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SOME FIXED POINT THEOREMS IN M_A -METRIC SPACE

K. ANTHONY SINGH^{1,*}, TH. CHHATRAJIT SINGH², N. PRIYOBARTA SINGH³, Y. ROHEN SINGH³

¹Department of Mathematics, D.M. College of Science, Imphal, Manipur-795001, India

²Department of Mathematics, Manipur Technical University, Takyelpat, Imphal-795004, India

³Department of Mathematics, National Institute of Technology, Imphal, Manipur-795004, India

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Abstract. In this note, we introduce the concept of M_A -metric space as a generalisation of partial A -metric space. We also, prove some fixed point theorems satisfying fundamental contraction principles in the setting of M_A -metric space.

Keywords: A -metric space; partial A -metric space; M_A -metric space; fixed point.

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1. INTRODUCTION

The generalisations of metric fixed point have been an important research area for the last many years and many researchers had contributed a lot in this area. The results on generalization of metric space can be seen in the research papers [1–14] and references therein. These generalisations were then also used to extend the scope of the study of fixed point theory.

Mujahid Abbas, Bashir Ali and Yusuf I Suleiman [15] introduced the concept of n -tuple metric space $A : X^n \rightarrow [0, \infty)$ and also generalised coupled common fixed point theorems for mixed weakly monotone maps in partially ordered A -metric spaces.

*Corresponding author

E-mail address: anthonykumam@manipuruniv.ac.in

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Using the concept of partially A -metric space, we extend fixed point results in M_A -metric space.

Definition 1.1. [11] Let X be a nonempty set and $p : X \times X \rightarrow [0, +\infty)$. We say that (X, p) is an ordinary partial metric space if for all $x, y, z \in X$ we have:

- (1) $x = y$ if and only if $p(x, y) = p(x, x) = p(y, y)$;
- (2) $p(x, x) \leq p(x, y)$;
- (3) $p(x, y) = p(y, x)$;
- (4) $p(x, z) \leq p(x, y) + p(y, z) - p(y, y)$.

The pair (X, p) is called partial metric space.

Definition 1.2. [16] Let X be a nonempty set. A function $m : X \times X \rightarrow \mathbb{R}$ is called an m -metric space if the following conditions are satisfied:

- (m1) $m(x, x) = m(y, y) = m(x, y) \Leftrightarrow x = y$,
- (m2) $m_{xy} \leq m(x, y)$,
- (m3) $m(x, y) = m(y, x)$,
- (m4) $(m(x, y) - m_{xy}) \leq (m(x, z) - m_{xz}) + (m(z, y) + m_{zy})$.

Then the pair (X, m) is called an M -metric space.

Definition 1.3. [1] Let X be a nonempty set. An S -metric on X is a function $S : X^3 \rightarrow [0, \infty)$ that satisfies the following conditions,

1. $S(x, y, z) \geq 0$,
2. $S(x, y, z) = 0$ if and only if $x = y = z$
3. $S(x, y, z) \leq S(x, x, a) + S(y, y, a) + S(z, z, a)$

for each $x, y, z, a \in X$.

The pair (X, S) is called S -metric space.

Definition 1.4. [15] Let X be a nonempty set. A function $A : X^n \rightarrow [0, \infty)$ is called an A -metric on X if for any $x_i, a \in X, i = 1, 2, \dots, n$, the following conditions hold:

- (A1) $A(x_1, x_2, x_3, \dots, x_{n-1}, x_n) \geq 0$,

(A2) $A(x_1, x_2, x_3, \dots, x_{n-1}, x_n) = 0$ if and only if $x_1 = x_2 = x_3 = \dots = x_{n-1} = x_n$,

(A3)

$$\begin{aligned} A(x_1, x_2, x_3, \dots, x_{n-1}, x_n) &\leq [A(x_1, x_1, x_1, \dots, (x_1)_{n-1}, a) \\ &\quad + A(x_2, x_2, x_2, \dots, (x_2)_{n-1}, a) \\ &\quad + A(x_3, x_3, x_3, \dots, (x_3)_{n-1}, a) \\ &\quad \vdots \\ &\quad + A(x_{n-1}, x_{n-1}, x_{n-1}, \dots, (x_{n-1})_{n-1}, a) \\ &\quad + A(x_n, x_n, x_n, \dots, (x_n)_{n-1}, a).] \end{aligned}$$

The pair (X, A) is called an A -metric space.

Definition 1.5. [15] Let X be a nonempty set. A partial A -metric space is a function $A_P : X^n \rightarrow [0, \infty)$ that satisfies the following conditions, for all $x_1, x_2, \dots, x_n, t \in X$;

- (i) $A_P(x_1, x_2, \dots, x_n) \geq 0$,
- (ii) $x_1 = x_2 = \dots = x_n$ if and only if $A_P(x_1, x_1, \dots, x_1) = A_P(x_2, x_2, \dots, x_2) = \dots = A_P(x_n, x_n, \dots, x_n)$,
- (iii)

$$\begin{aligned} A_P(x_1, x_2, \dots, x_n) &\leq A_P(x_1, x_1, \dots, (x_1)_{n-1}, t) + A_P(x_2, x_2, \dots, (x_2)_{n-1}, t) \\ &\quad + \dots + A_P(x_n, x_n, \dots, (x_n)_{n-1}, t) - A_P(t, t, \dots, t), \end{aligned}$$

- (iv) $A_P(x_1, x_1, \dots, x_1) \leq A_P(x_1, x_2, \dots, x_n)$,
- (v) $A_P(x_1, x_1, \dots, x_1, x_2) = A_P(x_2, x_2, \dots, x_2, x_1)$.

