  $t = 0$ . So does  $(\psi + I)^{-1}$ . Obviously,  $(\psi, \varphi) \in \Phi_1 \times \Phi_2$  and (3.2) guarantee

$$\psi_1 \text{ is upper semi-continuous and } \psi_1(0) = 0. \quad (3.4)$$

Assume that  $\{a_n\}_{n \in \mathbb{N}}$  is an arbitrary sequence in  $\mathbb{R}^+$  with

$$a_{n+1} \leq \psi_1(a_n), \quad \forall n \in \mathbb{N}. \quad (3.5)$$

Suppose that  $a_{n_0} = 0$  for some  $n_0 \in \mathbb{N}$ . It follows from (3.2), (3.4) and (3.5) that

$$0 \leq a_{n_0+1} \leq \psi_1(a_{n_0}) = \psi_1(0) = 0,$$

that is,  $a_{n_0+1} = 0$ . Similarly we have  $a_n = a_{n-1} = \dots = a_{n_0} = 0$  for each  $n > n_0$ , that is,  $\lim_{n \rightarrow \infty} a_n = 0$ . Suppose that  $a_n > 0$  for all  $n \in \mathbb{N}$ . If  $a_{k+1} \geq a_k$  for some  $k \in \mathbb{N}$ , it follows from

(3.2), (3.5) and  $(\psi, \varphi) \in \Phi_1 \times \Phi_2$  that

$$\begin{aligned} \psi(a_k) + a_k &\leq \psi(a_{k+1}) + a_{k+1} = (\psi + I)(a_{k+1}) \leq (\psi + I)\psi_1(a_k) \\ &= (\psi + I - \varphi)(a_k) \\ &= \psi(a_k) + a_k - \varphi(a_k) < \psi(a_k) + a_k \end{aligned}$$

which is a contradiction. Consequently,  $\{a_n\}_{n \in \mathbb{N}}$  is a positive and decreasing, which implies that  $\{a_n\}_{n \in \mathbb{N}}$  converges to some  $a \geq 0$ . Suppose that  $a > 0$ . By means of (3.4) and (3.5), we find

$$0 < a = \limsup_{n \rightarrow \infty} a_{n+1} \leq \limsup_{n \rightarrow \infty} \psi_1(a_n) \leq \psi_1(a),$$

which together with (3.2) and  $(\psi, \varphi) \in \Phi_1 \times \Phi_2$  means

$$\psi(a) + a \leq \psi(a) + a - \varphi(a) < \psi(a) + a,$$

which is a contradiction. Hence  $a = 0$ . Consequently,  $\psi_1 \in \Phi_3$ .

In order to prove (3.3), we have to consider two possible cases as follows:

Case 1.  $M(x_0, y_0, z_0) = 0$  for some  $x_0, y_0, z_0 \in X$ . It is easy to verify

$$\begin{aligned} G(Ax_0, By_0, Cz_0) &= G(Ax_0, Ax_0, Tx_0) = G(By_0, By_0, Sy_0) \\ &= G(Cz_0, Cz_0, Hz_0) = G(Tx_0, Sy_0, Hz_0), \end{aligned}$$

which yields

$$Ax_0 = Tx_0 = By_0 = Sy_0 = Cz_0 = Hz_0$$

and

$$G(Tx_0, Sy_0, Hz_0) = \psi_1(M(x_0, y_0, z_0));$$

Case 2.  $M(x, y, z) > 0$  for all  $x, y, z \in X$ . It follows from (3.1), (3.2) and  $(\psi, \varphi) \in \Phi_1 \times \Phi_2$  that

$$\psi(G(Tx, Sy, Hz)) \leq \psi(M(x, y, z)) - \varphi(M(x, y, z)) < \psi(M(x, y, z)), \quad \forall x, y, z \in X,$$

which yields

$$G(Tx, Sy, Hz) < M(x, y, z), \quad \forall x, y, z \in X,$$

and

$$\begin{aligned}
 (\psi + I)(G(Tx, Sy, Hz)) &= \psi(G(Tx, Sy, Hz)) + G(Tx, Sy, Hz) \\
 &< \psi(M(x, y, z)) - \varphi(M(x, y, z)) + M(x, y, z) \\
 &= (\psi + I - \varphi)(M(x, y, z)), \quad \forall x, y, z \in X,
 \end{aligned}$$

which together with (3.2) gives (3.3). This completes the proof.

