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J. Math. Comput. Sci. 2022, 12:156

<https://doi.org/10.28919/jmcs/6719>

ISSN: 1927-5307

COMMON FIXED POINT THEOREMS IN COMPLEX VALUED S_b METRIC SPACES

RAJESH PANDYA¹, AKLESH PARIYA^{2,*}, ANTIMA SINDERSIYA³, SANDEEP KUMAR TIWARI¹

¹School of studies in Mathematics, Vikram University (M.P.), India

²Department of Mathematics, S.V.P. Govt. College, Kukshi, (M.P.), India

³Department of Mathematics, Govt. Madhav Science College, Ujjain (M.P.), India

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Abstract. The aim of this paper is to present some common fixed point results for four mappings satisfying generalized contractive condition in a complex valued S_b -metric space using weak compatibility. Our result generalizes, extends and improve existing results of Priyobarta, Rohen and Mlaiki [9] and several researchers (see 1, 2, 3, 5, 6, 7, 8, 9, 10, 11, 12, 14, 15 and references their mentioned in) in context of b- metric, S_b metric space, complex valued metric space, complex valued b- metric space, complex valued S-metric space to complex valued S_b -metric spaces.

Keyword. common fixed point; compatible mapping; weakly compatible mapping; complex valued S_b metric space.

2010 AMS Subject Classification: 54H25, 47H10.

1. INTRODUCTION

Azam et al. [1] developed complex valued metric spaces. As an extension of metric spaces, Bakhtin [3] proposed the notion of b-metric space. Rao et al. [10] integrated these ideas and developed complex valued b-metric spaces as extensions of these spaces, proving fixed point theorems in a complex valued b-metric space. Kang et al. [5] proposed the concept of complex valued G-metric spaces and demonstrated the theory of contraction in this space. Mlaiki [6] developed the complex valued S-metric space and demonstrated the presence and uniqueness of a shared fixed point in

*Corresponding author

E-mail address: pariya.aklesh3@gmail.com

Received September 1, 2021

this space for two self-mappings. Although complex valued metric spaces are a subset of cone metric spaces, our contraction, which has a product and quotient of S_b -metric spaces, cannot be extended to a cone metric space. Recently, Souayah and Mlaiki [15] proposed the idea of S_b -metric spaces as a generalisation of metric space, which was followed by Sedghi et al [12] 's introduction of s- metric space. More, recently Priyobarta, Rohen and Mlaiki [9] introduced the concept of complex valued S_b -metric space and prove some interesting and new results. Our result generalizes, extends and improve existing results of Priyobarta, Rohen and Mlaiki [9].

2. BASIC DEFINITIONS AND PRELIMINARIES

Definition.2.1[6]. Let X be a nonempty set and let $b \geq 1$ be a given number. A function $S: X^3 \rightarrow [0, \infty)$ is said to be S_b -metric if and only if for all $x, y, z, t \in X$ the following conditions are satisfied:

- (i) $S(x, y, z) = 0$ if and only if $x = y = z$;
- (ii) $S(x, x, y) = S(y, y, x)$ for all $x, y \in X$;
- (iii) $S(x, y, z) \leq b[S(x, x, t) + S(y, y, t) + S(z, z, t)]$.

The pair (X, S) is called a S_b -metric space.

Definition 2.2[6]. Let (X, S) be an S_b -metric space and $\{x_n\}$ be a sequence in X . Then

- (i) a sequence $\{x_n\}$ is called convergent if and only if there exists $z \in X$ such that $S(x_n, x_n, z) \rightarrow 0$ as $n \rightarrow \infty$. In this case we write $\lim_n x_n = z$,
- (ii) a sequence $\{x_n\}$ is called a Cauchy sequence if and only if $S(x_n, x_n, x_m) \rightarrow 0$ as $n, m \rightarrow \infty$.
- (iii) (X, S) is said to be a complete S_b -metric space if every Cauchy sequence $\{x_n\}$ converges to a point $x \in X$ such that $\lim_{n, m \rightarrow \infty} S(x_n, x_n, x_m) = \lim_{n, m \rightarrow \infty} S(x_n, x_n, x) = S(x, x, x)$.

The following definition is recently introduced by Azam et al. [1].