The pair (X, A_P) is called a partial A -metric space.

Definition 1.6. [15] Let X be a nonempty set. A partial A -metric on X is a function $A_p : X^n \rightarrow [0, \infty)$ that satisfies the following conditions for all $x_1, x_2, \dots, x_n, t \in X$,

- (i) $x_1 = x_2$ if and only if $A_p(x_1, x_1, \dots, x_1) = A_p(x_2, x_2, \dots, x_2) = A_p(x_1, x_1, \dots, x_1, x_2)$.

(ii)

$$A_p(x_1, x_2, \dots, x_n) \leq A_p(x_1, x_1, \dots, x_1, t) + A_p(x_2, x_2, \dots, x_2, t) + \dots + A_p(x_n, x_n, \dots, x_n, t) + A_p(t, t, \dots, t).$$

(iii) $A_p(x_1, x_1, \dots, x_1) \leq A_p(x_1, x_2, \dots, x_n).$

(iv) $A_p(x_1, x_1, \dots, x_1, x_2) = A_p(x_2, x_2, \dots, x_2, x_1).$

The pair (X, A_p) is called a partial A -metric space.

Next, we give the definition of an M_A -metric space, but first we introduce the following notations.

Notation 1.

1. $m_{A_{x_1, x_2, \dots, x_n}} := \min\{m_A(x_1, x_1, \dots, x_1), m_A(x_2, x_2, \dots, x_2), \dots, m_A(x_n, x_n, \dots, x_n)\}.$
2. $M_{A_{x_1, x_2, \dots, x_n}} := \max\{m_A(x_1, x_1, \dots, x_1), m_A(x_2, x_2, \dots, x_2), \dots, m_A(x_n, x_n, \dots, x_n)\}.$

Definition 1.7. An M_A -metric on a nonempty set X is a function $m_A : X^n \rightarrow \mathbb{R}^+$ such that for all $x_1, x_2, \dots, x_n, t \in X$, the following conditions are satisfied:

1. $m_A(x_1, x_1, \dots, x_1) = m_A(x_2, x_2, \dots, x_2) = m_A(x_1, x_1, \dots, x_1, x_2)$ if and only if $x_1 = x_2.$
2. $m_{A_{x_1, x_2, \dots, x_n}} \leq m_A(x_1, x_2, \dots, x_n).$
3. $m_A(x_1, x_1, \dots, x_1, x_2) = m_A(x_2, x_2, \dots, x_2, x_1).$
- 4.

$$\begin{aligned} (m_A(x_1, x_2, \dots, x_n) - m_{A_{x_1, x_2, \dots, x_n}}) &\leq (m_A(x_1, x_1, \dots, x_1, t) - m_{A_{x_1, x_1, \dots, x_1, t}}) \\ &+ (m_A(x_2, x_2, \dots, x_2, t) - m_{A_{x_2, x_2, \dots, x_2, t}}) \\ &+ \dots \\ &+ (m_A(x_n, x_n, \dots, x_n, t) - m_{A_{x_n, x_n, \dots, x_n, t}}) \end{aligned}$$

The pair (X, m_A) is called an M_A -metric space. Notice that the condition $m_A(x_1, x_1, \dots, x_1) = m_A(x_2, x_2, \dots, x_2) = \dots = m_A(x_n, x_n, \dots, x_n) = m_A(x_1, x_2, \dots, x_n) \Leftrightarrow x_1 = x_2 = \dots = x_n$ implies that (1) above.

It is straightforward to verify that every partial A -metric space is an M_A -metric space but the converse is not true. The following example is an M_A -metric which is not a partial A -metric space.

Example 1. Let $X = \{1, 2, \dots, n\}$ and define

Definition 1.8. Let (X, m_A) be an M_A -metric space. Then

1. a sequence $\{x_p\}$ in X converges to a point x if and only if $\lim_{p \rightarrow \infty} (m_A(x_p, x_p, \dots, x_p, x) - m_{A_{x_p, x_p, \dots, x_p, x}}) = 0$.
2. a sequence $\{x_p\}$ in X is said to be M_A -Cauchy sequence if and only if

$$\lim_{p, q \rightarrow \infty} (m_A(x_p, x_p, \dots, x_p, x_q) - m_{A_{x_p, x_p, \dots, x_p, x_q}})$$

and

$$\lim_{p, q \rightarrow \infty} (M_{A_{x_p, x_p, \dots, x_p, x_q}} - m_{A_{x_p, x_p, \dots, x_p, x_q}})$$

exists and finite.