**Remark 3.1** It follows from Lemma 3.1 that the  $(\psi, \varphi)$ -weakly contractive conditions (3.1) relative to six mappings  $A, B, C, S, T$  and  $H$  implies the  $\psi_1$ -weakly contractive conditions (3.3) relative to six mappings  $A, B, C, S, T$  and  $H$ .

**Theorem 3.1** Let  $A, B, C, S, T$  and  $H$  be self mappings in a  $G$ -metric space  $(X, G)$  such that:

$$\{A, T\}, \{B, S\} \text{ and } \{C, H\} \text{ are weakly compatible;} \quad (3.6)$$

$$T(X) \subseteq B(X), S(X) \subseteq C(X) \text{ and } H(X) \subseteq A(X); \quad (3.7)$$

$$\text{one of } A(X), B(X), C(X), S(X), T(X) \text{ and } H(X) \text{ is complete;} \quad (3.8)$$

$$G(Tx, Sy, Hz) \leq \psi(M(x, y, z)), \forall x, y, z \in X, \quad (3.9)$$

Where  $\psi$  is in  $\Phi_3$ .

Then  $A, B, C, S, T$  and  $H$  have a unique common fixed point in  $X$ .

**Proof**

Let  $x_0 \in X$ . It follows from (3.7) that there exist two sequence  $\{y_n\}_{n \in \mathbb{N}}$  and  $\{x_n\}_{n \in \mathbb{N}}$  in  $X$  such that

$$\begin{aligned}
 y_{3n+1} &:= Bx_{3n+1} = Tx_{3n}, \\
 y_{3n+2} &:= Cx_{3n+2} = Sx_{3n+1}, \\
 y_{3n+3} &:= Ax_{3n+3} = Hx_{3n+2}.
 \end{aligned} \quad (3.10)$$

Put  $G_n = G(y_n, y_{n+1}, y_{n+2})$  for all  $n \in \mathbb{N}$ . Now we prove

$$\lim_{n \rightarrow \infty} G_n = 0 \quad (3.11)$$

$$G_{3n} = G(Tx_{3n}, Sx_{3n+1}, Hx_{3n-1}) \leq \psi(M(x_{3n}, x_{3n+1}, x_{3n-1})), \forall n \in \mathbb{N} \quad (3.12)$$

and

$$\begin{aligned} & M(x_{3n}, x_{3n+1}, x_{3n-1}) \\ = & \max\{G(Ax_{3n}, Bx_{3n+1}, Cx_{3n-1}), G(Ax_{3n}, Ax_{3n}, Tx_{3n}), \\ & G(Bx_{3n+1}, Bx_{3n+1}, Sx_{3n+1}), G(Cx_{3n-1}, Cx_{3n-1}, Hx_{3n-1}), \\ & \frac{1}{2}[G(Ax_{3n}, Bx_{3n+1}, Cx_{3n-1}) + G(Tx_{3n}, Sx_{3n+1}, Hx_{3n-1})]\} \\ = & \max\{G(y_{3n}, y_{3n+1}, y_{3n-1}), G(y_{3n}, y_{3n}, y_{3n+1}), \\ & G(y_{3n+1}, y_{3n+1}, y_{3n+2}), G(y_{3n-1}, y_{3n-1}, y_{3n}), \\ & \frac{1}{2}(G(y_{3n}, y_{3n+1}, y_{3n-1}) + G(y_{3n+1}, y_{3n+2}, y_{3n}))\} \\ = & \max\{G_{3n-1}, G(y_{3n}, y_{3n}, y_{3n+1}), G(y_{3n+1}, y_{3n+1}, y_{3n+2}), \\ & G(y_{3n-1}, y_{3n-1}, y_{3n}), \frac{1}{2}(G_{3n-1} + G_{3n})\} \\ \leq & \max\{G_{3n-1}, G_{3n}, \frac{1}{2}(G_{3n-1} + G_{3n})\} \\ = & \max\{G_{3n-1}, G_{3n}\}, \quad \forall n \in \mathbb{N} \end{aligned} \quad (3.13)$$

