



Available online at <http://scik.org>

J. Math. Comput. Sci. 10 (2020), No. 6, 2307-2319

<https://doi.org/10.28919/jmcs/4876>

ISSN: 1927-5307

## ON COMMON FIXED POINTS OF SUBCOMPATIBLE MAPPINGS IN S-METRIC SPACES

PRASAD KANCHANAPALLY\*, V. NAGA RAJU

Department of Mathematics, University College of Science,  
Osmania University, Hyderabad-500007, Telangana State, India

Copyright © 2020 the author(s). This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

**Abstract.** In this paper, we prove two common fixed point theorems for two pairs of subcompatible mappings which are also subsequentially continuous under different generalized contractions in S-metric spaces. We also give examples to support our results.

**Keywords:** S-metric space; subcompatible mappings; reciprocally continuous mappings; subsequentially continuous mappings.

**2010 AMS Subject Classification:** 54H25, 47H10.

### 1. INTRODUCTION

In 2006, Mustafa and Sims [3] introduced G-metric spaces as a generalization of metric spaces and proved the existence of fixed points under different contractions. In 2012, Sedghi, Shobe and Aliouche [1] introduced a new concept called an S-metric space and studied its some properties. They also stated that an S-metric space is a generalization of a G-metric space. But, in 2014 Dung, Hieu and Radojevic [4] showed by an example that an S-metric space is not a generalization of a G-metric space and conversely. Thus the class of S-metric spaces and the

---

\*Corresponding author

E-mail address: [iitm.prasad@gmail.com](mailto:iitm.prasad@gmail.com)

Received July 24, 2020

class of G-metric spaces are distinct. On the other hand, in 2011, H. Bouhadjera et al. [6] introduced new concepts in metric spaces called subcompatibility and subsequential continuity by generalizing occasionally weakly compatibility and reciprocal continuity respectively.

In this paper, we define subcompatibility and subsequential continuity in S-metric spaces and establish two common fixed point theorems.

In the following, we present some definitions which are frequently used in this paper.

## 2. PRELIMINARIES

**Definition 2.1.** [1] Let  $X$  be a non empty set. Then we say that a function  $S: X^3 \rightarrow [0, \infty)$  is an S-metric on  $X$  iff it satisfies the following for all  $\alpha, \beta, \gamma$  and  $\theta \in X$

P1)  $S(\alpha, \beta, \gamma) = 0$  iff  $\alpha = \beta = \gamma$ .

P2)  $S(\alpha, \beta, \gamma) \leq S(\alpha, \alpha, \theta) + S(\beta, \beta, \theta) + S(\gamma, \gamma, \theta)$ .

Here  $(X, S)$  is called an S-metric space.

**Example 2.2.**  $(X, S)$  is an S-metric space ,

where  $X = [0, 1]$  and  $S(\alpha, \beta, \gamma) = \begin{cases} 0, & \text{for } \alpha = \beta = \gamma \\ \max\{\alpha, \beta, \gamma\}, & \text{otherwise} \end{cases}$  for  $\alpha, \beta, \gamma \in X$ .

**Example 2.3.** [2]  $(X, S)$  is an S-metric space ,

where  $X = \mathbb{R}$  and  $S(\alpha, \beta, \gamma) = |\alpha - \gamma| + |\beta - \gamma|$  for  $\alpha, \beta, \gamma \in X$ .

**Example 2.4.**  $(X, S)$  is an S-metric space ,

where  $X = [0, 4]$  and  $S(\alpha, \beta, \gamma) = \max\{|\alpha - \gamma|, |\beta - \gamma|\}$  for  $\alpha, \beta, \gamma \in X$ .

**Definition 2.5.** [1] We say that a sequence  $(\alpha_n)$  in an S-metric space  $(X, S)$  converges to some  $\alpha \in X$  iff  $S(\alpha_n, \alpha_n, \alpha) \rightarrow 0$  as  $n \rightarrow \infty$ .

**Lemma 2.6.** [1] In an S-metric space  $(X, S)$ , we have  $S(\alpha, \alpha, \gamma) = S(\gamma, \gamma, \alpha)$  for all  $\alpha, \gamma \in X$ .

**Lemma 2.7.** [1] In an S-metric space  $(X, S)$ , if there exist sequences  $(\alpha_n)$  and  $(\beta_n)$  in  $X$  such that  $\lim_{n \rightarrow \infty} \alpha_n = \alpha$  and  $\lim_{n \rightarrow \infty} \beta_n = \beta$ , then  $\lim_{n \rightarrow \infty} S(\alpha_n, \alpha_n, \beta_n) = S(\alpha, \alpha, \beta)$ .

**Definition 2.8.** We say that two self maps  $f$  and  $R$  of an S-metric space  $(X, S)$  are subcompatible iff there exists a sequence  $(\alpha_n)$  in  $X$  such that  $\lim_{n \rightarrow \infty} R(\alpha_n) = \lim_{n \rightarrow \infty} f(\alpha_n) = \gamma$  for some  $\gamma \in X$  and  $\lim_{n \rightarrow \infty} S(fR\alpha_n, fR\alpha_n, Rf\beta_n) = 0$ .

**Example 2.9.** Consider an S-metric space  $(X, S)$ ,

where  $X = [0, \infty)$  and  $S(\alpha, \beta, \gamma) = |\alpha - \gamma| + |\beta - \gamma|$  for  $\alpha, \beta, \gamma \in X$ .

Define two self maps  $f, R$  on  $X$  by  $f\alpha = \alpha$  and  $R\alpha = 1$  for  $\alpha \in X$ . Now consider  $\alpha_n = 1 + \frac{1}{n}$  for  $n \in \mathbb{N}$ . Then  $f\alpha_n = 1 + \frac{1}{n}$  and  $R\alpha = 1$  for all  $n \in \mathbb{N}$ . This will imply that

$S(f\alpha_n, f\alpha_n, 1) = S(1 + \frac{1}{n}, 1 + \frac{1}{n}, 1) = \frac{2}{n}$  and  $S(R\alpha_n, R\alpha_n, 1) = 0$  for every  $n \in \mathbb{N}$ . It follows that  $f\alpha_n \rightarrow 1$  and  $R\alpha_n \rightarrow 1$ , as  $n \rightarrow \infty$ . Note that  $(fR)\alpha = 1$  and  $(Rf)\alpha = 1$  for  $\alpha \in X$ . This implies that  $S(fR\alpha_n, fR\alpha_n, Rf\alpha_n) = S(1, 1, 1) = 0 \rightarrow 0$ , as  $n \rightarrow \infty$ . Thus there exists a sequence  $(\alpha_n)$  in  $X$  such that  $\lim_{n \rightarrow \infty} R(\alpha_n) = \lim_{n \rightarrow \infty} f(\alpha_n) = 1 \in X$  and  $\lim_{n \rightarrow \infty} S(fR\alpha_n, fR\alpha_n, Rf\alpha_n) = 0$ . Therefore  $f$  and  $R$  are subcompatible.