3. an M_A -metric space is said to be complete if every M_A -Cauchy sequence $\{x_p\}$ converges to a point x such that

$$\lim_{p \rightarrow \infty} (m_A(x_p, x_p, \dots, x_p, x) - m_{A_{x_p, x_p, \dots, x_p, x}}) = 0$$

and

$$\lim_{p \rightarrow \infty} (M_{A_{x_p, x_p, \dots, x_p, x}} - m_{A_{x_p, x_p, \dots, x_p, x}}) = 0.$$

A ball in the M_A -metric (X, m_A) space with centre $x \in X$ and radius $\eta > 0$ is defined by

$$B_A[x, \eta] = \{x_2 \in X : m_A(x_1, x_1, \dots, x_1, x_2) - m_{A_{x_1, x_1, \dots, x_1, x_2}}\} \leq \eta.$$

The topology of (X, M_A) is generated by means of the basis $\beta = \{B_A[x, \eta] : \eta > 0\}$.

Lemma 1.1. Assume $x_p \rightarrow x$ and $y_p \rightarrow y$ as $p \rightarrow \infty$ in an M_A -metric space (X, m_A) . Then,

$$\lim_{p \rightarrow \infty} (m_A(x_p, x_p, \dots, x_p, y_p) - m_{A_{x_p, x_p, \dots, x_p, y_p}}) = m_A(x, x, \dots, x, y) - m_{A_{x, x, \dots, x, y}}.$$

Proof. The proof follows by the inequality (4) in definition (1.7). Indeed, we have

$$\begin{aligned} & |(m_A(x_p, x_p, \dots, x_p, y_p) - m_{A_{x_p, x_p, \dots, x_p, y_p}}) - (m_A(x, x, \dots, x, y) - m_{A_{x, x, \dots, x, y}})| \\ & \leq (n-1) |(m_A(x_p, x_p, \dots, x_p, x) - m_{A_{x_p, x_p, \dots, x_p, x}}) + (m_A(y_p, y_p, \dots, y_p, y) - m_{A_{y_p, y_p, \dots, y_p, y}})| \end{aligned}$$

□

2. MAIN RESULTS

In this section, we consider some results about the existence and uniqueness of fixed point for self-mappings on an M_A -metric space, under different contraction principles.

Theorem 2.1. *Let (X, m_A) be a complete M_A -metric space and T be a self-mapping on X satisfying the following condition:*

$$(1) \quad m_A(Tx, Tx, \dots, Tx, Ty) \leq km_A(x, x, \dots, x, y)$$

for all $x, y \in X$, where $k \in [0, 1)$. Then T has a unique fixed point u . Moreover, $m_A(u, u, \dots, u) = 0$.

Proof. Since $k \in [0, 1)$, we can choose a natural number n_0 such that for a given $0 < \varepsilon < 1$, we have $k^{n_0} < \frac{\varepsilon}{4(n-1)}$. Let $T^{n_0} = F$ and $F^i x_0 = x_i$ for all natural number i , where x_0 is arbitrary. Hence, for all $x, y \in X$, we have

$$\begin{aligned} m_A(Fx, \dots, Fx, Fy) &= m_A(T^{n_0}x, \dots, T^{n_0}x, T^{n_0}y) \\ &\leq k^{n_0} m_A(x, x, \dots, x, y) \end{aligned}$$

For any i , we have

$$\begin{aligned} m_A(x_{i+1}, \dots, x_{i+1}, x_i) &= m_A(Fx_i, \dots, Fx_i, Fx_{i-1}) \\ &\leq k^{n_0} m_A(x_i, \dots, x_i, x_{i-1}) \\ &\leq k^{n_0+i} m_A(x_1, \dots, x_1, x_0) \rightarrow 0 \text{ as } i \rightarrow \infty. \end{aligned}$$

Similarly, by (1) we have $m_A(x_i, \dots, x_i, x_i) \rightarrow 0$ as $i \rightarrow \infty$. Thus, we choose l such that

$$m_A(x_{l+1}, \dots, x_{l+1}, x_l) < \frac{\varepsilon}{4(n-1)}$$

and

$$m_A(x_l, \dots, x_l, x_l) < \frac{\varepsilon}{2(n-1)}.$$

Now, let $\eta = \frac{\varepsilon}{2} + m_A(x_l, \dots, x_l, x_l)$. Define the set

$$B_A[x_l, \eta] = \{y \in X | m_A(x_l, \dots, x_l, y) - m_{A_{x_l, x_l, \dots, x_l, y \leq \eta}}\}.$$