Suppose that  $G_{3n_0-1} < G_{3n_0}$  for some  $n_0 \in \mathbb{N}$ . It follows (3.9), (3.13) and Lemma 2.1 that

$$\begin{aligned} & G_{3n_0} \leq \psi(M(x_{3n_0}, x_{3n_0+1}, x_{3n_0-1})) \\ \leq & \psi(\max\{G_{3n_0-1}, G_{3n_0}\}) = \psi(G_{3n_0}) < G_{3n_0}, \end{aligned}$$

which is a contradiction. Hence

$$G_{3n} \leq G_{3n-1}, \quad \forall n \in \mathbb{N}. \quad (3.14)$$

Similarly we infer

$$G_{3n+1} \leq G_{3n}, \quad \forall n \in \mathbb{N}. \quad (3.15)$$

and

$$G_{3n+2} \leq G_{3n+1}, \quad \forall n \in \mathbb{N}. \quad (3.16)$$

From (3.14), (3.15) and (3.16) we have

$$G_{n+1} \leq G_n, \quad \forall n \in \mathbb{N},$$

which means that the sequence  $\{G_n\}_{n \in \mathbb{N}}$  is nonincreasing and bounded. consequently there exists  $r \geq 0$  with  $\lim_{n \rightarrow \infty} G_n = r$ . Suppose that  $r > 0$ . It follows from (3.9), (3.14),  $\psi \in \Phi_3$ , and Lemma 2.1 that

$$\begin{aligned} r &= \limsup_{n \rightarrow \infty} G_{3n} \leq \limsup_{n \rightarrow \infty} \psi(M(x_{3n}, x_{3n+1}, x_{3n-1})) \\ &\leq \limsup_{n \rightarrow \infty} \psi(G_{3n-1}) \leq \psi(r) < r, \end{aligned}$$

which is a contradiction. Hence  $r = 0$ , that is, (3.11) holds.

Next we prove that  $\{y_n\}_{n \in \mathbb{N}}$  is a cauchy sequence. Because of (3.11) it is sufficient to verify that  $\{y_{3n}\}_{n \in \mathbb{N}}$  is a cauchy sequence. Suppose to the contrary: that is,  $\{y_{3n}\}$  is not a cauchy sequence. Then there exists  $\varepsilon > 0$  for which we can find subsequence  $\{y_{3m_k}\}$  and  $\{y_{3n_k}\}$  of  $\{y_{3n}\}$  such that  $m_k$  is the smallest index for which  $3m_k > 3n_k > k$ , and