**Definition 2.10.** [5] We say that a mapping  $f$  of an S-metric sapce  $(X, S)$  into another S-metric space  $(Y, S')$  is continuous at a point  $\alpha \in X$  iff  $(f(\alpha_n))$  converges to  $f(\alpha)$  in  $Y$ , whenever any sequence  $(\alpha_n)$  converges to  $\alpha$  in  $X$ .

**Definition 2.11.** We say that two self maps  $f$  and  $R$  of an S-metric space  $(X, S)$  are reciprocal continuous iff any sequence  $(\alpha_n)$  in  $X$  such that  $\lim_{n \rightarrow \infty} R(\alpha_n) = \lim_{n \rightarrow \infty} f(\alpha_n) = \gamma$  for some  $\gamma \in X$  implies  $\lim_{n \rightarrow \infty} fR(\alpha_n) = f\gamma$  and  $\lim_{n \rightarrow \infty} Rf(\alpha_n) = R\gamma$ .

Clearly if  $f$  and  $g$  are continuous, then they are reciprocal continuous. Its converse in general need not be true.

**Definition 2.12.** We say that two self maps  $f$  and  $R$  of an S-metric space  $(X, S)$  are subsequentially continuous iff there exists a sequence  $(\alpha_n)$  in  $X$  such that  $\lim_{n \rightarrow \infty} R(\alpha_n) = \lim_{n \rightarrow \infty} f(\alpha_n) = \gamma$  for some  $\gamma \in X$  satisfying  $\lim_{n \rightarrow \infty} fR(\alpha_n) = f\gamma$  and  $\lim_{n \rightarrow \infty} Rf(\alpha_n) = R\gamma$ .

Clearly if  $f$  and  $g$  are continuous or reciprocal continuous, then they are subsequentially continuous. In general, its converse need not be true.

**Example 2.13** Consider an S-metric space  $(X, S)$ ,

where  $X = [0, \infty)$  and  $S(\alpha, \beta, \gamma) = |\alpha - \gamma| + |\beta - \gamma|$  for  $\alpha, \beta, \gamma \in X$ .

Now we define  $f, R: X \rightarrow X$  by  $f(\alpha) = \begin{cases} \frac{\alpha}{4}, & \text{for } \alpha \in [0, 1] \\ 4\alpha - 3, & \text{for } \alpha \in (1, \infty) \end{cases}$  and

$R(\alpha) = \begin{cases} \frac{\alpha}{3}, & \text{for } \alpha \in [0, 1] \\ 3\alpha - 2, & \text{for } \alpha \in (1, \infty) \end{cases}$  for  $\alpha \in X$ .

Case(i): We first show that  $f$  and  $R$  are not continuous.

For this, consider  $\alpha_n = 1 + \frac{1}{n}$  for  $n \in \mathbb{N}$ . Then we have  $f\alpha_n = 1 + \frac{4}{n}$  and  $R\alpha_n = 1 + \frac{3}{n}$  for  $n \in \mathbb{N}$ . This will imply that  $S(\alpha_n, \alpha_n, 1) = 2|\alpha_n - 1| = 2|1 + \frac{1}{n} - 1| \rightarrow 0$ , as  $n \rightarrow \infty$ . This shows

that  $\alpha_n \rightarrow 1$ . Note that  $S(f\alpha_n, f\alpha_n, 1) = S(1 + \frac{4}{n}, 1 + \frac{4}{n}, 1) = \frac{8}{n}$  and  $S(R\alpha_n, R\alpha_n, 1) = S(1 + \frac{3}{n}, 1 + \frac{3}{n}, 1) = \frac{6}{n}$  for all  $n \in \mathbb{N}$ . This imply that  $f(\alpha_n) \rightarrow 1 \neq \frac{1}{4} = f(1)$  and  $R(\alpha_n) \rightarrow 1 \neq \frac{1}{3} = R(1)$ . Thus there exists a sequence  $(\alpha_n)$  in  $X$  such that  $\alpha_n$  converges to 1, but  $f(\alpha_n)$  does not converge to  $f(1)$  and also  $R(\alpha_n)$  does not converge to  $R(1)$ . This shows that  $f$  and  $R$  are not continuous functions on  $X$ .

Case(ii): Now let us show that  $f$  and  $R$  are subsequentially continuous. For this, consider  $\alpha_n = \frac{1}{n}$  for  $n \in \mathbb{N}$ . Then we have  $f\alpha_n = \frac{1}{4n}$  and  $R\alpha_n = \frac{1}{3n}$  for all  $n \in \mathbb{N}$ . Now look at  $S(f\alpha_n, f\alpha_n, 0) = \frac{2}{4n}$  and  $S(R\alpha_n, R\alpha_n, 0) = \frac{2}{3n}$  for every  $n \in \mathbb{N}$ . This will imply that  $f\alpha_n \rightarrow 0$  and  $R\alpha_n \rightarrow 0$ , as  $n \rightarrow \infty$ . Also note that  $fR\alpha_n = \frac{1}{12n}$  and  $Rf\alpha_n = \frac{1}{12n}$  and  $S(fR\alpha_n, fR\alpha_n, 0) = \frac{1}{6n}$  and  $S(Rf\alpha_n, Rf\alpha_n, 0) = \frac{1}{6n}$  for every  $n \in \mathbb{N}$ . This will imply that  $fR\alpha_n \rightarrow 0 = f0$  and  $Rf\alpha_n \rightarrow 0 = R0$ , as  $n \rightarrow \infty$ . Thus there exists a sequence  $(\alpha_n)$  in  $X$  such that  $\lim_{n \rightarrow \infty} R(\alpha_n) = \lim_{n \rightarrow \infty} f(\alpha_n) = 0 \in X$  for implies  $\lim_{n \rightarrow \infty} fR(\alpha_n) = f(0)$  and  $\lim_{n \rightarrow \infty} Rf(\alpha_n) = R(0)$ . Therefore  $f$  and  $R$  are subsequentially continuous.

Case(iii): Finally, we show that  $f$  and  $R$  are not reciprocal continuous.

For this, let  $\alpha_n = 1 + \frac{1}{n}$  for  $n \in \mathbb{N}$ . By case(i), we have  $f(\alpha_n) \rightarrow 1$  and  $R(\alpha_n) \rightarrow 1$ . Now look at  $fR\alpha_n = 1 + \frac{1}{12n}$  and  $Rf\alpha_n = 1 + \frac{1}{9n}$ . This will imply that  $S(fR\alpha_n, fR\alpha_n, 1) = \frac{24}{n}$  and  $S(Rf\alpha_n, Rf\alpha_n, 1) = \frac{18}{n}$  for every  $n \in \mathbb{N}$ . This imply that  $fR\alpha_n \rightarrow 1 \neq f(1) = \frac{1}{4}$  and  $Rf\alpha_n \rightarrow 1 \neq R(1) = \frac{1}{3}$ , as  $n \rightarrow \infty$ . Thus there exists a sequence  $(\alpha_n)$  in  $X$  such that  $\lim_{n \rightarrow \infty} R(\alpha_n) = \lim_{n \rightarrow \infty} f(\alpha_n) = 1 \in X$  and  $\lim_{n \rightarrow \infty} fR(\alpha_n) \neq f(1)$  and  $\lim_{n \rightarrow \infty} Rf(\alpha_n) \neq R(1)$ . Therefore  $f$  and  $R$  are not reciprocal continuous.