Definition 2.3[1]. Let \mathbb{C} be the set of complex numbers and $z_1, z_2 \in \mathbb{C}$. Define a partial order \preceq on \mathbb{C} as follows:

$z_1 \preceq z_2$ if and only if $\operatorname{Re}(z_1) \leq \operatorname{Re}(z_2)$, $\operatorname{Im}(z_1) \leq \operatorname{Im}(z_2)$.

Consequently, one can infer that $z_1 \preceq z_2$ if one of the following conditions is satisfied:

- (i) $\operatorname{Re}(z_1) = \operatorname{Re}(z_2)$, $\operatorname{Im}(z_1) < \operatorname{Im}(z_2)$,
- (ii) $\operatorname{Re}(z_1) < \operatorname{Re}(z_2)$, $\operatorname{Im}(z_1) = \operatorname{Im}(z_2)$,
- (iii) $\operatorname{Re}(z_1) < \operatorname{Re}(z_2)$, $\operatorname{Im}(z_1) < \operatorname{Im}(z_2)$,
- (iv) $\operatorname{Re}(z_1) = \operatorname{Re}(z_2)$, $\operatorname{Im}(z_1) = \operatorname{Im}(z_2)$,

In particular, we write $z_1 \prec z_2$ if $z_1 \neq z_2$ and one of (i), (ii), and (iii) is satisfied and we write $z_1 < z_2$ if only (iii) is satisfied. Notice that $0 \preceq z_1 \preceq z_2 \Rightarrow |z_1| < |z_2|$, and $z_1 \preceq z_2, z_2 < z_3 \Rightarrow z_1 < z_3$.

Definition 2.4.[9] Let X be a nonempty set and let $b \geq 1$ be a given real number. Suppose that a mapping $S: X^3 \rightarrow \mathbb{C}$ satisfies:

- (CS_b1) $0 < S(x, y, z)$ for all $x, y, z \in X$ with $x \neq y \neq z \neq x$.
- (CS_b2) $S(x, y, z) = 0$ if and only if $x = y = z$;
- (CS_b3) $S(x, x, y) = S(y, y, x)$ for all $x, y \in X$;
- (CS_b4) $S(x, y, z) \preceq b[S(x, x, a) + S(y, y, a) + S(z, z, a)]$ for all $x, y, z, a \in X$.

Then S is called a complex valued S_b -metric and the pair (X, S) is called a complex valued S_b -metric space.

Definition 2.5. [9] Let (X, S) be a complex valued S_b -metric space and let $\{x_n\}$ be a sequence in X .

- (i) A sequence $\{x_n\}$ is a complex valued S_b -convergent to x if for every $a \in \mathbb{C}$ with $0 < a$ there exists $k \in \mathbb{N}$ such that $S(x_n, x_n, x) < a$ or $S(x, x, x_n) < a$ for all $n \geq k$ and denoted by $\lim_{n \rightarrow \infty} x_n = x$.
- (ii) A sequence $\{x_n\}$ is called a complex valued S_b -Cauchy if for every $a \in \mathbb{C}$ with $0 < a$ there exists $k \in \mathbb{N}$ such that $S(x_n, x_n, x_m) < a$ for each $m, n \geq k$.
- (iii) If every complex valued S_b -Cauchy sequence is complex valued S_b -convergent in (X, S) , then (X, S) is said to be complex valued S_b -complete

Definition 2.6[4]. Let f and g be two self-maps defined on a set X , then f and g are said to be weakly compatible if they commute at coincidence points.

3. MAIN RESULTS

Theorem 3.1 Let A, B, f and g be four self mappings of a complete complex valued S_b -metric space (X, S) with the coefficient $b \geq 1$ and satisfying

$$(3.1) \quad A \subset g, \quad B \subset f$$

$$(3.2) \quad S(Ax, Ax, By) \lesssim \alpha_1 \left\{ \frac{S(fx, fx, gy)S(By, By, fx)}{2S(fx, fx, gy) + S(By, By, gy)} \right\} + \alpha_2 \{S(Ax, fx, fx) + S(By, By, gy)\} \\ + \alpha_3 \{S(By, By, fx) + S(Ax, Ax, gy)\} + \alpha_4 S(fx, fx, gy).$$

If $2S(fx, fx, gy) + S(By, By, gy) \neq 0$, for all $x, y \in X$, $\alpha_i \geq 0$ ($i = 1, 2, 3, 4$) with at least one α_i is nonzero and $b\alpha_1 + 2\alpha_2 + 3b\alpha_3 + \alpha_4 < 1$. If one of A, B, f or g is a complete subspace of X , then

- (i) (A, f) and (B, g) have a unique coincidence point in X ,
- (ii) if (A, f) and (B, g) are weakly compatible, then A, B, f and g have a unique common fixed point in X .