$$G(y_{3n_k}, y_{3m_k}, y_{3m_k}) \geq \varepsilon \quad (3.17)$$

This means that



$$G(y_{3n_k}, y_{3m_k-3}, y_{3m_k-3}) < \varepsilon \quad (3.18)$$

Taking advantage of (3.17), (3.18), and (G3)-(G5), we get

$$\begin{aligned} \varepsilon &\leq G(y_{3n_k}, y_{3m_k}, y_{3m_k}) \\ &\leq G(y_{3n_k}, y_{3m_k-3}, y_{3m_k-3}) + G(y_{3m_k-3}, y_{3m_k}, y_{3m_k}) \\ &\leq G(y_{3n_k}, y_{3m_k-3}, y_{3m_k-3}) + G(y_{3m_k-3}, y_{3m_k-2}, y_{3m_k-2}) \\ &\quad + G(y_{3m_k-2}, y_{3m_k}, y_{3m_k}) \\ &\leq G(y_{3n_k}, y_{3m_k-3}, y_{3m_k-3}) + G(y_{3m_k-3}, y_{3m_k-1}, y_{3m_k-2}) \\ &\quad + G(y_{3m_k-2}, y_{3m_k-1}, y_{3m_k}) \\ &< \varepsilon + G_{3m_k-3} + G_{3m_k-2} \end{aligned} \quad (3.19)$$

and

$$\begin{aligned} |G(y_{3m_k+1}, y_{3m_k+2}, y_{3n_k}) - G(y_{3m_k}, y_{3m_k}, y_{3n_k})| &\leq 2G_{3m_k}, \\ |G(y_{3m_k}, y_{3m_k+1}, y_{3n_k-1}) - G(y_{3m_k+1}, y_{3m_k+2}, y_{3n_k})| &\leq G_{3m_k} + G_{3n_k-1}; \end{aligned} \quad (3.20)$$

Letting  $k \rightarrow \infty$  in (3.19) and (3.20) and using (3.11), we have

$$\begin{aligned} \lim_{k \rightarrow \infty} G(y_{3m_k}, y_{3m_k}, y_{3n_k}) &= \lim_{k \rightarrow \infty} G(y_{3m_k+1}, y_{3m_k+2}, y_{3n_k}) \\ &= \lim_{k \rightarrow \infty} G(y_{3m_k}, y_{3m_k+1}, y_{3n_k-1}) = \varepsilon \end{aligned}$$

And also, from (3.9) and (3.10) we have

$$\begin{aligned} &G(y_{3m_k+1}, y_{3m_k+2}, y_{3n_k}) \\ &= G(Tx_{3m_k}, Sx_{3m_k+1}, Hx_{3n_k-1}) \\ &\leq \psi(M(x_{3m_k}, x_{3m_k+1}, x_{3n_k-1})), \end{aligned}$$

where

$$\begin{aligned}
& M(x_{3m_k}, x_{3m_k+1}, x_{3n_k-1}) \\
= & \max\{G(Ax_{3m_k}, Bx_{3m_k+1}, Cx_{3n_k-1}), G(Ax_{3m_k}, Ax_{3m_k}, Tx_{3m_k}), \\
& G(Bx_{3m_k+1}, Bx_{3m_k+1}, Sx_{3m_k+1}), G(Cx_{3n_k-1}, Cx_{3n_k-1}, Hx_{3n_k-1}), \\
& \frac{1}{2}[G(Ax_{3m_k}, Bx_{3m_k+1}, Cx_{3n_k-1}) + G(Tx_{3m_k}, Sx_{3m_k+1}, Hx_{3n_k-1})]\} \\
= & \max\{G(y_{3m_k}, y_{3m_k+1}, y_{3n_k-1}), G(y_{3m_k}, y_{3m_k}, y_{3m_k+1}), \\
& G(y_{3m_k+1}, y_{3m_k+1}, y_{3m_k+2}), G(y_{3n_k-1}, y_{3n_k-1}, y_{3n_k}), \\
& \frac{1}{2}[G(y_{3m_k}, y_{3m_k+1}, y_{3n_k-1}) + G(y_{3m_k+1}, y_{3m_k+2}, y_{3n_k})]\} \\
& \rightarrow \max\{\varepsilon, 0, 0, 0, \varepsilon\} \\
= & \varepsilon \quad \text{as } k \rightarrow \infty. \tag{3.21}
\end{aligned}$$