Note that, $x_l \in B_A[x_l, \eta]$. Therefore $B_A[x_l, \eta] \neq \emptyset$. Let $z \in B_A[x_l, \eta]$ be arbitrary. Hence,

$$\begin{aligned} m_A(Fz, \dots, Fz, Fx_l) &\leq k^{n_0} m_A(z, \dots, z, x_l) \\ &\leq k^{n_0} [(n-1) \{m_A(z, z, \dots, z) - m_{A_{z, z, \dots, z}}\} \\ &\quad + m_A(x_l, x_l, \dots, x_l) - m_{A_{x_l, x_l, \dots, x_l}} + m_{A_{z, z, \dots, z, x_l}}] \\ &\leq \frac{\varepsilon}{4(n-1)} [(n-1) \frac{\varepsilon}{2(n-1)} + m_{A_{z, z, \dots, z, x_l}} + m_A(x_l, x_l, \dots, x_l)] \\ &\leq \frac{\varepsilon}{4(n-1)} [\frac{\varepsilon}{2} + m_{A_{z, z, \dots, z, x_l}} + m_A(x_l, x_l, \dots, x_l)] \\ &\leq \frac{\varepsilon}{4(n-1)} [1 + 2m_A(x_l, x_l, \dots, x_l)]. \end{aligned}$$

Also, we know that

$$m_A(Fx_l, Fx_l, \dots, Fx_l, x_l) = m_A(x_{l+1}, x_{l+1}, \dots, x_{l+1}, x_l) < \frac{\varepsilon}{4(n-1)}.$$

Therefore,

$$\begin{aligned} m_A(Fz, Fz, \dots, Fz, x_l) - m_{A_{Fz, \dots, Fz, x_l}} &\leq (n-1) [m_A(Fz, Fz, \dots, Fx_l) - m_{A_{Fz, \dots, Fz, Fx_l}}] \\ &\quad + m_A(Fx_l, \dots, Fx_l, x_l) - m_{A_{Fx_l, \dots, Fx_l, x_l}} \\ &\leq (n-1) m_A(Fz, Fz, \dots, Fx_l) + m_{A_{Fx_l, \dots, Fx_l, x_l}} \\ &\leq (n-1) \frac{\varepsilon}{4(n-1)} [1 + 2m_A(x_l, x_l, \dots, x_l)] + \frac{\varepsilon}{4(n-1)} \\ &= \frac{\varepsilon}{4} + \frac{\varepsilon}{4(n-1)} + \frac{\varepsilon}{2} m_A(x_l, x_l, \dots, x_l) \\ &= \frac{n\varepsilon}{4(n-1)} + \frac{\varepsilon}{2} m_A(x_l, x_l, \dots, x_l) \\ &< \frac{\varepsilon}{2} + m_A(x_l, x_l, \dots, x_l). \end{aligned}$$

Thus, $Fz \in B_b[x_l, \eta]$ which implies that F maps $B_b[x_l, \eta]$ into itself. Thus by repeating the process we deduce that for all $n \geq 1$, we have $F^n x_l \in B_b[x_l, \eta]$ and that is $x_m \in B_b[x_l, \eta]$ for all $m \geq l$. Therefore, for all $m > n \geq l$ where $n = l + i$ for some i .

$$\begin{aligned} m_A(x_n, \dots, x_n, x_m) &= m_A(Fx_{n-1}, \dots, Fx_{n-1}, Fx_{m-1}) \\ &\leq k^{n_0} m_A(x_{n-1}, \dots, x_{n-1}, x_{m-1}) \\ &\leq k^{2n_0} m_A(x_{n-2}, \dots, x_{n-2}, x_{m-2}) \\ &\vdots \\ &\leq k^{in_0} m_A(x_l, \dots, x_l, x_{m-i}) \\ &\leq m_A(x_l, \dots, x_l, x_{m-i}) \\ &\leq \frac{\varepsilon}{2} + m_{A_{x_l, \dots, x_l, x_{m-i}}} + m_A(x_l, \dots, x_l, x_l) \\ &\leq \frac{\varepsilon}{2} + 2m_A(x_l, \dots, x_l, x_l) \end{aligned}$$

Also, we have $m_A(x_l, \dots, x_l, x_l) < \frac{\varepsilon}{4}$, which implies that $m_A(x_n, \dots, x_n, x_m) < \varepsilon$ for all $m > n > l$, and thus $m_A(x_n, \dots, x_n, x_m) - m_{A_{x_n, \dots, x_n, x_m}} < \varepsilon$ for all $m > n > l$. By the contraction condition (1), we see that the sequence $\{m_A(x_n, \dots, x_n, x_l)\}$ is decreasing and hence, for all $m > n > l$, we have

$$\begin{aligned} M_{A_{x_n, \dots, x_n, x_m}} - m_{A_{x_n, \dots, x_n, x_m}} &\leq M_{A_{x_n, \dots, x_n, x_m}} \\ &= m_A(x_n, \dots, x_n, x_n) \\ &\leq km_A(x_{n-1}, x_{n-1}, \dots, x_{n-1}) \\ &\vdots \\ &\leq k^n m_A(x_0, x_0, \dots, x_0) \rightarrow 0 \text{ as } n \rightarrow \infty. \end{aligned}$$

Thus, we deduce that

$$\lim_{n, m \rightarrow \infty} [m_A(x_n, \dots, x_n, x_m) - m_{A_{x_n, \dots, x_n, x_m}}] = 0$$

and

$$\lim_{n, m \rightarrow \infty} [M_{A_{x_n, \dots, x_n, x_m}} - m_{A_{x_n, \dots, x_n, x_m}}] = 0.$$