Proof. Let x_0 be an arbitrary point in X . We define a sequence $\{y_{2n}\}$ in X such that

$$y_{2n} = Ax_{2n} = gx_{2n+1} \\ y_{2n+1} = Bx_{2n+1} = fx_{2n+2} \quad ; n = 0, 1, 2, \dots$$

Then

$$S(y_{2n}, y_{2n}, y_{2n+1}) = S(Ax_{2n}, Ax_{2n}, Bx_{2n+1}) \\ S(y_{2n}, y_{2n}, y_{2n+1}) \lesssim \alpha_1 \left\{ \frac{S(fx_{2n}, fx_{2n}, Tx_{2n+1}) S(Bx_{2n+1}, Bx_{2n+1}, fx_{2n})}{2S(fx_{2n}, fx_{2n}, gx_{2n+1}) + S(Bx_{2n+1}, Bx_{2n+1}, gx_{2n+1})} \right\} \\ + \alpha_2 \{S(Ax_{2n}, Ax_{2n}, fx_{2n}) + S(Bx_{2n+1}, Bx_{2n+1}, gx_{2n+1})\} \\ + \alpha_3 \{S(Bx_{2n+1}, Bx_{2n+1}, fx_{2n}) + S(Ax_{2n}, Ax_{2n}, gx_{2n+1})\} \\ + \alpha_4 S(fx_{2n}, fx_{2n}, gx_{2n+1}) \\ S(y_{2n}, y_{2n}, y_{2n+1}) \lesssim \alpha_1 \left\{ \frac{S(y_{2n-1}, y_{2n-1}, y_{2n}) S(y_{2n+1}, y_{2n+1}, y_{2n-1})}{2S(y_{2n-1}, y_{2n-1}, y_{2n}) + S(y_{2n+1}, y_{2n+1}, y_{2n})} \right\} \\ + \alpha_2 \{S(y_{2n}, y_{2n}, y_{2n-1}) + S(y_{2n+1}, y_{2n+1}, y_{2n})\} \\ + \alpha_3 \{S(y_{2n+1}, y_{2n+1}, y_{2n-1}) + S(y_{2n}, y_{2n}, y_{2n})\} \\ + \alpha_4 S(y_{2n-1}, y_{2n-1}, y_{2n})$$

By condition, $(CS_b 3)$ and $(CS_b 4)$ in the definition of the complex S_b metric spaces, we get

$$\begin{aligned}
S(y_{2n+1}, y_{2n+1}, y_{2n-1}) &= S(y_{2n-1}, y_{2n-1}, y_{2n}) \\
&\lesssim b[S(y_{2n-1}, y_{2n-1}, y_{2n}) + S(y_{2n-1}, y_{2n-1}, y_{2n}) + S(y_{2n+1}, y_{2n+1}, y_{2n})] \\
&\lesssim b[2S(y_{2n-1}, y_{2n-1}, y_{2n}) + S(y_{2n+1}, y_{2n+1}, y_{2n})]
\end{aligned}$$

Therefore,

$$\begin{aligned}
S(y_{2n}, y_{2n}, y_{2n+1}) &\lesssim b\alpha_1 S(y_{2n-1}, y_{2n-1}, y_{2n}) + \alpha_2 \{S(y_{2n}, y_{2n}, y_{2n-1}) + S(y_{2n+1}, y_{2n+1}, y_{2n})\} \\
&\quad + \alpha_3 S(y_{2n+1}, y_{2n+1}, y_{2n-1}) + \alpha_4 S(y_{2n-1}, y_{2n-1}, y_{2n}) \\
&\lesssim b\alpha_1 S(y_{2n-1}, y_{2n-1}, y_{2n}) + \alpha_2 \{S(y_{2n-1}, y_{2n-1}, y_{2n}) + S(y_{2n}, y_{2n}, y_{2n+1})\} \\
&\quad + \alpha_3 b \{2S(y_{2n+1}, y_{2n+1}, y_{2n}) + S(y_{2n-1}, y_{2n-1}, y_{2n})\} \\
&\quad + \alpha_4 S(y_{2n-1}, y_{2n-1}, y_{2n})
\end{aligned}$$