In view of (3.9), (3.10), (3.21),  $\psi \in \Phi_3$  and Lemma 2.1, we gain

$$\begin{aligned}
\varepsilon & = \limsup_{k \rightarrow \infty} G(y_{3m_k+1}, y_{3m_k+2}, y_{3n_k}) = \limsup_{k \rightarrow \infty} G(Tx_{3m_k}, Sx_{3m_k+1}, Hx_{3n_k-1}) \\
& \leq \limsup_{k \rightarrow \infty} \psi(M(x_{3m_k}, x_{3m_k+1}, x_{3n_k-1})) \leq \psi(\varepsilon) < \varepsilon,
\end{aligned}$$

which is a contradiction. Hence  $\{y_n\}_{n \in \mathbb{N}}$  is a Cauchy sequence.

Assume that  $A(X)$  is complete. Observe that  $\{y_{3n}\}_{n \in \mathbb{N}}$  is a Cauchy sequence in  $A(X)$ . Consequently there exists  $(z, v) \in A(X) \times X$  with  $\lim_{n \rightarrow \infty} y_{3n+3} = z = Av$ . It is easy to see

$$\begin{aligned}
z & = \lim_{n \rightarrow \infty} y_n = \lim_{n \rightarrow \infty} Bx_{3n+1} = \lim_{n \rightarrow \infty} Tx_{3n} = \lim_{n \rightarrow \infty} Cx_{3n+2} \\
& = \lim_{n \rightarrow \infty} Sx_{3n+1} = \lim_{n \rightarrow \infty} Hx_{3n+2} = \lim_{n \rightarrow \infty} Ax_{3n+3} = Av. \tag{3.22}
\end{aligned}$$

Suppose that  $Tv \neq z$ . From (3.22) we have

$$\begin{aligned}
& M(v, x_{3n+1}, x_{3n+2}) \\
= & \max\{G(Av, Bx_{3n+1}, Cx_{3n+2}), G(Av, Av, Tv), \\
& G(Bx_{3n+1}, Bx_{3n+1}, Sx_{3n+1}), G(Cx_{3n+2}, Cx_{3n+2}, Hx_{3n+2}), \\
& \frac{1}{2}[G(Av, Bx_{3n+1}, Cx_{3n+2}) + G(Tv, Sx_{3n+1}, Hx_{3n+2})]\} \\
= & \max\{G(z, y_{3n+1}, y_{3n+2}), G(z, z, Tv), G(y_{3n+1}, y_{3n+1}, y_{3n+2}), \\
& G(y_{3n+2}, y_{3n+2}, y_{3n+3}), \frac{1}{2}[G(z, y_{3n+1}, y_{3n+2}) + G(Tv, y_{3n+2}, y_{3n+3})]\} \\
\rightarrow & \max\{G(z, z, z), G(z, z, Tv), G(z, z, z), \\
& G(z, z, z), \frac{1}{2}[G(z, z, z) + G(Tv, z, z)]\} \\
= & \max\{0, G(z, z, Tv), 0, 0, \frac{1}{2}G(z, z, Tv)\} \\
= & G(z, z, Tv) \quad \text{as } n \rightarrow \infty,
\end{aligned}$$

which together with (3.9),  $\psi \in \Phi_3$ , and Lemma 2.1 yields

$$\begin{aligned}
G(Tv, z, z) &= \limsup_{n \rightarrow \infty} G(Tv, y_{3n+2}, y_{3n+3}) = \limsup_{n \rightarrow \infty} G(Tv, Sx_{3n+1}, Hx_{3n+2}) \\
&\leq \limsup_{n \rightarrow \infty} \psi(M(v, x_{3n+1}, x_{3n+2})) \leq \psi(G(Tv, z, z)) < G(Tv, z, z),
\end{aligned}$$

which is a contradiction. Hence  $Tv = z$ . It follows from (3.7) that there exists a point  $w \in X$  with  $z = Bw = Tv$ . Suppose that  $Sw \neq z$ . In light of (3.22), we deduce