### 3. MAIN RESULTS

**Theorem 3.1.** Suppose in an S-metric space  $X$ , there are four self maps  $f, g, R$  and  $T$  on  $X$  satisfying i)  $S(f\alpha, f\alpha, g\beta) \leq \phi(S(R\alpha, R\alpha, T\beta))$  for all  $\alpha, \beta \in X$ , where  $\phi : [0, \infty) \rightarrow [0, \infty)$  is a continuous function such that  $\phi(0) = 0$  and  $0 < \phi(k) < k$  for every  $k > 0$

ii)  $(f, R)$  and  $(g, T)$  are subcompatible

iii)  $(f, R)$  and  $(g, T)$  are subsequentially continuous.

Then  $f, g, R$  and  $T$  have a unique common fixed point.

**Proof :** Since  $(f, R)$  is subcompatible, we can find a sequence  $(\alpha_n)$  in  $X$  such that

$\lim_{n \rightarrow \infty} R\alpha_n = \lim_{n \rightarrow \infty} f\alpha_n = \gamma$  for some  $\gamma \in X$  and  $\lim_{n \rightarrow \infty} S(fR\alpha_n, fR\alpha_n, Rf\alpha_n) = 0$ . Now  $(g, T)$  is sub-compatible implies that there exists a sequence  $(\beta_n)$  in  $X$  such that  $\lim_{n \rightarrow \infty} g\beta_n = \lim_{n \rightarrow \infty} T\beta_n = \delta$  for some  $\delta \in X$  and  $\lim_{n \rightarrow \infty} S(gT\alpha_n, gT\alpha_n, Tg\alpha_n) = 0$ . Since  $(f, R)$  is subsequentially continuous,  $(f\alpha_n)$  and  $(R\alpha_n)$  converge to  $\gamma$ , we have  $\lim_{n \rightarrow \infty} fR\alpha_n = f\gamma$  and  $\lim_{n \rightarrow \infty} Rf\alpha_n = R\gamma$ . Similarly, since  $(g, T)$  is subsequentially continuous,  $(g\alpha_n)$  and  $(T\alpha_n)$  converge to  $\delta$ , we have  $\lim_{n \rightarrow \infty} gT\alpha_n = g\delta$  and  $\lim_{n \rightarrow \infty} Tg\alpha_n = T\delta$ .

Now  $\lim_{n \rightarrow \infty} fR\alpha_n = f\gamma$ ,  $\lim_{n \rightarrow \infty} Rf\alpha_n = R\gamma$  and  $\lim_{n \rightarrow \infty} S(fR\alpha_n, fR\alpha_n, Rf\alpha_n) = 0$  imply that  $S(f\gamma, f\gamma, R\gamma) = 0$  and hence  $f\gamma = R\gamma$ . Since  $\lim_{n \rightarrow \infty} gT\alpha_n = g\delta$ ,  $\lim_{n \rightarrow \infty} Tg\alpha_n = T\delta$  and  $\lim_{n \rightarrow \infty} S(gT\alpha_n, gT\alpha_n, Tg\alpha_n) = 0$ ,  $S(g\delta, g\delta, T\delta) = 0$  and hence  $g\delta = T\delta$ . For each  $n \in \mathbb{N}$ , we consider

$$S(f\alpha_n, f\alpha_n, g\beta_n) \leq \phi(S(R\alpha_n, R\alpha_n, T\beta_n)).$$

Letting  $n \rightarrow \infty$ , we have

$S(\gamma, \gamma, \delta) \leq \phi(S(\gamma, \gamma, \delta)) = \phi(0) = 0$ , since  $\phi$  is continuous. This implies  $S(\gamma, \gamma, \delta) = 0$  and hence  $\gamma = \delta$ . Now let us show that  $f\gamma = \gamma$ . For each  $n \in \mathbb{N}$ , we consider

$$S(f\gamma, f\gamma, g\beta_n) \leq \phi(S(R\gamma, R\gamma, T\beta_n)).$$

Now letting  $n \rightarrow \infty$ , we have

$$\begin{aligned} S(f\gamma, f\gamma, \delta) &\leq \phi(S(R\gamma, R\gamma, \delta)) \\ &= \phi(S(f\gamma, f\gamma, \delta)). \end{aligned}$$

Therefore  $S(f\gamma, f\gamma, \delta) \leq \phi(S(f\gamma, f\gamma, \delta))$ . This will imply that  $S(f\gamma, f\gamma, \gamma) \leq \phi(S(f\gamma, f\gamma, \gamma))$ , since

$\gamma = \delta$ . If  $S(f\gamma, f\gamma, \gamma) \neq 0$ , then by definition of  $\phi$ ,  $S(f\gamma, f\gamma, \gamma) < \phi(S(f\gamma, f\gamma, \gamma))$ -contradiction. Therefore, we must have  $S(f\gamma, f\gamma, \gamma) = 0$  and hence  $f\gamma = \gamma$ .

Now we show that  $g\gamma = \gamma$ . Note that  $S(f\gamma, f\gamma, g\gamma) \leq \phi(S(R\gamma, R\gamma, T\gamma))$ . Since  $f\gamma = R\gamma$ , we have  $S(f\gamma, f\gamma, g\gamma) \leq \phi(S(f\gamma, f\gamma, g\gamma))$ . This will imply that  $S(\gamma, \gamma, g\gamma) \leq \phi(S(\gamma, \gamma, g\gamma))$ , since  $f\gamma = \gamma$ .

If  $S(\gamma, \gamma, g\gamma) \neq 0$ , then  $S(\gamma, \gamma, g\gamma) > 0$ . By definition of  $\phi$ , we have  $\phi(S(\gamma, \gamma, g\gamma)) < S(\gamma, \gamma, g\gamma)$ . This will imply that  $S(\gamma, \gamma, g\gamma) < S(\gamma, \gamma, g\gamma)$  -contradiction. Therefore  $S(\gamma, \gamma, g\gamma) = 0$  and hence  $g\gamma = \gamma$ . Since  $f\gamma = R\gamma$  and  $f\gamma = \gamma$ , then  $f\gamma = R\gamma = \gamma$  and hence  $\gamma$  is a common fixed point of  $f$  and  $R$ . Similarly,  $g\gamma = \gamma$  and  $g\gamma = T\gamma$  imply that  $g\gamma = T\gamma = \gamma$  and hence  $\gamma$  is a common fixed point of  $g$  and  $T$ . Therefore  $\gamma$  is a common fixed point of  $f, R, g$  and  $T$ .

Let us now show the uniqueness of common fixed point of  $f, g, R$  and  $T$ . For this, let  $\theta$  be

another common fixed point of  $f$ ,  $g$ ,  $R$  and  $T$ . Then  $f\theta=g\theta=R\theta=T\theta=\theta$  and  $f\gamma=g\gamma=R\gamma=T\gamma=\gamma$ . Now we consider  $S(\theta, \theta, \gamma)=S(f\theta, f\theta, g\gamma) \leq \phi(S(R\theta, R\theta, T\gamma))=\phi(S(\theta, \theta, \gamma))$ . If  $S(\theta, \theta, \gamma) \neq 0$ , then we must have  $S(\theta, \theta, \gamma) < S(\theta, \theta, \gamma)$ -contradiction. Therefore  $\theta = \gamma$  and the result is proved.