$$\begin{aligned}
S(y_{2n}, y_{2n}, y_{2n+1}) &\lesssim (b\alpha_1 + \alpha_2 + b\alpha_3 + \alpha_4) S(y_{2n-1}, y_{2n-1}, y_{2n}) \\
&\quad + (\alpha_2 + 2b\alpha_3) S(y_{2n}, y_{2n}, y_{2n+1})
\end{aligned}$$

$$S(y_{2n}, y_{2n}, y_{2n+1}) \lesssim \frac{b\alpha_1 + \alpha_2 + b\alpha_3 + \alpha_4}{1 - \alpha_2 - 2b\alpha_3} S(y_{2n-1}, y_{2n-1}, y_{2n}).$$

Let $k = \frac{b\alpha_1 + \alpha_2 + b\alpha_3 + \alpha_4}{1 - \alpha_2 - 2b\alpha_3}$ and since $b\alpha_1 + 2\alpha_2 + 3b\alpha_3 + \alpha_4 < 1$ and $b \geq 1$ then we get $k < 1$.

Thus

$$S(y_{2n}, y_{2n}, y_{2n+1}) \lesssim k S(y_{2n-1}, y_{2n-1}, y_{2n}).$$

Similarly

$$S(y_{2n+1}, y_{2n+1}, y_{2n+2}) \lesssim k S(y_{2n}, y_{2n}, y_{2n+1}).$$

If $k < 1$, then

$$\begin{aligned}
|S(y_{2n+1}, y_{2n+1}, y_{2n+2})| &\leq k |S(y_{2n}, y_{2n}, y_{2n+1})| \leq k^2 |S(y_{2n-1}, y_{2n-1}, y_{2n})| \\
&\leq \dots \leq k^{2n+1} |S(y_0, y_0, y_1)|.
\end{aligned}$$

Thus for any $m > n$, $m, n \in N$ we get

$$\begin{aligned}
|S(y_{2n}, y_{2n}, y_{2m})| &\leq 2b |S(y_{2n}, y_{2n}, y_{2n+1})| + b |S(y_{2n+1}, y_{2n+1}, y_{2m})| \\
|S(y_{2n}, y_{2n}, y_{2m})| &\leq 2b |S(y_{2n}, y_{2n}, y_{2n+1})| + 2b^2 |S(y_{2n+1}, y_{2n+1}, y_{2n+2})| \\
&\quad + b^2 |S(y_{2n+2}, y_{2n+2}, y_{2m})| \\
&\leq 2b |S(y_{2n}, y_{2n}, y_{2n+1})| + 2b^2 |S(y_{2n+1}, y_{2n+1}, y_{2n+2})| \\
&\quad + 2b^3 |S(y_{2n+2}, y_{2n+2}, y_{2n+3})| + \dots
\end{aligned}$$

$$\begin{aligned}
& + 2b^{m-n}|S(y_{2m-1}, y_{2m-1}, y_{2m})| \\
|S(y_{2n}, y_{2n}, y_{2m})| & \leq 2b k^{2n}|S(y_0, y_0, y_1)| + 2b^2 k^{2n+1}|S(y_0, y_0, y_1)| \\
& + 2b^3 k^{2n+2}|S(y_0, y_0, y_1)| + \dots + 2b^{m-n} k^{2m-1}|S(y_0, y_0, y_1)| \\
& \leq 2(bk^{2n} + b^2 k^{2n+1} + \dots + b^{m-n} k^{2m-1})|S(y_0, y_0, y_1)| \\
& = \frac{2bk^{2n}}{1-bk} |S(y_0, y_0, y_1)|.
\end{aligned}$$

Since $bk, k < 1$, we have

$$|S(y_{2n}, y_{2n}, y_{2m})| \leq \frac{2bk^{2n}}{1-bk} |S(y_0, y_0, y_1)| \rightarrow 0 \text{ as } n \rightarrow \infty.$$

Hence $\{y_{2n}\}$ is a S_b -Cauchy sequence in X . Since X is complete, there exist a point $u \in X$ such that

$$y_{2n} = Ax_{2n} = gx_{2n+1} \rightarrow u \text{ as } n \rightarrow \infty.$$

Suppose that f is complete subspace of X , there exists a point $v \in X$ such that $fv = u$.