$$\begin{aligned}
& M(x_{3n}, w, x_{3n+2}) \\
= & \max\{G(Ax_{3n}, Bw, Cx_{3n+2}), G(Ax_{3n}, Ax_{3n}, Tx_{3n}), \\
& G(Bw, Bw, Sw), G(Cx_{3n+2}, Cx_{3n+2}, Hx_{3n+2}) \\
& \frac{1}{2}[G(Ax_{3n}, Bw, Cx_{3n+2}) + G(Tx_{3n}, Sw, Hx_{3n+2})]\} \\
\rightarrow & \max\{G(z, z, z), G(z, z, z), G(z, z, Sw), G(z, z, z) \\
& \frac{1}{2}[G(z, z, z) + G(z, Sw, z)]\}
\end{aligned}$$

(1)

$$\begin{aligned}
&= \max\{0, 0, G(z, z, Sw), 0, \frac{1}{2}G(z, z, Sw)\} \\
&= G(z, z, Sw) \quad \text{as } n \rightarrow \infty,
\end{aligned}$$

which together with (3.9), (3.10), (3.22),  $\psi \in \Phi_3$ , and Lemma 2.1 yields

$$\begin{aligned}
G(z, Sw, z) &= \limsup_{n \rightarrow \infty} G(y_{3n+1}, Sw, y_{3n+3}) = \limsup_{n \rightarrow \infty} G(Tx_{3n}, Sw, Hx_{3n+2}) \\
&\leq \limsup_{n \rightarrow \infty} \psi(M(x_{3n}, w, x_{3n+2})) \leq \psi(G(z, z, Sw)) < G(z, z, Sw),
\end{aligned}$$

which is a contradiction, and hence  $Sw = z$ . It follows from (3.7) that there exists a point  $u \in z$  with  $z = Cu = Sw$ . Suppose that  $Hu \neq z$ . In light of (3.22), we deduce

$$\begin{aligned}
&M(x_{3n}, x_{3n+1}, u) \\
&= \max\{G(Ax_{3n}, Bx_{3n+1}, Cu), G(Ax_{3n}, Ax_{3n}, Tx_{3n}), \\
&\quad G(Bx_{3n+1}, Bx_{3n+1}, Sx_{3n+1}), G(Cu, Cu, Hu)\} \\
&\quad \frac{1}{2}[G(Ax_{3n}, Bx_{3n+1}, Cu) + G(Tx_{3n}, Sx_{3n+1}, Hu)] \\
&\rightarrow \max\{G(z, z, z), G(z, z, z), G(z, z, z), G(z, z, Hu)\} \\
&\quad \frac{1}{2}[G(z, z, z) + G(z, z, Hu)] \\
&= \max\{0, 0, 0, G(z, z, Hu), \frac{1}{2}G(z, z, Hu)\} \\
&= G(z, z, Hu) \quad \text{as } n \rightarrow \infty,
\end{aligned}$$

which together with (3.9), (3.10), (3.22),  $\psi \in \Phi_3$ , and Lemma 2.1 yields

$$\begin{aligned}
G(z, z, Hu) &= \limsup_{n \rightarrow \infty} G(y_{3n+1}, y_{3n+2}, Hu) = \limsup_{n \rightarrow \infty} G(Tx_{3n}, Sx_{3n+1}, Hu) \\
&\leq \limsup_{n \rightarrow \infty} \psi(M(x_{3n}, x_{3n+1}, u)) \leq \psi(G(z, z, Hu)) < G(z, z, Hu),
\end{aligned}$$

which is impossible, and hence  $Hu = z$ . Thus (3.6) means  $Az = ATv = TAv = Tz$ ,  $Bz = BSw = Sz$  and  $Cz = CHu = HCu = Hz$ . Suppose that  $G(Tz, Sz, Hz) \neq 0$ . Then we have