Hence, the sequence $\{x_n\}$ is an M_A -Cauchy. Since X is complete, there exists $u \in X$ such that

$$\lim_{n \rightarrow \infty} [m_A(x_n, \dots, x_n, u) - m_{A_{x_n, \dots, x_n, u}}] = 0$$

and

$$\lim_{n \rightarrow \infty} [M_A(x_n, \dots, x_n, u) - m_{A_{x_n, \dots, x_n, u}}] = 0.$$

The contraction condition (1) implies that $m_A(x_n, x_n, \dots, x_n) \rightarrow 0$ as $n \rightarrow \infty$. Moreover, notice that

$$\lim_{n \rightarrow \infty} [M_A(x_n, \dots, x_n, u) - m_{A_{x_n, \dots, x_n, u}}] = \lim_{n \rightarrow \infty} |m_A(x_n, x_n, \dots, x_n) - m_A(u, u, \dots, u)| = 0,$$

and hence $m_A(u, u, \dots, u) = 0$. Since $x_n \rightarrow u$, $m_A(u, u, \dots, u) = 0$ and $m_A(x_n, x_n, \dots, x_n) \rightarrow 0$ as $n \rightarrow \infty$, then

$$\lim_{n \rightarrow \infty} m_A(x_n, \dots, x_n, u) = \lim_{n \rightarrow \infty} m_{A_{x_n, \dots, x_n, u}} = 0.$$

Since $m_A(Tx_n, \dots, Tx_n, Tu) \leq km_A(x_n, \dots, x_n, u) \rightarrow 0$ as $n \rightarrow \infty$, then $Tx_n \rightarrow Tu$.

Now, we show that $Tu = u$. By Lemma (1.1) and that $Tx_n \rightarrow Tu$ and $x_{n+1} = Tx_n \rightarrow u$, we have

$$\begin{aligned} \lim_{n \rightarrow \infty} m_A(x_n, \dots, x_n, u) &= m_{A_{x_n, \dots, x_n, u}} = 0 \\ &= \lim_{n \rightarrow \infty} m_A(x_{n+1}, \dots, x_{n+1}, u) - m_{A_{x_{n+1}, \dots, x_{n+1}, u}} \\ &= \lim_{n \rightarrow \infty} m_A(Tx_n, \dots, Tx_n, u) - m_{A_{Tx_n, \dots, Tx_n, u}} \\ &= m_A(u, \dots, u, u) - m_{A_{Tu, \dots, Tu, u}} \\ &= m_A(Tu, \dots, Tu, u) - m_{A_{Tu, \dots, Tu, u}} \end{aligned}$$

Hence, $m_A(Tu, \dots, Tu, u) = m_{A_{Tu, \dots, Tu, u}} = m_A(u, u, \dots, u)$, but also by the contraction condition (1) we see that $m_{A_{Tu, \dots, Tu, u}} = m_A(Tu, Tu, \dots, Tu)$. Therefore, (2) in definition (1.7) implies that $Tu = u$.

To prove the uniqueness of the fixed point u , assume that T has two fixed points $u, v \in X$; that is $Tu = u$ and $Tv = v$. Thus,

$$m_A(u, \dots, u, v) = m_A(Tu, \dots, Tu, Tv) \leq km_A(u, \dots, u, v) < m_A(u, u, \dots, u, v),$$

$$m_A(u, \dots, u, u) = m_A(Tu, Tu, \dots, Tu) \leq km_A(u, \dots, u, u) < m_A(u, u, \dots, u, u),$$

and

$$m_A(v, v, \dots, v) = m_A(Tv, Tv, \dots, Tv) \leq km_A(v, v, \dots, v) < m_A(v, v, \dots, v),$$

which implies that $m_A(u, u, \dots, u, v) = 0 = m_A(u, u, \dots, u) = m_A(v, v, \dots, v)$, and hence $u = v$ as desired. Finally, assume that u is a fixed point of T . Then applying the contraction condition (1) with $k \in [0, 1)$, implies that

$$\begin{aligned} m_A(u, u, \dots, u) &= m_A(Tu, Tu, \dots, Tu) \\ &\leq km_A(u, u, \dots, u) \\ &\vdots \\ &\leq k^n m_A(u, u, \dots, u). \end{aligned}$$

Taking the limit as $n \rightarrow \infty$, implies that $m_A(u, u, \dots, u) = 0$.

In the following result, we prove the existence and uniqueness of a fixed point for a self-mapping in M_A -metric space, but under a more general contraction. □

Theorem 2.2. *Let (X, m_A) be a complete M_A -metric space and T be a self-mapping on X satisfying the following condition*

$$(2) \quad m_A(Tx, \dots, Tx, Ty) \leq \lambda [m_A(x, \dots, x, Tx) + m_A(y, \dots, y, Ty)]$$

for all $x, y \in X$, where $\lambda \in [0, \frac{1}{2})$. Then T has a unique fixed point u , where $m_A(u, u, \dots, u) = 0$.