**Corollary 3.2.** Suppose in an S-metric space  $X$ , there are two self maps  $f$  and  $R$  on  $X$  satisfying  
i)  $S(f\alpha, f\alpha, f\beta) \leq \phi(S(R\alpha, R\alpha, R\beta))$  for all  $\alpha, \beta \in X$ , where  $\phi : [0, \infty) \rightarrow [0, \infty)$  is a continuous function such that  $\phi(0) = 0$  and  $0 < \phi(k) < k$  for every  $k > 0$

ii)  $(f, R)$  is subcompatible

iii)  $(f, R)$  is subsequentially continuous.

Then  $f$  and  $R$  have a unique common fixed point.

**Proof :** Follows from the Theorem 3.1 by taking  $g=f$  and  $T=R$  on  $X$ .

**Corollary 3.3.** Suppose in an S-metric space  $X$ , there are four self maps  $f$ ,  $g$ ,  $R$  and  $T$  on  $X$  satisfying i)  $S(f\alpha, f\alpha, g\beta) \leq q(S(R\alpha, R\alpha, T\beta))$  for all  $\alpha, \beta \in X$  and for some  $q \in [0, 1)$

ii)  $(f, R)$  and  $(g, T)$  are subcompatible

iii)  $(f, R)$  and  $(g, T)$  are subsequentially continuous.

Then  $f$ ,  $g$ ,  $R$  and  $T$  have a unique common fixed point.

**Proof :** Let  $\phi : [0, \infty) \rightarrow [0, \infty)$  be a function defined by  $\phi(k) = qk$  for  $k \in [0, \infty)$ . Clearly it is continuous function on  $[0, \infty)$  such that  $\phi(0) = 0$  and  $0 < \phi(k) < k$  for all  $k > 0$ . Therefore all the conditions of Theorem 3.1 are satisfied and hence the result proved.

**Corollary 3.4.** Suppose in an S-metric space  $X$ , there is a self map  $f$  on  $X$  satisfying

i)  $S(f\alpha, f\alpha, f\beta) \leq q(S(\alpha, \alpha, \beta))$  for all  $\alpha, \beta \in X$  and for some  $q \in [0, 1)$

ii)  $(f, I)$  is subcompatible

iii)  $(f, I)$  is subsequentially continuous, where  $I$  is the identity self map on  $X$ .

Then  $f$  has a unique fixed point.

**Proof :** Let  $\phi : [0, \infty) \rightarrow [0, \infty)$  be a function defined by  $\phi(k) = qk$  for  $k \in [0, \infty)$ . Clearly it is continuous function on  $[0, \infty)$  such that  $\phi(0) = 0$  and  $0 < \phi(k) < k$  for all  $k > 0$ . Now we set  $g=f$  and  $R=T=I$  on  $X$  in the Theorem 3.1 and hence the result proved.

**Theorem 3.5.** Suppose in an S-metric space  $X$ , there are four self maps  $f$ ,  $g$ ,  $R$  and  $T$  on  $X$  satisfying

i) (f, R) and (g, T) are subcompatible

ii) (f, R) and (g, T) are subsequentially continuous

iii)  $\Psi(S(f\alpha, f\alpha, g\beta)) \leq \Psi(\chi(\alpha, \beta)) - \phi(\chi(\alpha, \beta))$  for all  $\alpha, \beta \in X$ , where  $\phi : [0, \infty) \rightarrow [0, \infty)$  is a continuous function such that  $\phi(0) = 0$  and  $0 < \phi(k) < k$  for every  $k > 0$  and  $\Psi : [0, \infty) \rightarrow [0, \infty)$  is a continuous function such that  $\Psi(0) = 0$  and

$$\chi(\alpha, \beta) = \max\{S(R\alpha, R\alpha, T\beta), S(R\alpha, R\alpha, f\alpha), S(T\beta, T\beta, g\beta), S(R\alpha, R\alpha, g\beta), S(T\beta, T\beta, f\alpha)\}$$

for  $\alpha, \beta \in X$ .

Then f, g, R and T have a unique common fixed point.

**Proof :** Suppose that (f, R) is subcompatible. Then we can find a sequence  $(\alpha_n)$  in X such that  $\lim_{n \rightarrow \infty} R\alpha_n = \lim_{n \rightarrow \infty} f\alpha_n = \gamma$  for some  $\gamma \in X$  and  $\lim_{n \rightarrow \infty} S(fR\alpha_n, fR\alpha_n, Rf\alpha_n) = 0$ . Now (g, T) is subcompatible implies that there exists a sequence  $(\beta_n)$  in X such that  $\lim_{n \rightarrow \infty} g\beta_n = \lim_{n \rightarrow \infty} T\beta_n = \delta$  for some  $\delta \in X$  and  $\lim_{n \rightarrow \infty} S(gT\alpha_n, gT\alpha_n, Tg\alpha_n) = 0$ . Since (f, R) is subsequentially continuous,  $(f\alpha_n)$  and  $(R\alpha_n)$  converge to  $\gamma$ , we have  $\lim_{n \rightarrow \infty} fR\alpha_n = f\gamma$  and  $\lim_{n \rightarrow \infty} Rf\alpha_n = R\gamma$ . Similarly, since (g, T) is subsequentially continuous,  $(g\beta_n)$  and  $(T\beta_n)$  converge to  $\delta$ , we have  $\lim_{n \rightarrow \infty} gT\beta_n = g\delta$  and  $\lim_{n \rightarrow \infty} Tg\beta_n = T\delta$ .

Now  $\lim_{n \rightarrow \infty} fR\alpha_n = f\gamma$ ,  $\lim_{n \rightarrow \infty} Rf\alpha_n = R\gamma$  and  $\lim_{n \rightarrow \infty} S(fR\alpha_n, fR\alpha_n, Rf\alpha_n) = 0$  imply that  $S(f\gamma, f\gamma, R\gamma) = 0$  and hence  $f\gamma = R\gamma$ . Since  $\lim_{n \rightarrow \infty} gT\beta_n = g\delta$ ,  $\lim_{n \rightarrow \infty} Tg\beta_n = T\delta$  and  $\lim_{n \rightarrow \infty} S(gT\beta_n, gT\beta_n, Tg\beta_n) = 0$ , we have  $S(g\delta, g\delta, T\delta) = 0$  and hence  $g\delta = T\delta$ . Now we show that  $\gamma = \delta$ . For each  $n \in \mathbb{N}$ , we have

$$\Psi(S(f\alpha_n, f\alpha_n, g\beta_n)) \leq \Psi(\chi(\alpha_n, \beta_n)) - \phi(\chi(\alpha_n, \beta_n)), \text{ where}$$

$$\chi(\alpha_n, \beta_n) = \max\{S(R\alpha_n, R\alpha_n, T\beta_n), S(R\alpha_n, R\alpha_n, f\alpha_n), S(T\beta_n, T\beta_n, g\beta_n), S(R\alpha_n, R\alpha_n, g\beta_n), S(T\beta_n, T\beta_n, f\alpha_n)\}$$

for every  $n \in \mathbb{N}$ . Now letting  $n \rightarrow \infty$ , we have

$$\lim_{n \rightarrow \infty} \chi(\alpha_n, \beta_n) = \max\{S(\gamma, \gamma, \delta), S(\gamma, \gamma, \gamma), S(\delta, \delta, \delta), S(\gamma, \gamma, \delta), S(\delta, \delta, \gamma)\} = S(\gamma, \gamma, \delta).$$

Then we have

$$\Psi(S(\gamma, \gamma, \delta)) \leq \Psi(S(\gamma, \gamma, \delta)) - \phi(S(\gamma, \gamma, \delta)).$$

This will imply that  $\phi(S(\gamma, \gamma, \delta)) \leq 0$  and hence  $\phi(S(\gamma, \gamma, \delta)) = 0$ .