$$\begin{aligned}
& M(z, z, z) \\
&= \max\{G(Az, Bz, Cz), G(Az, Az, Tz), G(Bz, Bz, Sz), \\
&\quad G(Cz, Cz, Hz), \frac{1}{2}[G(Az, Bz, Cz) + G(Tz, Sz, Hz)]\} \\
&= \max\{G(Tz, Sz, Hz), 0, 0, 0, G(Tz, Sz, Hz)\} \\
&= G(Tz, Sz, Hz),
\end{aligned}$$

which together with (3.9),  $\psi \in \Phi_3$ , and Lemma 2.1 yields

$$G(Tz, Sz, Hz) \leq \psi(M(z, z, z)) = \psi(G(Tz, Sz, Hz)) < G(Tz, Sz, Hz),$$

which is impossible, and hence  $G(Tz, Sz, Hz) = 0$ . So  $Tz = Sz = Hz$ . Suppose that  $Tz \neq z$ . Then we have

$$\begin{aligned}
& M(z, w, u) \\
&= \max\{G(Az, Bw, Cu), G(Az, Az, Tz), G(Bw, Bw, Sw), \\
&\quad G(Cu, Cu, Hu), \frac{1}{2}[G(Az, Bw, Cu) + G(Tz, Sw, Hu)]\} \\
&= \max\{G(Tz, Sw, Hu), 0, 0, 0, G(Tz, Sw, Hu)\} \\
&= G(Tz, Sw, Hu) \\
&= G(Tz, z, z),
\end{aligned}$$

which together with (3.9),  $\psi \in \Phi_3$ , and Lemma 2.1 implies

$$G(Tz, z, z) = G(Tz, Sw, Hu) \leq \psi(M(z, w, u)) = \psi(G(Tz, z, z)) < G(Tz, z, z),$$

which is impossible and hence  $Tz = z$ , that is,  $z$  is a common fixed point of  $A, B, C, S, T$  and  $H$ . Suppose that  $A, B, C, S, T$  and  $H$  have another common fixed point  $u \in X \setminus \{z\}$ . Then we have

$$\begin{aligned} & M(z, z, u) \\ &= \max\{G(Az, Bz, Cu), G(Az, Az, Tz), G(Bz, Bz, Sz), \\ & \quad G(Cu, Cu, Hu), \frac{1}{2}[G(Az, Bz, Cu) + G(Tz, Sz, Hu)]\} \\ &= \max\{G(z, z, u), 0, 0, 0, G(z, z, u)\} \\ &= G(z, z, u), \end{aligned}$$

and

$$G(z, z, u) = G(Tz, Sz, Hu) \leq \psi(M(z, z, u)) = \psi(G(z, z, u)) < G(z, z, u),$$

which is a contradiction and hence  $z$  is a unique common fixed point of  $A, B, C, S, T$  and  $H$  in  $X$ .

Similarly we conclude that  $A, B, C, S, T$  and  $H$  have a unique common fixed point in  $X$  if one of  $B(X), C(X), S(X), T(X)$  and  $H(X)$  is complete. Then the proof is complete.

Utilizing Theorems 3.1 and Remark 3.1, we get the following results.

**Theorem 3.2** Let  $A, B, C, S, T$  and  $H$  be self mappings in a  $G$ -metric space  $(X, G)$  satisfying (3.6)-(3.8) and

$$\psi(G(Tx, Sy, Hz)) \leq \psi(M(x, y, z)) - \varphi(M(x, y, z)), \quad \forall x, y, z \in X,$$

where  $(\psi, \varphi)$  is in  $\Phi_1 \times \Phi_2$ . Then  $A, B, C, S, T$  and  $H$  have a unique common fixed point in  $X$ .