Proof. Let $x_0 \in X$ be arbitrary. Consider the sequence $\{x_n\}$ defined by $x_n = T^n x_0$ and $m_{A_n} = m_A(x_n, \dots, x_n, x_{n+1})$. Note that if there exists a natural number n such that $m_{A_n} = 0$, then x_n is a

fixed point of T and we are done. So, we may assume that $m_A > 0$ for $n \geq 0$. By (2), we obtain for any $n \geq 0$,

$$\begin{aligned}
 m_{A_n} &= m_A(x_n, \dots, x_n, x_{n+1}) \\
 &= m_A(Tx_{n-1}, \dots, Tx_{n-1}, Tx_n) \\
 &\leq \lambda [m_A(x_{n-1}, \dots, x_{n-1}, Tx_{n-1}) + m_A(x_n, \dots, x_n, Tx_n)] \\
 &= \lambda [m_A(x_{n-1}, \dots, x_{n-1}, x_n) + m_A(x_n, \dots, x_n, x_{n-1})] \\
 &= \lambda [m_{A_{n-1}} + m_{A_n}] \\
 \Rightarrow m_{A_n} &\leq \lambda m_{A_{n-1}} + \lambda m_{A_n} \\
 \Rightarrow m_{A_n} &\leq \mu m_{A_{n-1}}
 \end{aligned}$$

where $\mu = \frac{\lambda}{1-\lambda} < 1$ as $\lambda \in [0, \frac{1}{2})$.

By repeating this process, we get

$$m_{A_n} \leq \mu^n m_{A_0}.$$

Thus, $\lim_{n \rightarrow \infty} m_{A_n} = 0$. By (2), for all natural number n, m , we have

$$\begin{aligned}
 m_A(x_n, \dots, x_n, x_m) &= m_A(T^n x_0, \dots, T^n x_0, T^m x_0) \\
 &= m_A(Tx_{n-1}, \dots, Tx_{n-1}, Tx_{m-1}) \\
 &\leq \lambda [m_A(x_{n-1}, \dots, x_{n-1}, Tx_{n-1}) + m_A(x_{m-1}, \dots, x_{m-1}, Tx_{m-1})] \\
 &= \lambda [m_A(x_{n-1}, \dots, x_{n-1}, x_n) + m_A(x_{m-1}, \dots, x_{m-1}, x_m)] \\
 &\leq \lambda [m_{A_{n-1}} + m_{A_{m-1}}].
 \end{aligned}$$

Since $\lim_{n \rightarrow \infty} m_{A_n} = 0$, for every $\varepsilon > 0$, we can find a natural number n_0 such that $m_{A_n} < \frac{\varepsilon}{2}$ and $m_{A_m} < \frac{\varepsilon}{2}$ for all $m, n > n_0$. Therefore, it follows that

$$\begin{aligned}
 m_A(x_n, \dots, x_n, x_m) &\leq \lambda [m_{A_{n-1}} + m_{A_{m-1}}] \\
 &< \lambda \left[\frac{\varepsilon}{2} + \frac{\varepsilon}{2} \right] \\
 &< \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon \text{ for all } n, m > n_0.
 \end{aligned}$$

This implies that

$$m_A(x_n, \dots, x_n, x_m) - m_{A_{x_n, \dots, x_n, x_m}} < \varepsilon$$

for all $n, m > n_0$.

Now, for all natural numbers n, m , we have

$$\begin{aligned} M_{A_{x_n, \dots, x_n, x_m}} &= m_A(Tx_{n-1}, \dots, Tx_{n-1}, Tx_{n-1}) \\ &\leq \lambda [m_A(x_{n-1}, \dots, x_{n-1}, Tx_{n-1}) + m_A(x_{n-1}, \dots, x_{n-1}, Tx_{n-1})] \\ &= \lambda [m_A(x_{n-1}, \dots, x_{n-1}, x_n) + m_A(x_{n-1}, \dots, x_{n-1}, x_n)] \\ &= \lambda [m_{A_{n-1}} + m_{A_{n-1}}] \\ &= 2\lambda m_{A_{n-1}}. \end{aligned}$$

As $\lim_{n \rightarrow \infty} m_{A_{n-1}} = 0$, for every $\varepsilon > 0$ we can find a natural number n_0 such that $m_{A_n} < \frac{\varepsilon}{2}$ and for all $m, n > n_0$. Therefore, it follows that

$$\begin{aligned} M_{A_{x_n, \dots, x_n, x_m}} &\leq \lambda [m_{A_{n-1}} + m_{A_{n-1}}] \\ &< \lambda \left[\frac{\varepsilon}{2} + \frac{\varepsilon}{2} \right] \\ &< \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon \text{ for all } n, m > n_0, \end{aligned}$$

which implies that

$$M_{A_{x_n, \dots, x_n, x_m}} - m_{A_{x_n, \dots, x_n, x_m}} < \varepsilon \text{ for all } n, m > n_0.$$

Thus, $\{x_n\}$ is an M_A -Cauchy sequence in X . Since X is complete, there exists $u \in X$ such that

$$\lim_{n \rightarrow \infty} m_A(x_n, \dots, x_n, u) - m_{A_{x_n, \dots, x_n, u}} = 0.$$