By definition of  $\phi$ , we must have  $S(\gamma, \gamma, \delta) = 0$  and hence  $\gamma = \delta$ . Now let us show that  $f\gamma = \gamma$ .

For each  $n \in \mathbb{N}$ , we have

$$\Psi(S(f\gamma, f\gamma, g\beta_n)) \leq \Psi(\chi(\gamma, \beta_n)) - \phi(\chi(\gamma, \beta_n)), \text{ where}$$

$$\chi(\gamma, \beta_n) = \max\{S(R\gamma, R\gamma, T\beta_n), S(R\gamma, R\gamma, f\gamma), \\ S(T\beta_n, T\beta_n, g\beta_n), S(R\gamma, R\gamma, g\beta_n), S(T\beta_n, T\beta_n, f\gamma)\}$$

for every  $n \in \mathbb{N}$ . Now letting  $n \rightarrow \infty$ , we have

$$\lim_{n \rightarrow \infty} \chi(\gamma, \beta_n) = \max\{S(R\gamma, R\gamma, \gamma), S(R\gamma, R\gamma, f\gamma), S(\gamma, \gamma, \gamma), S(R\gamma, R\gamma, \gamma), S(\gamma, \gamma, f\gamma)\} \\ = \max\{S(f\gamma, f\gamma, \gamma), S(f\gamma, f\gamma, f\gamma), S(\gamma, \gamma, \gamma), S(f\gamma, f\gamma, \gamma), S(\gamma, \gamma, f\gamma)\} = S(f\gamma, f\gamma, \delta).$$

Then we have  $\Psi(S(f\gamma, f\gamma, \gamma)) \leq \Psi(S(f\gamma, f\gamma, \gamma)) - \phi(S(f\gamma, f\gamma, \gamma))$ . This will imply that  $\phi(S(f\gamma, f\gamma, \gamma)) \leq 0$  and hence  $\phi(S(f\gamma, f\gamma, \gamma)) = 0$ . By definition of  $\phi$ , we must have  $S(f\gamma, f\gamma, \gamma) = 0$  and hence  $f\gamma = \gamma = R\gamma$ . Now we show that  $g\gamma = \gamma$ . For this, we have

$$\Psi(S(f\gamma, f\gamma, g\gamma)) \leq \Psi(\chi(\gamma, \gamma)) - \phi(\chi(\gamma, \gamma)), \text{ where}$$

$$\chi(\gamma, \gamma) = \max\{S(R\gamma, R\gamma, T\gamma), S(R\gamma, R\gamma, f\gamma), S(T\gamma, T\gamma, g\gamma), S(R\gamma, R\gamma, g\gamma), S(T\gamma, T\gamma, f\gamma)\} \\ = \max\{S(\gamma, \gamma, g\gamma), S(\gamma, \gamma, \gamma), S(g\gamma, g\gamma, g\gamma), S(\gamma, \gamma, g\gamma), S(g\gamma, g\gamma, \gamma)\} = S(g\gamma, g\gamma, \gamma).$$

Therefore  $\Psi(S(f\gamma, f\gamma, g\gamma)) \leq \Psi(S(g\gamma, g\gamma, \gamma)) - \phi(S(g\gamma, g\gamma, \gamma))$ . This will imply that

$\Psi(S(\gamma, \gamma, g\gamma)) \leq \Psi(S(g\gamma, g\gamma, \gamma)) - \phi(S(g\gamma, g\gamma, \gamma))$ . It follows that  $\phi(S(g\gamma, g\gamma, \gamma)) \leq 0$ . This implies that  $\phi(S(g\gamma, g\gamma, \gamma)) = 0$  and hence  $g\gamma = \gamma = T\gamma$ .

Now let us show the uniqueness of common fixed point of  $f$ ,  $g$ ,  $R$  and  $T$ . For this, let  $\rho \in X$  be another common fixed point of  $f$ ,  $g$ ,  $R$  and  $T$ . Then  $f\rho = g\rho = R\rho = T\rho = \rho$  and  $f\gamma = g\gamma = R\gamma = T\gamma = \gamma$ .

Note that  $\Psi(S(\gamma, \gamma, \rho)) \leq \Psi(\chi(\gamma, \rho)) - \phi(\chi(\gamma, \rho))$ , where

$$\chi(\gamma, \rho) = \max\{S(R\gamma, R\gamma, T\rho), S(R\gamma, R\gamma, f\gamma), S(T\rho, T\rho, g\rho), S(R\gamma, R\gamma, g\rho), S(T\rho, T\rho, f\gamma)\} \\ = \max\{S(\gamma, \gamma, \rho), S(\gamma, \gamma, \gamma), S(\rho, \rho, \rho), S(\gamma, \gamma, \rho), S(\rho, \rho, \gamma)\} = S(\gamma, \gamma, \rho).$$

Therefore  $\Psi(S(\gamma, \gamma, \rho)) \leq \Psi(S(\gamma, \gamma, \rho)) - \phi(S(\gamma, \gamma, \rho))$ . This will imply that  $\phi(S(\gamma, \gamma, \rho)) \leq 0$  and hence  $\phi(S(\gamma, \gamma, \rho)) = 0$ . Then by definition of  $\phi$ ,  $S(\gamma, \gamma, \rho) = 0$  and therefore  $\gamma = \rho$ . Hence the result is proved.

**Corollary 3.6.** Suppose in an S-metric space  $X$ , there are three self maps  $f$ ,  $g$  and  $R$  on  $X$  satisfying

i)  $(f, R)$  and  $(g, R)$  are subcompatible

ii)  $(f, R)$  and  $(g, R)$  are subsequentially continuous

iii)  $\Psi(S(f\alpha, f\alpha, g\beta)) \leq \Psi(\chi(\alpha, \beta)) - \phi(\chi(\alpha, \beta))$  for all  $\alpha, \beta \in X$ , where  $\phi : [0, \infty) \rightarrow [0, \infty)$  is a continuous function such that  $\phi(0) = 0$  and  $0 < \phi(k) < k$  for every  $k > 0$  and  $\Psi : [0, \infty) \rightarrow [0, \infty)$  is a continuous function such that  $\Psi(0) = 0$  and



$\chi(\alpha, \beta) = \max\{S(R\alpha, R\alpha, R\beta), S(R\alpha, R\alpha, f\alpha), S(R\beta, R\beta, g\beta), S(R\alpha, R\alpha, g\beta), S(R\beta, R\beta, f\alpha)\}$   
for  $\alpha, \beta \in X$ .