Consequently, we find $Av = u$.

Consider

$$\begin{aligned}
S(Av, Av, y_{2n+1}) & = S(Av, Av, Bx_{2n+1}) \\
& \lesssim \alpha_1 \left\{ \frac{S(fv, fv, gx_{2n+1}) S(Bx_{2n+1}, Bx_{2n+1}, fv)}{2S(fv, fv, gx_{2n+1}) + S(Bx_{2n+1}, Bx_{2n+1}, gx_{2n+1})} \right\} \\
& + \alpha_2 \{S(Av, Av, fv) + S(Bx_{2n+1}, Bx_{2n+1}, gx_{2n+1})\} \\
& + \alpha_3 \{S(Bx_{2n+1}, Bx_{2n+1}, fv) + S(Av, Av, gx_{2n+1})\} \\
& + \alpha_4 S(fv, fv, gx_{2n+1}).
\end{aligned}$$

Letting $n \rightarrow \infty$, we get

$$S(Av, Av, u) \lesssim \alpha_2 S(Av, Av, u) + \alpha_3 S(Av, Av, u)$$

$$(1 - \alpha_2 - \alpha_3)S(Av, Av, u) \lesssim 0$$

$$S(Av, Av, u) \lesssim 0.$$

This implies that $S(Av, Av, u) = 0$, that is $Av = u$.

Thus, we have $fv = Av = u$, so that u is a coincidence point of A and f .

Now since $u = Av$ and $A \subset g$, there exists a point $w \in X$ such that $u = gw$.

We claim that $Bw = u$.

Consider

$$S(u, u, Bw) = S(Av, Av, Bw)$$

$$S(u, u, Bw) \lesssim \alpha_1 \left\{ \frac{S(fv, fv, gw)S(Bw, Bw, fv)}{2S(fv, fv, gw) + S(Bw, Bw, gw)} \right\} + \alpha_2 \{S(Av, Av, fv) + S(Bw, Bw, gw)\} \\ + \alpha_3 \{S(Bw, Bw, fv) + S(Av, Av, gw)\} + \alpha_4 S(fv, gw)$$

$$\Rightarrow S(u, u, Bw) \lesssim \alpha_2 S(Bw, Bw, u) + \alpha_3 S(Bw, Bw, u),$$

$$\Rightarrow (1 - \alpha_2 - \alpha_3)S(u, u, Bw) \lesssim 0 \text{ which gives } S(u, u, Bw) = 0, \text{ that is } Bw = u.$$

Hence, we have $u = gw = Bw$, so that u is a coincidence point of B and g .

Now, suppose that u' is another coincidence point of A and f , that is $u' = fv' = Av'$ for some $v' \in X$.

Consider

$$S(u', u', u) = S(Au', Au', Bw)$$

$$S(u', u', u) \lesssim \alpha_1 \left\{ \frac{S(fv', fv', gw)S(Bw, Bw, fv')}{2S(fv', fv', gw) + S(Bw, Bw, gw)} \right\} + \alpha_2 \{S(Av', Av', fv') + S(Bw, Bw, Tw)\} \\ + \alpha_3 \{S(Bw, Bw, fv') + S(Av', Av', gw)\} + \alpha_4 S(fv', fv', gw) \\ \lesssim \alpha_1 \left\{ \frac{S(u, u, u)S(u, u, u')}{2S(u, u, u) + S(u, u, u')} \right\} + \alpha_2 \{S(u', u', u') + S(u, u, u)\} \\ + \alpha_3 \{S(u, u, u') + S(u', u', u)\} + \alpha_4 S(u', u', u)$$

$$S(u', u', u) \lesssim \left(\frac{1}{2}\alpha_1 + 2\alpha_3 + \alpha_4\right) S(u', u', u).$$

This implies that $|S(u', u', u)| < \left(\frac{1}{2}\alpha_1 + 2\alpha_3 + \alpha_4\right) |S(u', u', u)|$, which leads us to a contradiction. Hence $|S(u', u', u)| = 0$, that is $u' = u$.