Now, we show that u is a fixed point of T in X . For any natural number n , we have,

$$\begin{aligned} &\lim_{n \rightarrow \infty} m_A(x_n, \dots, x_n, u) - m_{A_{x_n, \dots, x_n, u}} = 0 \\ &= \lim_{n \rightarrow \infty} m_A(x_{n+1}, \dots, x_{n+1}, u) - m_{A_{x_{n+1}, \dots, x_{n+1}, u}} \\ &= \lim_{n \rightarrow \infty} m_A(Tx_n, \dots, Tx_n, u) - m_{A_{Tx_n, \dots, Tx_n, u}} \\ &= m_A(Tu, \dots, Tu, u) - m_{A_{Tu, \dots, Tu, u}}. \end{aligned}$$

This implies that $m_A(Tu, \dots, Tu, u) = m_{A_{u, \dots, u, Tu}} = 0$, and that is $m_A(Tu, \dots, Tu, u) = m_{A_{u, \dots, u, Tu}}$.

Now, assume that

$$\begin{aligned} m_A(Tu, \dots, Tu, u) &= m_A(Tu, \dots, Tu, Tu) \\ &\leq 2\lambda m_A(u, \dots, u, Tu) \\ &= 2\lambda m_A(Tu, \dots, Tu, u) \\ &< m_A(u, \dots, u, Tu) \end{aligned}$$

Thus,

$$\begin{aligned} m_A(Tu, \dots, Tu, u) &= m_A(u, \dots, u, u) \\ &\leq m_A(Tu, \dots, Tu, Tu) \\ &\leq 2\lambda m_A(u, \dots, u, Tu) \\ &< m_A(u, \dots, u, Tu) \end{aligned}$$

Therefore, $Tu = u$ and thus u is a fixed point of T .

Next, we show that if u is a fixed point, then $m_A(u, \dots, u, u) = 0$. Assume that u is a fixed point of T , then using the contraction (2), we have

$$\begin{aligned} m_A(u, u, \dots, u) &= m_A(Tu, \dots, Tu, Tu) \\ &\leq \lambda [m_A(u, u, \dots, u, Tu) + m_A(u, u, \dots, u, Tu)] \\ &= 2\lambda m_A(u, u, \dots, u, Tu) \\ &= 2\lambda m_A(u, u, \dots, u) \\ &< m_A(u, u, \dots, u) \text{ since } \lambda \in [0, \frac{1}{2}), \end{aligned}$$

that is, $m_A(u, u, \dots, u) = 0$.

Finally, to prove the uniqueness, assume that T has two fixed points, say $u, v \in X$. Hence,

$$\begin{aligned} m_A(u, \dots, u, v) &= m_A(Tu, \dots, Tu, Tv) \\ &\leq \lambda [m_A(u, u, \dots, u, Tu) + m_A(v, v, \dots, v, Tv)] \\ &= \lambda [m_A(u, u, \dots, u) + m_A(v, v, \dots, v)] = 0, \end{aligned}$$

which implies that

$$m_A(u, \dots, u, v) = 0 = m_A(u, u, \dots, u) = m_A(v, v, \dots, v),$$

and $u = v$ as required. □

In closing, the authors would like to bring to the reader’s attention that in this interesting M_A -metric space, it is possible to add some control functions in both contractions of Theorems 1 and 2.

Theorem 2.3. *Let (X, m_A) be a complete M_A -metric space and T be a self-mapping on X satisfying the following condition: for all $x_1, x_2, \dots, x_n \in X$*

$$(3) \quad m_A(Tx_1, Tx_2, \dots, Tx_n) \leq m_A(x_1, x_2, \dots, x_n) - \phi(m_A(x_1, x_2, \dots, x_n)),$$

where $\phi : [0, \infty) \rightarrow [0, \infty)$ is a continuous and non-decreasing function and $\phi^{-1}(0) = 0$ and $\phi(t) > 0$ for all $t > 0$. Then T has a unique fixed point in X .

Proof. Let $x_0 \in X$. Define the sequence $\{x_n\}$ in X such that $x_n = T^{n-1}x_0 = Tx_{n-1}$ for all $n \in \mathbb{N}$. Note that if there exists an $n \in \mathbb{N}$ such that $x_{n+1} = x_n$, then x_n is a fixed point for T . Without loss of generality, assume that $x_{n+1} \neq x_n$ for all $n \in \mathbb{N}$. Now

$$\begin{aligned} m_A(x_n, x_{n+1}, \dots, x_{n+1}) &= m_A(Tx_{n-1}, Tx_n, \dots, Tx_n) \\ &\leq m_A(x_{n-1}, x_n, \dots, x_n) - \phi(m_A(x_{n-1}, x_n, \dots, x_n)) \\ (4) \quad &\leq m_A(x_{n-1}, x_n, \dots, x_n) \end{aligned}$$