Then  $f, g$  and  $R$  have a unique common fixed point.

**Proof :** Follows from the Theorem 3.5 by taking  $T=R$ .

Now we give examples in support of main results.

**Example 3.7.** Consider an S-metric space  $(X, S)$ ,

where  $X = [0, 1]$  and  $S(\alpha, \beta, \gamma) = \begin{cases} 0, & \text{for } \alpha = \beta = \gamma \\ \max\{\alpha, \beta, \gamma\}, & \text{otherwise} \end{cases}$  for all  $\alpha, \beta, \gamma \in X$ .

Define four self maps  $f, g, R$  and  $T$  on  $X$  as follows:

For  $\alpha \in X$ ,  $f\alpha = \frac{\alpha}{6}$ ,  $g\alpha = \frac{\alpha}{6}$ ,  $T\alpha = \alpha$  and  $R\alpha = \frac{\alpha}{2}$ . We also define  $\phi : [0, \infty) \rightarrow [0, \infty)$  by  $\phi(\alpha) = \frac{\alpha}{2}$  for  $\alpha \in [0, \infty)$ . Clearly  $\phi$  is continuous on  $[0, \infty)$  satisfying  $\phi(0) = 0$  and  $0 < \phi(\alpha) < \alpha$  for all  $\alpha > 0$ . Let  $\alpha, \beta \in X$ . Now consider the following cases.

Case(i): Let  $\alpha < \beta$ . Then we have

$$S(f\alpha, f\alpha, g\beta) = \max\{\frac{\alpha}{6}, \frac{\alpha}{6}, \frac{\beta}{6}\} = \frac{1}{6} \max\{\alpha, \alpha, \beta\} = \frac{\beta}{6}$$

$$\text{and } \phi(S(R\alpha, R\alpha, T\beta)) = \frac{1}{2}S(R\alpha, R\alpha, T\beta) = \frac{1}{2} \max\{\frac{\alpha}{2}, \frac{\alpha}{2}, \beta\} = \frac{\beta}{2}, \text{ since } \frac{\alpha}{2} < \frac{\beta}{2} < \beta.$$

Therefore  $S(f\alpha, f\alpha, g\beta) \leq \phi(S(R\alpha, R\alpha, T\beta))$ .

Now consider the case  $\alpha > \beta$ . This will imply that

$$S(f\alpha, f\alpha, g\beta) = \max\{\frac{\alpha}{6}, \frac{\alpha}{6}, \frac{\beta}{6}\} = \frac{1}{6} \max\{\alpha, \alpha, \beta\} = \frac{\alpha}{6}$$

$$\text{and } \phi(S(R\alpha, R\alpha, T\beta)) = \frac{1}{2}S(R\alpha, R\alpha, T\beta) = \frac{1}{2} \max\{\frac{\alpha}{2}, \frac{\alpha}{2}, \beta\}.$$

**subcase(i) :** Let  $\frac{\alpha}{2} > \beta$ . Then we must have

$$\phi(S(R\alpha, R\alpha, T\beta)) = \frac{1}{2}(\frac{\alpha}{2}) = \frac{\alpha}{4} \geq S(R\alpha, R\alpha, T\beta).$$

**subcase(ii) :** Let  $\frac{\alpha}{2} < \beta$ . Then we have

$$\phi(S(R\alpha, R\alpha, T\beta)) = \frac{\beta}{2} > \frac{\alpha}{6} = S(R\alpha, R\alpha, T\beta). \text{ From both cases, we conclude that}$$

$S(f\alpha, f\alpha, g\beta) \leq \phi(S(R\alpha, R\alpha, T\beta))$  for all  $\alpha, \beta \in X$ .

Case(ii): Consider  $\alpha_n = \frac{1}{n}$  for  $n \in \mathbb{N}$ . Then  $f\alpha_n = \frac{1}{6n}$  and  $R\alpha_n = \frac{1}{2n}$  for  $n \in \mathbb{N}$ . This will imply that  $S(f\alpha_n, f\alpha_n, 0) = \max\{\frac{1}{6n}, \frac{1}{6n}, 0\} = \frac{1}{6n}$  and  $S(R\alpha_n, R\alpha_n, 0) = \max\{\frac{1}{2n}, \frac{1}{2n}, 0\} = \frac{1}{2n}$  for  $n \in \mathbb{N}$ . This shows  $f\alpha_n \rightarrow 0$  and  $R\alpha_n \rightarrow 0$ , as  $n \rightarrow \infty$ . Now look at  $fR\alpha_n = \frac{1}{12n}$  and  $Rf\alpha_n = \frac{1}{12n}$  for  $n \in \mathbb{N}$ . It follows that  $S(fR\alpha_n, fR\alpha_n, Rf\alpha_n) = 0$  for all  $n \in \mathbb{N}$ . This will imply that  $S(fR\alpha_n, fR\alpha_n, Rf\alpha_n) \rightarrow 0$ , as  $n \rightarrow \infty$ . Thus there exists a sequence  $(\alpha_n)$  in  $X$  such that  $\lim_{n \rightarrow \infty} R(\alpha_n) = \lim_{n \rightarrow \infty} f(\alpha_n) = 0 \in X$

and  $\lim_{n \rightarrow \infty} S(fR\alpha_n, fR\alpha_n, Rf\alpha_n) = 0$ . Therefore  $(f, R)$  is subcompatible.

Also note that  $fR\alpha_n \rightarrow f(0) = 0$  and  $Rf\alpha_n \rightarrow R(0) = 0$ . Thus there exists a sequence  $(\alpha_n)$  in  $X$  such that  $\lim_{n \rightarrow \infty} R(\alpha_n) = \lim_{n \rightarrow \infty} f(\alpha_n) = 0 \in X$  and also  $\lim_{n \rightarrow \infty} fR(\alpha_n) = f(0)$  and  $\lim_{n \rightarrow \infty} Rf(\alpha_n) = R(0)$ . Therefore  $(f, R)$  is subsequentially continuous.