**Example 3.1** Let  $X = [0, 1]$  be endowed with the Euclidean  $G$ -metric

$$G(x, y, z) = \begin{cases} 0 & x = y = z; \\ \max\{x, y, z\} & \text{else.} \end{cases}$$

Let  $A, B, C, S, T, H: X \rightarrow X$  be defined by  $Ax = 2x$ ,  $Bx = x$ ,  $Cx = x^2$ ,  $Sx = 0$ ,

$$Tx = \begin{cases} 0 & \forall x \in X \setminus \{\frac{1}{2}\}; \\ \frac{1}{2} & x = \frac{1}{2}. \end{cases}$$

$$Hx = \begin{cases} 0 & \forall x \in X \setminus \{\frac{1}{2}\}; \\ \frac{1}{6} & x = \frac{1}{2}. \end{cases}$$

And define  $\psi: \mathbb{R}^+ \rightarrow \mathbb{R}^+$  by:

$$\psi(t) = \frac{2}{3}t.$$

It is easy to verify that (3.6)-(3.8) holds and  $\psi \in \Phi_3$ . Put  $x, y, z \in X$ , in order to verify (3.9), we consider four cases as follows:

Case 1.  $x \in X \setminus \{\frac{1}{2}\}$ ,  $z \in X \setminus \{\frac{1}{2}\}$ . It is clear that

$$G(Tx, Sy, Hz) = 0 \leq \psi(M(x, y, z));$$

Case 2.  $x \in X \setminus \{\frac{1}{2}\}$ ,  $z = \frac{1}{2}$ . Clearly we have

$$\begin{aligned} & M(x, y, z) \\ &= \max\{G(Ax, By, Cz), G(Ax, Ax, Tx), G(By, By, Sy), G(Cz, Cz, Hz), \\ & \quad \frac{1}{2}[G(Ax, By, Cz) + G(Tx, Sy, Hz)]\} \\ &\geq G(Cz, Cz, Hz) = \frac{1}{4} \end{aligned}$$

It follows that

$$\psi(M(x, y, z)) \geq \frac{2}{3} \times \frac{1}{4} = \frac{1}{6},$$

$$G(Tx, Sy, Hz) = \frac{1}{6} \leq \psi(M(x, y, z)).$$

Case 3.  $x = \frac{1}{2}$ ,  $z \in X \setminus \{\frac{1}{2}\}$ . It is clear that

$$\begin{aligned} & M(x, y, z) \\ &= \max\{G(Ax, By, Cz), G(Ax, Ax, Tx), G(By, By, Sy), G(Cz, Cz, Hz), \\ &\quad \frac{1}{2}[G(Ax, By, Cz) + G(Tx, Sy, Hz)]\} \\ &\geq G(Ax, Ax, Tx) = 1 \end{aligned}$$

It follows that

$$\begin{aligned} \psi(M(x, y, z)) &= \frac{2}{3} \times 1 \geq \frac{2}{3} \\ G(Tx, Sy, Hz) &= \frac{1}{2} < \frac{2}{3} \leq \psi(M(x, y, z)) \end{aligned}$$

Case 4.  $x = \frac{1}{2}$ ,  $z = \frac{1}{2}$ . Clearly we have

$$\begin{aligned} & M(x, y, z) \\ &= \max\{G(Ax, By, Cz), G(Ax, Ax, Tx), G(By, By, Sy), G(Cz, Cz, Hz), \\ &\quad \frac{1}{2}[G(Ax, By, Cz) + G(Tx, Sy, Hz)]\} \\ &\geq G(Ax, By, Cz) = 1 \end{aligned}$$

It follows that

$$\begin{aligned} \psi(M(x, y, z)) &= \frac{2}{3} \times 1 = \frac{2}{3} \\ G(Tx, Sy, Hz) &= \frac{1}{2} < \frac{2}{3} \leq \psi(M(x, y, z)) \end{aligned}$$

Note that  $A, B, C, S, T$  and  $H$  satisfy all the hypotheses of Theorem 3.1. Hence  $A, B, C, S, T$  and  $H$  have a unique common fixed point. Here 0 is the fixed point of  $A, B, C, S, T$  and  $H$ .

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