Now, suppose that u'' is another coincidence point of B and g , that is $u'' = Bw' = gw'$ for some $w' \in X$, we have

$$S(u, u, u'') = S(Av, Av, Bw')$$

$$S(u, u, u'') \lesssim \left(\frac{1}{2}\alpha_1 + 2\alpha_3 + \alpha_4\right) S(u, u, u'').$$

This implies that $|S(u, u, u'')| < (\alpha_1 + 2\alpha_3 + \alpha_4)|S(u, u, u'')|$, which leads us to a contradiction.

So that $|S(u, u, u'')| = 0$, that is $u = u''$.

Thus, u is the unique coincidence point of (A, f) and (B, g) .

Now since pairs (A, f) and (B, g) are weakly compatible on X and $u = fv = Av = gw = Bw$, and $Afv = fAv$, $Bgw = gBw$.

Implies that

$$\begin{aligned} Au &= Afv = fAv = fu \\ Bu &= Bgw = gBw = gu. \end{aligned}$$

Now consider

$$\begin{aligned} S(Au, Au, Bu) &\lesssim \alpha_1 \left\{ \frac{S(fu, fu, gu) S(Bu, Bu, fu)}{2S(fu, fu, gu) + S(Bu, Bu, gu)} \right\} + \alpha_2 \{S(Au, Au, fu) + S(Bu, Bu, gu)\} \\ &\quad + \alpha_3 \{S(Bu, Bu, fu) + S(Au, Au, gu)\} + \alpha_4 S(fu, fu, gu) \\ &\lesssim \frac{1}{2} \alpha_1 S(Bu, Bu, Au) + 2\alpha_3 \{S(Bu, Bu, Au) + \alpha_4 S(Au, Au, Bu)\} \end{aligned}$$

$$S(Au, Au, Bu) \lesssim \left(\frac{1}{2}\alpha_1 + 2\alpha_3 + \alpha_4\right) S(Au, Au, Bu)$$

Implies that $Au = Bu$, that is

$$Au = fu = Bu = gu.$$

Again consider

$$\begin{aligned} S(Av, Av, Bu) &\lesssim \alpha_1 \left\{ \frac{S(fv, fv, gu) S(Bu, Bu, fv)}{2d(fv, fv, gu) + d(Bu, Bu, gu)} \right\} + \alpha_2 \{S(Av, Av, fv) + S(Bu, Bu, gu)\} \\ &\quad + \alpha_3 \{S(Bu, Bu, fv) + S(Av, Av, gu)\} + \alpha_4 S(fv, fv, gu) \end{aligned}$$

$$\begin{aligned} S(Av, Av, Bu) &\lesssim \alpha_1 \left\{ \frac{S(Av, Av, Bu) S(Bu, Bu, Av)}{2S(Av, Av, Bu) + S(Bu, Bu, Bu)} \right\} + \alpha_2 \{S(Av, Av, Av) + S(Bu, Bu, Bu)\} \\ &\quad + \alpha_3 \{S(Bu, Bu, Av) + S(Av, Av, Bu)\} + \alpha_4 S(Av, Av, gu) \end{aligned}$$

$$S(Av, Av, Bu) \lesssim \left(\frac{1}{2}\alpha_1 + 2\alpha_3 + \alpha_4\right) S(Av, Av, Bu),$$

we get $Av = Bu$, that is $u = Bu$, which implies that

$$u = Au = Bu = fu = gu.$$

Hence u is the unique common fixed point of A, B, f and g .

Remark 3.1. All the conditions of Theorem 3.1 remain true if we replace the contraction condition (3.2) by one of following conditions by equating $\alpha_1, \alpha_2, \alpha_3$ and α_4 to zero suitably in Theorem 3.1.

Corollary 3.1 Let A, B, f and g be four self mappings of a complete complex valued S_b -metric space (X, S) with the coefficient $b \geq 1$ and satisfying condition (3.1) and satisfying one of the following contraction conditions:

$$(i) S(Ax, Ax, By) \lesssim \alpha_1 \left\{ \frac{S(fx, fx, gy)S(By, By, fx)}{2S(fx, fx, gy) + S(By, By, gy)} \right\} + \alpha_2 \{S(Ax, fx, fx) + S(By, By, gy)\} \\ + \alpha_3 \{S(By, By, fx) + S(Ax, Ax, gy)\}$$