Case(iii): Now we show that the pair  $(g, T)$  is both subcompatible and subsequentially continuous. For this, we consider  $\alpha_n = \frac{1}{1+n}$  for  $n \in \mathbb{N}$ . Then  $g\alpha_n = \frac{1}{6(n+1)}$  and  $T\alpha_n = \frac{1}{n+1}$  for  $n \in \mathbb{N}$ . This will imply that  $S(g\alpha_n, g\alpha_n, 0) = \max\{\frac{1}{6(n+1)}, \frac{1}{6(n+1)}, 0\} = \frac{1}{6(n+1)}$  and  $S(T\alpha_n, T\alpha_n, 0) = \max\{\frac{1}{1+n}, \frac{1}{1+n}, 0\} = \frac{1}{1+n}$  for  $n \in \mathbb{N}$ . This shows  $g\alpha_n \rightarrow 0$  and  $T\alpha_n \rightarrow 0$ . Now look at  $gT\alpha_n = \frac{1}{6(n+1)}$  and  $Tg\alpha_n = \frac{1}{6(n+1)}$  for  $n \in \mathbb{N}$ . It follows that  $S(gT\alpha_n, gT\alpha_n, Tg\alpha_n) = 0$  for all  $n \in \mathbb{N}$ . This will imply that  $S(gT\alpha_n, gT\alpha_n, Tg\alpha_n) \rightarrow 0$ , as  $n \rightarrow \infty$ . Thus there exists a sequence  $(\alpha_n)$  in  $X$  such that  $\lim_{n \rightarrow \infty} g(\alpha_n) = \lim_{n \rightarrow \infty} T(\alpha_n) = 0 \in X$  and  $\lim_{n \rightarrow \infty} S(gT\alpha_n, gT\alpha_n, Tg\alpha_n) = 0$ . This shows that  $(g, T)$  is subcompatible. Also note that  $gT\alpha_n \rightarrow g(0) = 0$  and  $Tg\alpha_n \rightarrow T(0) = 0$ . Thus there exists a sequence  $(\alpha_n)$  in  $X$  such that  $\lim_{n \rightarrow \infty} T(\alpha_n) = \lim_{n \rightarrow \infty} g(\alpha_n) = 0 \in X$  and also  $\lim_{n \rightarrow \infty} gT(\alpha_n) = g(0)$  and  $\lim_{n \rightarrow \infty} Tg(\alpha_n) = T(0)$ . Hence  $(g, T)$  is subsequentially continuous. Therefore the hypothesis of the Theorem 3.1 is satisfied and  $f, g, R$  and  $T$  have a unique common fixed point, namely zero.

**Example 3.8.** Consider an S-metric space  $(X, S)$ ,

where  $X = [2, 13)$  and  $S(\alpha, \beta, \gamma) = |\alpha - \gamma| + |\beta - \gamma|$  for  $\alpha, \beta, \gamma \in X$ .

Now we define  $f, g, R$  and  $T: X \rightarrow X$  by  $f(\alpha) = \begin{cases} 2, & \text{for } \alpha \in \{2\} \cup (3, 13) \\ 8, & \text{for } \alpha \in (2, 3] \end{cases}$ ,

$g(\alpha) = \begin{cases} 2, & \text{for } \alpha \in \{2\} \cup (3, 13) \\ 3, & \text{for } \alpha \in (2, 3] \end{cases}$ ,  $R(\alpha) = \begin{cases} 2, & \text{for } \alpha = 2 \\ 9, & \text{for } \alpha \in (2, 3] \\ \frac{\alpha+3}{2}, & \text{for } \alpha \in (3, 13) \end{cases}$  and

$T(\alpha) = \begin{cases} 2, & \text{for } \alpha = 2 \\ 7, & \text{for } \alpha \in (2, 3] \\ \alpha - 1, & \text{for } \alpha \in (3, 13) \end{cases}$  for  $\alpha \in X$ .

Also we define  $\phi, \Psi: [0, \infty) \rightarrow [0, \infty)$  by  $\phi(k) = 2k$  and  $\Psi(k) = \frac{2k}{7}$  for  $k \in [0, \infty)$ . Note that  $\chi(\alpha, \beta) = \max\{S(R\alpha, R\alpha, T\beta), S(R\alpha, R\alpha, f\alpha), S(T\beta, T\beta, g\beta), S(R\alpha, R\alpha, g\beta), S(T\beta, T\beta, f\alpha)\}$

for  $\alpha, \beta \in X$ . Clearly  $\phi$  and  $\Psi$  are continuous satisfying  $\phi(0) = 0 = \Psi(0)$  and  $0 < \phi(k) < k$  for every  $k > 0$ . Now consider the following cases.

**Case(I):** Consider the first sub case for  $\alpha = \beta = 2$ . Then we have

$$\Psi(S(f\alpha, f\alpha, g\beta)) = \Psi(S(2, 2, 2)) = 0 \leq \Psi(\chi(\alpha, \beta)) - \phi(\chi(\alpha, \beta)) = 2\chi(\alpha, \beta) - \frac{2}{7}\chi(\alpha, \beta).$$

**Subcase(ii) :** Let  $\alpha = 2$  and  $\beta \in (2, 3]$ . Then  $\Psi(S(f\alpha, f\alpha, g\beta)) = 2S(f\alpha, f\alpha, g\beta) = 4$  and  $\chi(\alpha, \beta) = \max\{S(2, 2, 7), S(2, 2, 2), S(7, 7, 3), S(2, 2, 7), S(7, 7, 2)\} = 2|2 - 7| = 10$ . This will imply that  $\Psi(\chi(\alpha, \beta)) = 2(10) = 20$  and  $\phi(\chi(\alpha, \beta)) = \frac{2}{7}(10)$ . Therefore

$$\Psi(S(f\alpha, f\alpha, g\beta)) = 4 < 20 - \frac{20}{7} = \Psi(\chi(\alpha, \beta)) - \phi(\chi(\alpha, \beta)).$$

**Subcase(iii) :** Let  $\alpha = 2$  and  $\beta \in (3, 13)$ . Then we have

$$\Psi(S(f\alpha, f\alpha, g\beta)) = \Psi(S(2, 2, 2)) = 0 \leq \Psi(\chi(\alpha, \beta)) - \phi(\chi(\alpha, \beta)) = 2\chi(\alpha, \beta) - \frac{2}{7}\chi(\alpha, \beta).$$

**Subcase(iv) :** Let  $\alpha \in (2, 3]$  and  $\beta = 2$ . Then

$$\Psi(S(f\alpha, f\alpha, g\beta)) = 2S(f\alpha, f\alpha, g\beta) = 2S(8, 8, 2) = 24 \text{ and}$$

$\chi(\alpha, \beta) = \max\{S(9, 9, 2), S(9, 9, 8), S(2, 2, 2), S(9, 9, 2), S(2, 2, 8)\} = 2|9 - 2| = 14$ . This will imply that  $\Psi(\chi(\alpha, \beta)) = 2(14) = 28$  and  $\phi(\chi(\alpha, \beta)) = \frac{2}{7}(14) = 4$ .

Therefore  $\Psi(S(f\alpha, f\alpha, g\beta)) = 24 \leq 28 - 4 = \Psi(\chi(\alpha, \beta)) - \phi(\chi(\alpha, \beta))$ .

**Subcase(v) :** Let  $\alpha, \beta \in (2, 3]$ . Then  $\Psi(S(f\alpha, f\alpha, g\beta)) = 2S(f\alpha, f\alpha, g\beta) = 2S(8, 8, 3) = 20$  and  $\chi(\alpha, \beta) = \max\{S(9, 9, 7), S(9, 9, 8), S(7, 7, 3), S(9, 9, 3), S(7, 7, 8)\} = 2|9 - 3| = 12$ . This will imply that  $\Psi(\chi(\alpha, \beta)) = 2(12) = 24$  and  $\phi(\chi(\alpha, \beta)) = \frac{2}{7}(12) = \frac{24}{7}$ .