Similarly, we can prove that $m_A(x_{n-1}, x_n, \dots, x_n) \leq m_A(x_{n-2}, x_{n-1}, \dots, x_{n-1})$. Hence, $m_A(x_n, x_{n+1}, \dots, x_{n+1})$ is a nondecreasing sequence. Hence there exists $r \geq 0$ such that

$$\lim_{n \rightarrow \infty} m_A(x_n, x_{n+1}, \dots, x_{n+1}) = r.$$

Now, by taking the limit as $n \rightarrow \infty$ in the inequality (4), we get $r \leq r - \phi(r)$ which leads to a contraction unless $r = 0$. Therefore,

$$\lim_{n \rightarrow \infty} m_A(x_n, x_{n+1}, \dots, x_{n+1}) = 0.$$

Suppose that $\{x_n\}$ is not an M_A -Cauchy sequence. Then there exists an $\varepsilon > 0$ such that we can find subsequences x_{m_k} and x_{n_k} of $\{x_n\}$ such that

$$(5) \quad m_A(x_{n_k}, x_{m_k}, \dots, x_{m_k}) - m_{A_{x_{n_k}, x_{m_k}, \dots, x_{m_k}}} \geq \varepsilon$$

Choose n_k to be the smallest integer with $n_k > m_k$ and satisfies the inequality (5). Hence,

$$m_A(x_{n_k}, x_{m_{k-1}}, \dots, x_{m_{k-1}}) - m_{A_{x_{n_k}, x_{m_{k-1}}, \dots, x_{m_{k-1}}}} < \varepsilon.$$

Now,

$$\begin{aligned} \varepsilon &\leq m_A(x_{m_k}, x_{n_k}, \dots, x_{n_k}) - m_{A_{x_{m_k}, x_{n_k}, \dots, x_{n_k}}} \\ &\leq m_A(x_{m_k}, x_{n_k-1}, \dots, x_{n_k-1}) + (n-1)m_A(x_{n_k-1}, \dots, x_{n_k-1}) - m_{A_{x_{m_k}, x_{n_k-1}, \dots, x_{n_k-1}}} \\ &\geq \varepsilon + (n-1)m_A(x_{n_k-1}, \dots, x_{n_k-1}) \\ &< \varepsilon, \end{aligned}$$

as $n \rightarrow \infty$. Hence, we have contradiction. Without loss of generality, assume that $m_{A_{x_n, x_n, \dots, x_n, x_m}} = m_A(x_n, x_n, \dots, x_n, x_m)$. Then we have

$$\begin{aligned} 0 &\leq m_{A_{x_n, x_n, \dots, x_n, x_m}} - m_A(x_n, x_n, \dots, x_n, x_m) \\ &\leq M_{A_{x_n, x_n, \dots, x_n, x_m}} \\ &= m_A(x_n, x_n, \dots, x_n, x_m) \\ &= m_A(Tx_{n-1}, Tx_{n-1}, \dots, Tx_{n-1}) \\ &\leq m_A(x_{n-1}, x_{n-1}, \dots, x_{n-1}) - \phi(m_A(x_{n-1}, x_{n-1}, \dots, x_{n-1})) \\ &\leq m_A(x_{n-1}, x_{n-1}, \dots, x_{n-1}) \\ &\vdots \\ &\leq m_A(x_0, x_0, \dots, x_0). \end{aligned}$$

Hence, $\lim_{n \rightarrow \infty} m_{A_{x_n, x_n, \dots, x_n, x_m}} - m_{A_{x_n, x_n, \dots, x_n, x}}$ exists and finite. Therefore, $\{x_n\}$ is an M_A -Cauchy sequence. Since X is a complete, the sequence $\{x_n\}$ converges to an element $x \in X$; that is,

$$\begin{aligned} 0 &= \lim_{n \rightarrow \infty} m_A(x_n, x_n, \dots, x_n, x) - m_{A_{x_n, x_n, \dots, x_n, x}} \\ &= \lim_{n \rightarrow \infty} m_A(x_{n+1}, x_{n+1}, \dots, x_{n+1}, x) - m_{A_{x_{n+1}, x_{n+1}, \dots, x_{n+1}, x}} \\ &= \lim_{n \rightarrow \infty} m_A(Tx_n, Tx_n, \dots, Tx_n, x) - m_{A_{Tx_n, Tx_n, \dots, Tx_n, x}} \\ &= m_A(Tx, Tx, \dots, Tx, x) - m_{A_{Tx, Tx, \dots, Tx, x}} \end{aligned}$$

Similar to the proof of the Theorem 2, it is not difficult to show that this implies that, $Tx = x$ and so x is a fixed point.

Finally, we show that T has a unique fixed point. Assume that there are two fixed points $u, v \in X$ of T . If we have $m_A(u, u, \dots, u, v) > 0$, then condition (3) implies that

$$\begin{aligned} m_A(u, u, \dots, u, v) - m_A(Tu, Tu, \dots, Tu, v) &\leq m_A(u, u, \dots, u, v) - \phi(m_A(u, u, \dots, u, v)) \\ &< m_A(u, u, \dots, u, v) \end{aligned}$$

and that is a contradiction. Therefore, $m_A(u, u, \dots, u, v) = 0$ and similarly $m_A(u, u, \dots, u) = M_A(v, v, \dots, v) = 0$ and thus $u = v$ as desired. \square

CONFLICT OF INTERESTS

The author(s) declare that there is no conflict of interests.

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