If $2S(fx, fx, gy) + S(By, By, gy) \neq 0$, for all $x, y \in X$, $\alpha_i \geq 0$ ($i = 1, 2, 3$) with at least one α_i is nonzero and $b\alpha_1 + 2\alpha_2 + 3b\alpha_3 < 1$.

$$(ii) S(Ax, Ax, By) \lesssim \alpha_1 \left\{ \frac{S(fx, fx, gy)S(By, By, fx)}{2S(fx, fx, gy) + S(By, By, gy)} \right\} + \alpha_2 \{S(Ax, fx, fx) + S(By, By, gy)\} \\ + \alpha_4 S(fx, fx, gy).$$

If $2S(fx, fx, gy) + S(By, By, gy) \neq 0$, for all $x, y \in X$, $\alpha_i \geq 0$ ($i = 1, 2, 4$) with at least one α_i is nonzero and $b\alpha_1 + 2\alpha_2 + \alpha_4 < 1$.

$$(iii) S(Ax, Ax, By) \lesssim \alpha_1 \left\{ \frac{S(fx, fx, gy)S(By, By, fx)}{2S(fx, fx, gy) + S(By, By, gy)} \right\} + \alpha_3 \{S(By, By, fx) + \\ S(Ax, Ax, gy)\} + \alpha_4 S(fx, fx, gy).$$

If $2S(fx, fx, gy) + S(By, By, gy) \neq 0$, for all $x, y \in X$, $\alpha_i \geq 0$ ($i = 1, 3, 4$) with at least one α_i is nonzero and $b\alpha_1 + 3b\alpha_3 + \alpha_4 < 1$.

$$(iv) S(Ax, Ax, By) \lesssim \alpha_1 \left\{ \frac{S(fx, fx, gy)S(By, By, fx)}{2S(fx, fx, gy) + S(By, By, gy)} \right\} + \alpha_2 \{S(Ax, fx, fx) + S(By, By, gy)\}$$

If $2S(fx, fx, gy) + S(By, By, gy) \neq 0$, for all $x, y \in X$, $\alpha_i \geq 0$ ($i = 1, 2$) with at least one α_i is nonzero and $b\alpha_1 + 2\alpha_2 < 1$.

$$(v) S(Ax, Ax, By) \lesssim \alpha_1 \left\{ \frac{S(fx, fx, gy)S(By, By, fx)}{2S(fx, fx, gy) + S(By, By, gy)} \right\} + \alpha_3 \{S(By, By, fx) + S(Ax, Ax, gy)\}$$

If $2S(fx, fx, gy) + S(By, By, gy) \neq 0$, for all $x, y \in X$, $\alpha_i \geq 0$ ($i = 1, 2, 3, 4$) with at least one α_i is nonzero and $b\alpha_1 + 3b\alpha_3 < 1$.

$$(vi) S(Ax, Ax, By) \lesssim \alpha_1 \left\{ \frac{S(fx, fx, gy)S(By, By, fx)}{2S(fx, fx, gy) + S(By, By, gy)} \right\}$$

If $2S(fx, fx, gy) + S(By, By, gy) \neq 0$, for all $x, y \in X$, $\alpha_i \geq 0$ ($i = 1$) with at least one α_i is nonzero and $b\alpha_1 < 1$.

Remark 3.2. By putting $A = f$, $B = g$ and $A = B = I$ (identity mapping) in Theorem 3.1, we can obtain the following result:

Theorem 3.2 Let f and g be two self mappings of a complete complex valued S_b -metric space (X, S) with the coefficient $b \geq 1$ and satisfying

$$(i) f \subset g,$$

$$(ii) S(fx, fx, gy) \lesssim \alpha_1 \left\{ \frac{S(x,x,gy)S(y,y,fx)}{2S(x,x,gy) + S(y,y,gy)} \right\} + \alpha_2 \{S(x, fx, fx) + S(y, y, gy)\} \\ + \alpha_3 \{S(y, y, fx) + S(x, x, gy)\} + \alpha_4 S(x, x, y).$$

If $2S(x, x, gy) + S(y, y, gy) \neq 0$, for all $x, y \in X$, $\alpha_i \geq 0$ ($i = 1, 2, 3, 4$) with at least one α_i is nonzero and $b\alpha_1 + 2\alpha_2 + 3b\alpha_3 + \alpha_4 < 1$. If one of f or g is a complete subspace of X , then the pair (f, g) have a unique coincidence point in X . Also, if pair (f, g) is weakly compatible, then f and g have a unique common fixed point in X .