Therefore  $\Psi(S(f\alpha, f\alpha, g\beta)) = 20 < 24 - \frac{24}{7} = \Psi(\chi(\alpha, \beta)) - \phi(\chi(\alpha, \beta))$ .

**Subcase(vi) :** Let  $\alpha \in (2, 3]$  and  $\beta \in (3, 13)$ . Then

$$\Psi(S(f\alpha, f\alpha, g\beta)) = 2S(f\alpha, f\alpha, g\beta) = 2S(8, 8, 2) = 24 \text{ and}$$

$$\chi(\alpha, \beta) = \max\{S(9, 9, \beta - 1), S(9, 9, 2), S(\beta - 1, \beta - 1, 2), S(9, 9, 2), S(\beta - 1, \beta - 1, 8)\} = 20.$$

This will imply that  $\Psi(\chi(\alpha, \beta)) = 2(20) = 40$  and  $\phi(\chi(\alpha, \beta)) = \frac{2}{7}(40) = \frac{80}{7}$ . Therefore

$$\Psi(S(f\alpha, f\alpha, g\beta)) = 24 < 40 - \frac{80}{7} = \Psi(\chi(\alpha, \beta)) - \phi(\chi(\alpha, \beta)).$$

**Subcase(vii) :** Let  $\alpha \in (3, 13)$  and  $\beta = 2$ . Then we have

$$\Psi(S(f\alpha, f\alpha, g\beta)) = \Psi(S(2, 2, 2)) = 0 \leq \Psi(\chi(\alpha, \beta)) - \phi(\chi(\alpha, \beta)) = 2\chi(\alpha, \beta) - \frac{2}{7}\chi(\alpha, \beta).$$

**Subcase(viii) :** Let  $\alpha \in (3, 13)$  and  $\beta \in (2, 3]$ . Then we have

$$\Psi(S(f\alpha, f\alpha, g\beta)) = 2S(f\alpha, f\alpha, g\beta) = 2S(2, 2, 3) = 4 \text{ and}$$

$$\chi(\alpha, \beta) = \max\{S(\frac{\alpha+3}{2}, \frac{\alpha+3}{2}, 7), S(\frac{\alpha+3}{2}, \frac{\alpha+3}{2}, 2), S(7, 7, 3), S(\frac{\alpha+3}{2}, \frac{\alpha+3}{2}, 3), S(7, 7, 2)\} = 12. \text{ This}$$

will imply that  $\Psi(\chi(\alpha, \beta)) = 2(12) = 24$  and  $\phi(\chi(\alpha, \beta)) = \frac{2}{7}(12) = \frac{24}{7}$ . It follows that  $\Psi(S(f\alpha, f\alpha, g\beta)) = 4 < 24 - \frac{24}{7} = \Psi(\chi(\alpha, \beta)) - \phi(\chi(\alpha, \beta))$ .

**Subcase(ix)** : Let  $\alpha, \beta \in (3, 13)$ . Then we have

$$\Psi(S(f\alpha, f\alpha, g\beta)) = \Psi(S(2, 2, 2)) = 0 \leq \Psi(\chi(\alpha, \beta)) - \phi(\chi(\alpha, \beta)) = 2\chi(\alpha, \beta) - \frac{2}{7}\chi(\alpha, \beta).$$

From all sub cases, we conclude that

$$\Psi(S(f\alpha, f\alpha, g\beta)) \leq \Psi(\chi(\alpha, \beta)) - \phi(\chi(\alpha, \beta)) \text{ for all } \alpha, \beta \in X.$$

Case(II): Now let us show that the pairs  $(f, R)$  and  $(g, T)$  are subcompatible. For this, we choose  $\alpha_n = 2$  for all  $n \in \mathbb{N}$ . Then we have  $f\alpha_n = 2$  and  $R\alpha_n = 2$  for all  $n \in \mathbb{N}$ . Also we have  $fR\alpha_n = 2$  and  $Rf\alpha_n = 2$  for  $n \in \mathbb{N}$ . This will imply that  $f\alpha_n \rightarrow 2$  and  $R\alpha_n \rightarrow 2$  and also

$S(fR\alpha_n, fR\alpha_n, Rf\alpha_n) \rightarrow 0$ , as  $n \rightarrow \infty$ . Thus there exists a sequence  $(\alpha_n)$  in  $X$  such that

$\lim_{n \rightarrow \infty} R(\alpha_n) = \lim_{n \rightarrow \infty} f(\alpha_n) = 2 \in X$  and  $\lim_{n \rightarrow \infty} S(fR\alpha_n, fR\alpha_n, Rf\alpha_n) = 0$ . Therefore  $(f, R)$  is subcompatible. Similarly, we can easily show that the pair  $(g, T)$  is also subcompatible.

Case(III): Now we show that the pairs  $(f, R)$  and  $(g, T)$  are both subsequentially continuous. Clearly  $fR\alpha_n \rightarrow f(2) = 2$  and  $Rf\alpha_n \rightarrow R(2) = 2$  and also  $f\alpha_n \rightarrow 2$  and  $R\alpha_n \rightarrow 2$ , as  $n \rightarrow \infty$ . Thus there exists a sequence  $(\alpha_n)$  in  $X$  such that  $\lim_{n \rightarrow \infty} R(\alpha_n) = \lim_{n \rightarrow \infty} f(\alpha_n) = 2 \in X$  and  $\lim_{n \rightarrow \infty} fR(\alpha_n) = f(2)$  and  $\lim_{n \rightarrow \infty} Rf(\alpha_n) = R(2)$ . Therefore  $(f, R)$  is subsequentially continuous. Similarly, we can show that the pair  $(g, T)$  is subsequentially continuous. Therefore the hypothesis of the Theorem 3.5 is satisfied and  $f, R, g$  and  $T$  have a unique common fixed point, namely 2.

## CONFLICT OF INTERESTS

The author(s) declare that there is no conflict of interests.

## REFERENCES

- [1] S. Sedghi, N. Shobe, A. Aliouche, A generalization of fixed point theorem in S-metric spaces. *Mat. Vesn.* 64 (2012), 258–266.
- [2] S. Sedghi, N.V. Dung, Fixed point theorems on S-metric spaces. *Mat. Vesn.* 66 (2014), 113–124.
- [3] Z. Mustafa, B. Sims, A New Approach To Generalized Metric Spaces, *J. Nonlinear Convex Anal.* 7 (2006), 289–297.
- [4] N.V. Dung, N.T. Hieu, S. Radojevic, Fixed point theorems for g-monotone maps on partially ordered S-metric spaces, *Filomat.* 28 (2014), 1885–1898.

- [5] G.V.R. Babu, L.B. Kumssa, Fixed Points of  $(\alpha, \psi, \phi)$ - Generalized Weakly Contractive Maps and Property (P) in S-metric spaces, Filomat. 31 (2017), 4469-4481.
- [6] H. Bouhadjera, C. Godet-Thobie, Common fixed point theorems for pairs of subcompatible maps, ArXiv:0906.3159 [Math]. (2011).