Remark 3.3. All the conditions of Theorem 3.2 remain true if we replace the contraction condition in Theorem 3.2 by one of following conditions by equating $\alpha_1, \alpha_2, \alpha_3$ and α_4 to zero suitably in Theorem 3.2.

Corollary 3.2 Let f and g be two self mappings of a complete complex valued S_b -metric space (X, S) with the coefficient $b \geq 1$ and satisfying condition $f \subset g$ and satisfying one of the following contraction conditions:

$$(i) S(fx, fx, gy) \lesssim \alpha_1 \left\{ \frac{S(x,x,gy)S(y,y,fx)}{2S(x,x,gy) + S(y,y,gy)} \right\} + \alpha_2 \{S(x, fx, fx) + S(y, y, gy)\} \\ + \alpha_3 \{S(y, y, fx) + S(x, x, gy)\}$$

If $2S(x, x, gy) + S(y, y, gy) \neq 0$, for all $x, y \in X$, $\alpha_i \geq 0$ ($i = 1, 2, 3$) with at least one α_i is nonzero and $b\alpha_1 + 2\alpha_2 + 3b\alpha_3 < 1$.

$$(ii) S(fx, fx, gy) \lesssim \alpha_1 \left\{ \frac{S(x,x,gy)S(y,y,fx)}{2S(x,x,gy) + S(y,y,gy)} \right\} + \alpha_2 \{S(x, fx, fx) + S(y, y, gy)\} \\ + \alpha_4 S(x, x, y).$$

If $2S(x, x, gy) + S(y, y, gy) \neq 0$, for all $x, y \in X$, $\alpha_i \geq 0$ ($i = 1, 2, 4$) with at least one α_i is nonzero and $b\alpha_1 + 2\alpha_2 + \alpha_4 < 1$.

$$(iii) S(fx, fx, gy) \lesssim \alpha_1 \left\{ \frac{S(x,x,gy)S(y,y,fx)}{2S(x,x,gy) + S(y,y,gy)} \right\} +$$

$$\alpha_3\{S(y, y, fx) + S(x, x, gy)\} + \alpha_4 S(x, x, y).$$

If $2S(x, x, gy) + S(y, y, gy) \neq 0$, for all $x, y \in X$, $\alpha_i \geq 0$ ($i = 1, 3, 4$) with at least one α_i is nonzero and $b\alpha_1 + 2\alpha_2 + 3b\alpha_3 + \alpha_4 < 1$

$$(iv) \quad S(fx, fx, gy) \lesssim \alpha_1 \left\{ \frac{S(x, x, gy)S(y, y, fx)}{2S(x, x, gy) + S(y, y, gy)} \right\} + \alpha_2 \{S(x, fx, fx) + S(y, y, gy)\}$$

If $2S(x, x, gy) + S(y, y, gy) \neq 0$, for all $x, y \in X$, $\alpha_i \geq 0$ ($i = 1, 2$) with at least one α_i is nonzero and $b\alpha_1 + 2\alpha_2 < 1$.

$$(v) \quad S(fx, fx, gy) \lesssim \alpha_1 \left\{ \frac{S(x, x, gy)S(y, y, fx)}{2S(x, x, gy) + S(y, y, gy)} \right\} + \alpha_3 \{S(y, y, fx) + S(x, x, gy)\}$$

If $2S(x, x, gy) + S(y, y, gy) \neq 0$, for all $x, y \in X$, $\alpha_i \geq 0$ ($i = 1, 3$) with at least one α_i is nonzero and $b\alpha_1 + 3b\alpha_3 < 1$.

$$(vi) \quad S(fx, fx, gy) \lesssim \alpha_1 \left\{ \frac{S(x, x, gy)S(y, y, fx)}{2S(x, x, gy) + S(y, y, gy)} \right\}$$

If $2S(x, x, gy) + S(y, y, gy) \neq 0$, for all $x, y \in X$, $\alpha_i \geq 0$ ($i = 1$) with at least one α_i is nonzero and $b\alpha_1 < 1$.

CONFLICT OF INTERESTS

The authors declare that there is no conflict of interests.

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